

# Relation between mainshock rupture process and Omori's law for aftershock moment release rate

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## SUMMARY

We compare the source time functions (i.e., moment release rates) of three large California mainshocks with the seismic moment release rates during their aftershock sequences. Aftershock moment release rates, computed by summing aftershock moments in time intervals, follow a power-law time dependence similar to Omori's law from minutes to months after the mainshock; furthermore, in contrast to the previously observed saturation in numbers of aftershocks shortly after the mainshock rupture, no such saturation is seen in the aftershock moment release rates, which are dominated by the largest aftershocks. We argue that the observed saturation in aftershock numbers described by the 'time offset' parameter  $c$  in Omori's law is likely an artefact due to the underreporting of small aftershocks, which is related to the difficulty of detecting large numbers of small aftershocks in the mainshock coda. We further propose that it is more natural for  $c$  to be negative (i.e. singularity follows the onset of mainshock rupture) than positive (singularity precedes onset of rupture). To make a more general comparison of mainshock rupture process and aftershock moment rates, we then scale mainshock time functions to equalize the effects of the varied seismic moments. For the three California mainshocks, we compare the scaled time functions with similarly scaled aftershock moment rates. Finally, we compare global averages of scaled time functions of many shallow events to the average scaled aftershock moment release rate for six California mainshocks. In each of these comparisons, the extrapolation, using Omori's law, of the aftershock moment rates back in time to the onset of the mainshock rupture indicates that the temporal intensity of the aftershock moment release is about 1.5 orders of magnitude less than the maximum reached by the mainshock rupture. This may be due to the differing amplitudes and relative importance of static and dynamic stresses in aftershock initiation compared to mainshock rupture propagation.

**Key words:** aftershocks, rupture propagation, seismic coda, seismic-event rates, seismic moment, statistical methods.

## 1 INTRODUCTION

In this work we compare source time functions (seismic moment release rates) for California and global shallow large earthquakes with the seismic moment release rate of aftershock sequences. By using moment release rate rather than the number of aftershocks we circumvent the problem of missing weak aftershocks, since most of the total moment in earthquake sequences is contained in the largest events (Kagan 2002). Because we are interested in the transition between the mainshock rupture process and the beginning of the aftershock sequence, we need to use data from regional and local earthquake catalogues, based on interpretation of high-frequency seismograms, rather than global catalogues as the former record aftershocks that are closer in time to the mainshock rupture end than global catalogues (Kagan 2004).

We use available source-time functions (s.t.f.'s) for several large California earthquakes to infer the relation between mainshock rup-

ture process and moment release in their immediate aftershocks. We also analyse s.t.f.'s for global shallow earthquakes. Aftershock sequences of large earthquakes in southern California (1952 Kern County, 1992 Joshua Tree–Landers–Big Bear sequence, 1994 Northridge and 1999 Hector Mine), recorded in the CalTech catalogue are analysed to demonstrate that from minutes to months after the mainshock the moment release follows Omori's law.

## 2 TEMPORAL DISTRIBUTION OF AFTERSHOCKS

Omori [1894, Eq. (b) p. 117] found that aftershock rate for the 1891 Nobi and two other Japanese earthquakes decayed about as

$$n(t) = \frac{K}{t + c}, \quad (1)$$

where  $K$  and  $c$  are coefficients,  $t$  is the time since mainshock origin and  $n(t)$  is the aftershock frequency measured over a certain interval of time. Presently a more complicated equation is commonly used to approximate aftershock rate

$$n(t) = \frac{K}{(t + c)^p}. \quad (2)$$

This expression with the additional exponent parameter  $p$  is called the modified Omori formula (Utsu 1961; Utsu *et al.* 1995). Here we assume that the exponent  $p$  is 1.0, its typical value in empirical studies (Utsu *et al.* 1995; Kagan 2004; Gerstenberger *et al.* 2005—see their Supplement).

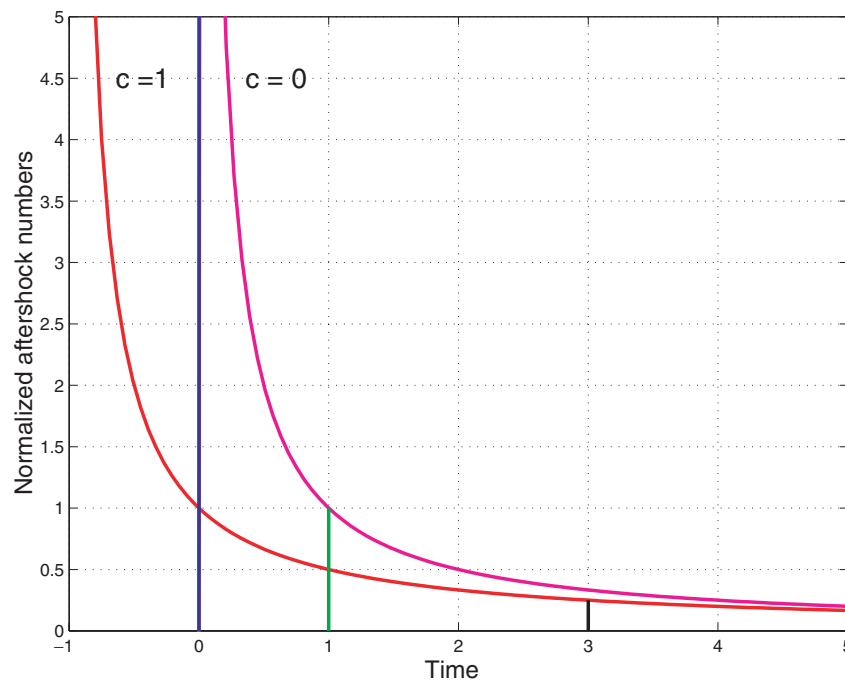
The aftershock rate decay still continues now in the focal zone of the 1891 Nobi earthquake (Utsu *et al.* 1995). Statistical analysis of earthquake catalogues indicates that a power-law dependence characterizes the occurrence of both foreshocks and aftershocks. From this point of view a mainshock may be considered as an aftershock, which happens to be stronger than the previous event (Kagan & Knopoff 1981; Agnew 2005; Gerstenberger *et al.* 2005).

The parameter  $c$  in eq. (1) is almost always found to be positive and typically ranges from 0.5 to 20 hr in empirical studies (Utsu 1961; Reasenber & Jones 1994, 1989; Utsu *et al.* 1995). It was introduced to explain the seeming saturation of aftershock rate close to the origin time of a mainshock. No reliable empirical regularities in the behavior of  $c$  have been found. Positive  $c$  in eq. (1) means that the singularity in eq. (1) occurs *before* the mainshock, which is unphysical. Negative  $c$  means that the singularity occurs after the mainshock. The latter case is a more physically natural assumption. In this case,  $n(t)$  is not defined for the period  $t \leq -c$ . This could correspond, for example, to the period of mainshock rupture, during which individual aftershocks usually cannot be defined, identified, or counted. However, eq. (1) assumes that earthquakes are

instantaneous, therefore, for times comparable to the rupture time of mainshocks Omori's law breaks down, since earthquake counting is not possible for such small time intervals. Moreover, Omori's law in its regular form, eqs (1) and (2), predicts that for time  $t \rightarrow 0$  the aftershock rate stabilizes around  $K/c$ . Again, aftershock counting is not usually feasible at the time of mainshock rupture and its coda, hence some time limit (Ogata 1983) needs to be introduced in eqs (1) and (2).

Fig. 1 shows Omori's law curves in the linear scale, whereas in Fig. 2 we display the curves in the more common log–log format. In the log–log case the line with a positive value of  $c$  describes a saturation of aftershock rate close to the earthquake origin time. Such a 'saturation' has been observed in many aftershock sequences (Reasenber & Jones 1989, 1994; Utsu *et al.* 1995). The saturation is usually interpreted as a delay between mainshock rupture end and the start of aftershock activity (Rundle *et al.* 2003; Kanamori & Brodsky 2004).

Kagan (2004) argues that the real cause of this apparent rate saturation is not a physical property of aftershock sequences, but is due to under-reporting of short-term aftershocks, especially smaller ones in earthquake catalogues. Peng & Vidale (2004) and Vidale *et al.* (2003, 2004) note that the number of aftershocks in the first few minutes of the sequence observed on high-pass filtered seismograms is several times higher than aftershock numbers recorded in local catalogues. Shcherbakov *et al.* (2004) find that the parameter  $c$  in Omori's law decreases as the magnitude of earthquakes considered increases. They attribute this dependence to 'the undercounting of small aftershocks at short times'. Chen *et al.* (2004, 2005) find that in the 1999 Chi-Chi, Taiwan earthquake, aftershocks start after passage of the rupture front and they decay according Omori's law even when rupture continues at more distant parts of the breaking fault. These results support our interpretation.



**Figure 1.** A positive  $c > 0$  in Omori's law means that the singularity in aftershock rate occurs at negative time ( $t < 0$ ), that is, before the mainshock. We show Omori laws with  $c = 1$  and  $c = 0$  here in linear scale and below in log–log scale (Fig. 2). In statistical analyses of earthquake catalogues, events before the green or black lines may be removed to ensure completeness of aftershock accounting (Kagan 2004). Positive  $c$  would fit a relative lack of early aftershocks (either real or apparent), but trends toward a singularity before the mainshock initiation. We propose that the positive empirical value for  $c$  is mostly due to the under-reporting of small aftershocks immediately following a mainshock.

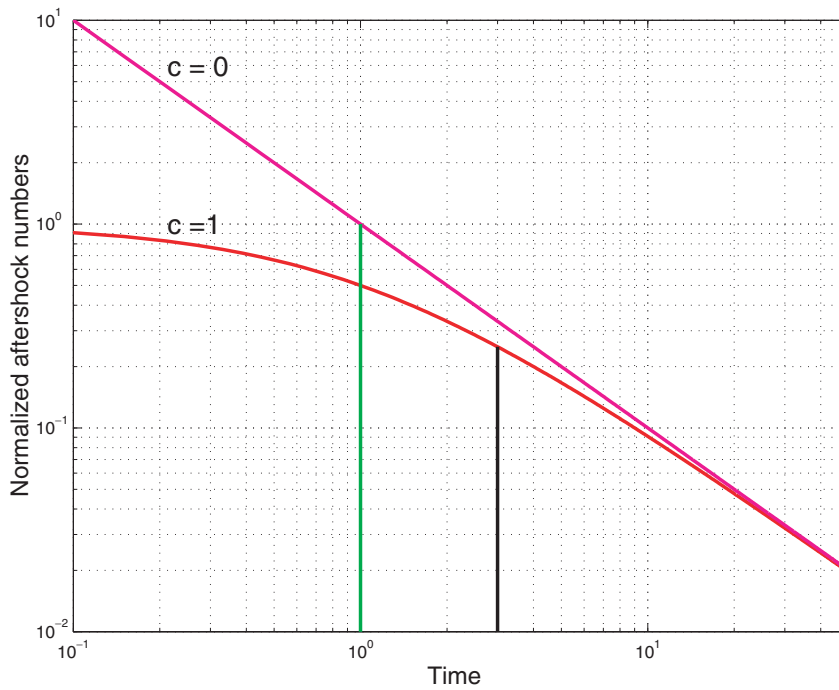


Figure 2. Same as Fig. 1 but in log-log scale.

### 3 SEISMIC MOMENT RELEASE IN EARTHQUAKES AND AFTERSHOCKS

#### 3.1 Three California earthquakes and their aftershocks

Fig. 3 displays seismic moment release curves (i.e. s.t.f.'s) for three recent large California earthquakes. These functions for the Landers, Northridge and Hector Mine mainshocks have been obtained by Dreger (1994), by Thio & Kanamori (1996) and Ji *et al.* (2002),

respectively. The apparent duration of earthquake rupture increases with earthquake size.

In Fig. 4 we show the aftershock distribution for the 1992 Northridge, California earthquake. The general time-magnitude aftershock pattern is seen in many other aftershock sequences (Kagan 2004): larger aftershocks begin early in the sequence, whereas the occurrence rate is progressively delayed for weaker events. Above the threshold, aftershocks in any magnitude band seem to be distributed almost uniformly over log time, which would correspond

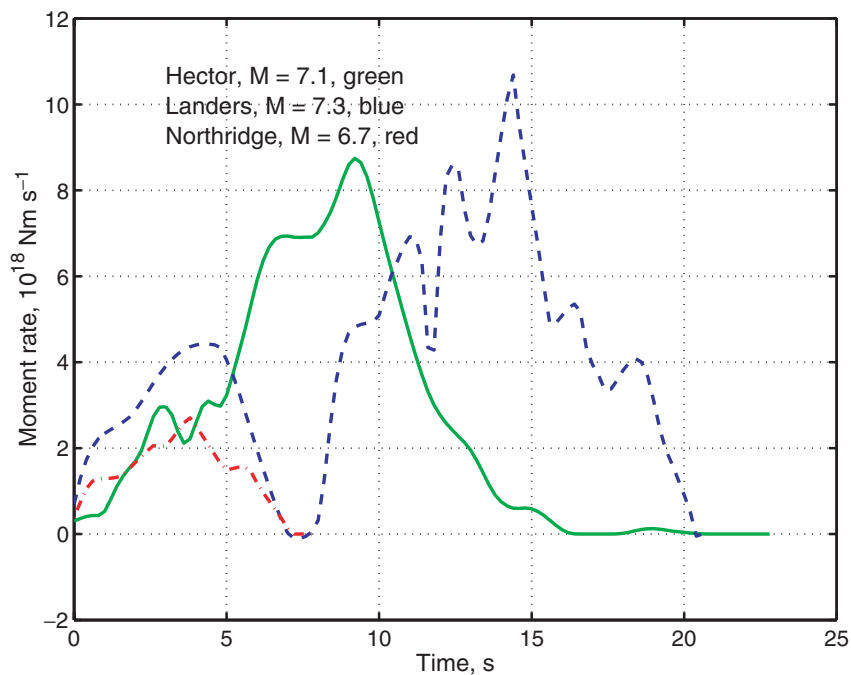
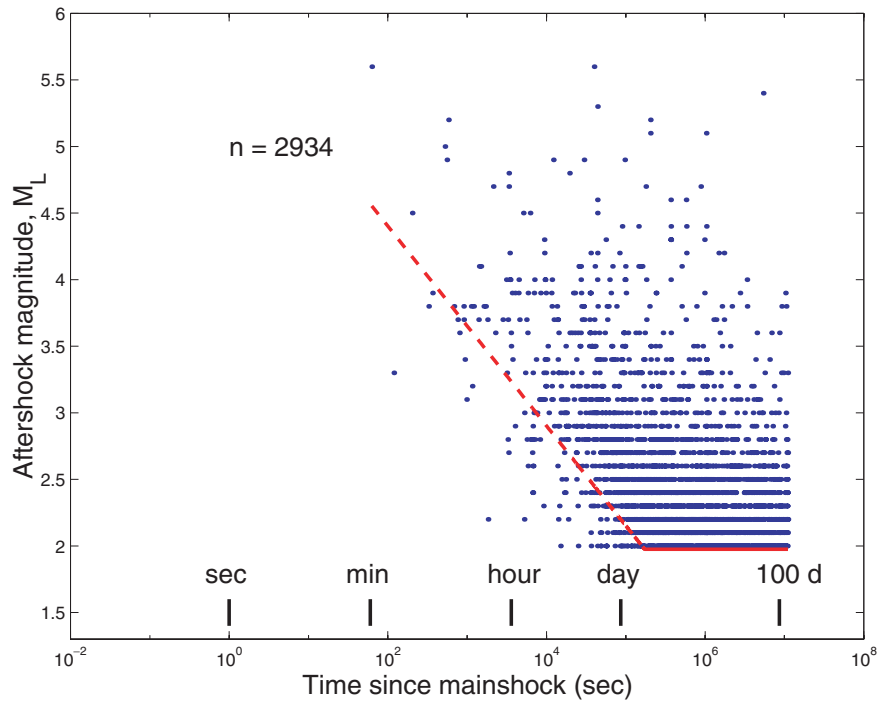


Figure 3. Seismic moment s.t.f.'s for three California earthquakes: 1992  $M7.3$  Landers (dashed line), 1994  $M6.7$  Northridge (dash-dotted line), and 1999  $M7.1$  Hector Mine (solid line).



**Figure 4.** Time-magnitude distribution of 1994 January 17  $M = 6.7$  Northridge, California aftershocks. The CalTech earthquake catalogue is used. Events in the 128 days following the mainshock and between latitude  $34.0^\circ\text{N}$  and  $34.5^\circ\text{N}$  and longitude  $118.35^\circ\text{W}$  and  $118.80^\circ\text{W}$  were selected. The dashed line shows an estimate of the completeness threshold (eq. 6), which can be used to correct aftershock frequency and moment release rate for missing aftershocks.

to their rate decay according to Omori's law (eq. 1). The magnitude threshold in early aftershock sequences decreases with time (Wiemer & Katsumata 1999, their Fig. 2; Wiemer *et al.* 2002, their Fig. 2; Kagan 2004). Therefore, the aftershock magnitude threshold approximation by eq. (6) (see below) is also shown.

Fig. 5 shows moment release rates during the 1994 Northridge, California earthquake and during its aftershock sequence. We subdivide time after the mainshock origin into intervals increasing by a factor of 2, and sum the scalar seismic moments of its recorded aftershocks (Kagan 2004). For most of the aftershocks seismic moment was not determined. We assume that their local magnitude is equivalent to the moment magnitude  $m$  (Hutton & Jones 1993) and calculate the moment  $M$  (in Nm) as

$$M = 10^{1.5(m+6)}, \quad (3)$$

(Hanks 1992).

Fig. 5 suggests that the aftershock moment rate  $\dot{M}(t)$  can be approximated by a power-law time dependence similar to Omori's law

$$\dot{M}(t) = \frac{k \tau_{pk} \dot{M}_{pk}}{t + c}, \quad (4)$$

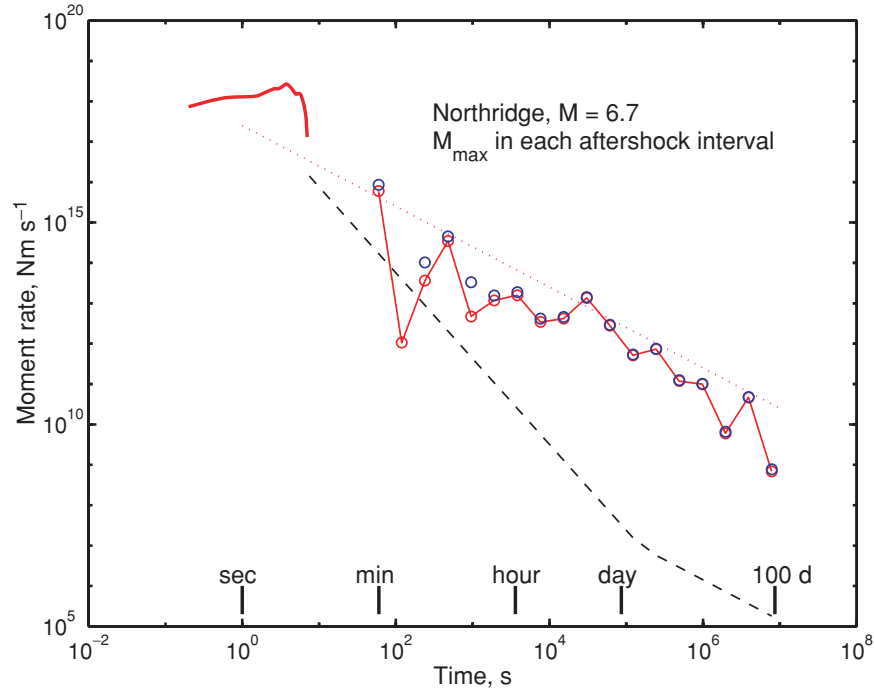
where  $t$  is time after mainshock origin,  $c$  is a coefficient similar to that in eq. (1), but possibly different in value,  $\dot{M}_{pk}$  is the peak moment release rate of a mainshock and  $\tau_{pk}$  is the time the peak occurs. The coefficient  $k$  characterizes the ratio of peak mainshock moment rate ( $\dot{M}_{pk}$ ) and aftershock moment rate extrapolated to  $\tau_{pk}$  (with  $c = 0$ ). We do not yet know how close the end of mainshock moment release comes to the beginning of the aftershock process; it is possible that there is no actual temporal gap between these two phenomena.

During the occurrence of a mainshock the rupture process is often punctuated by significant changes in moment-rate ampli-

tude, momentarily stopping or restarting rupture and other rupture complexities (Kagan 2004). As a result, large earthquakes in a detailed analysis are often subdivided into several subevents. Aftershock moment release, on the other hand, is calculated by summing the moments of several separate events. It seems possible that in the transition time interval after mainshock rupture end and the beginning of the recorded aftershock sequence, the moment release could exhibit intermediate features—quasi-continuous rupture episodes, which are supplanted by more discrete events. In part our recognition of distinct events is effected by the limited frequency content of seismograms, the presence of noise, etc. With ideal recording, the difference between mainshock and aftershock moment release rates may not be clear, abrupt, or well defined.

An advantage of moment summation of aftershocks as opposed to the more usual counting earthquake numbers, is that early in an aftershock sequence many small events may be missing from the catalogue as in Fig. 4. This undercount of small earthquakes gives an impression of aftershock rate saturation or rate decay when approaching the mainshock rupture end (i.e. going backwards in time towards the mainshock). In contrast, most of the moment in a sequence is carried by the strongest aftershocks, hence the bias in moment summation is less significant. However, summation of seismic moments carries a significant price—random fluctuations of the sum are very large (Zaliapin *et al.* 2005), hence more summands are needed to yield more reliable results.

Assuming that the aftershock size distribution follows the Gutenberg–Richter relation (Kagan 2004), we can calculate the moment rate of the undetected, or missing weak aftershocks and thus compensate for an incomplete catalogue record. The part of the total seismic moment  $M_s$  in an aftershock time interval, which is missing due to incompleteness of the small earthquake record, can



**Figure 5.** The s.t.f. for 1994  $M_{6.7}$  Northridge, California earthquake compared to moment release (red circles) of its immediate aftershocks, averaged over logarithmic time intervals. Blue circles show aftershock moment release corrected for under-reported small aftershocks (eq. 7), using the aftershock moment threshold (black dashed line) divided by the duration of the corresponding time interval to yield quantities comparable to the moment rate. The dotted line shows a power-law approximation for aftershock moment release rates, analogous to Omori's law (eq. 1).

be obtained by modifying eq. (21) in Kagan (2002):

$$F(M_s) = \left[ \frac{M_a}{M_{xp}} \right]^{1-\beta}, \quad (5)$$

where  $\beta$  is the parameter of earthquake size distribution ( $\beta = 2b/3$ ),  $b$  is the  $b$ -value of the magnitude–frequency relation,  $M_a$  is the lower moment threshold for the aftershock sequence, and  $M_{xp}$  is the maximum moment. The threshold  $M_a$  depends on time according to eq. (6). If  $M_a = M_{xp}$ , all moment is missing, whereas for  $M_a \rightarrow 0$ , the moment sum is complete.

For aftershock sequences we assume  $\beta = 2/3$  (Kagan 2002) and take the maximum moment ( $M_{xp}$ ) to be the moment of the mainshock: if an earthquake stronger than the mainshock occurs during aftershock sequence, then the former mainshock would be reclassified as a foreshock. As alternative possibilities, we equate  $M_{xp}$  to the moment of the largest aftershock in a time interval or to the largest aftershock in the sequence.

Helmstetter *et al.* (2005) found the following approximate relation between the magnitude completeness threshold  $m_a(t, m)$  at time  $t$  (in days) after a mainshock of magnitude  $m$

$$m_a(t, m) = m - 4.5 - 0.75 \log_{10}(t). \quad (6)$$

For several recent (1980–2004) southern California mainshocks (see Fig. 4 as an example), the magnitude completeness threshold has been as high as 4.5 shortly after the mainshock, dropping only to about 2 later in the sequence. The equation is plotted in Fig. 4. We use the above two equations to correct aftershock moment release curves for under-reporting small events.

After calculating the moment threshold eq. (6), and using eq. (3), we estimate the multiplicative correction coefficient

$$[1 - F(M_s)]^{-1}. \quad (7)$$

Calculating the correction term (eq. 7) for different mainshocks and various choices of  $M_{xp}$  (see above), we found out that, as one should expect from expression (eq. 6), the correction is largest for smallest time intervals. Even for these intervals the correction is less than 50 per cent. In Fig. 5 as well as in all the calculations below we take as the maximum moment  $M_{xp}$  in eq. (5) the value of the largest aftershock in each of the time intervals. Only for time intervals closest to the mainshock rupture end, is the difference between non-corrected and corrected values observable. In the second time interval, the largest aftershock was smaller than the assumed threshold value (eq. 6), thus no correction coefficient is calculated.

Fig. 6 shows scaled moment release rates for three California earthquakes and their aftershocks as well as averages of both sets. In averaging data sets here and below, we divide the sum either by the number of curves, or by the number of non-zero entries in a data set. The reason for the latter version is that s.t.f.'s for some earthquakes were not defined over the same intervals. Here the difference between two methods of averaging is quite minor.

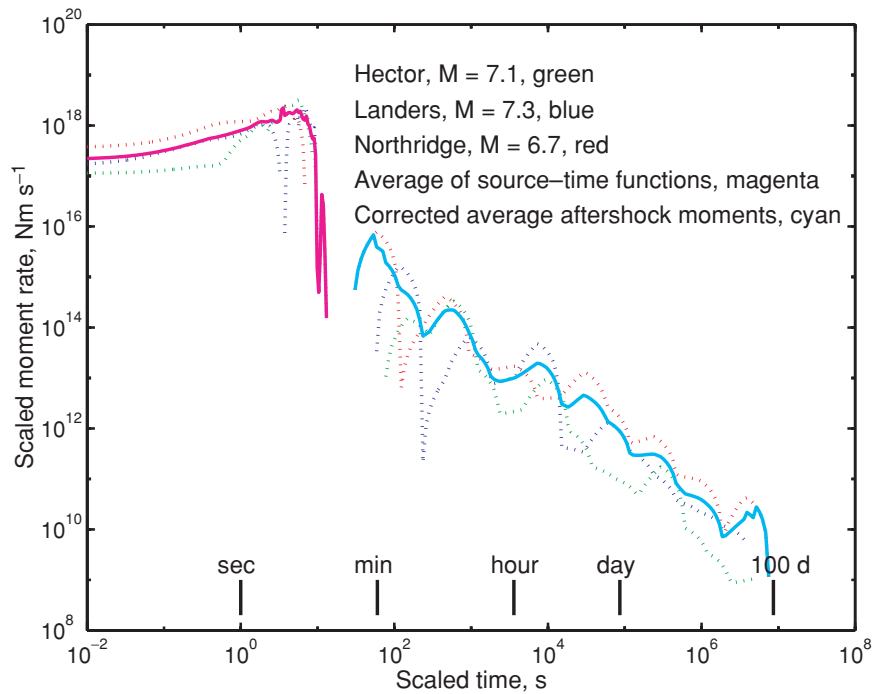
To average s.t.f.'s together, it is necessary to normalize for the effect of their varying seismic moments. Houston *et al.* (1998) and Houston (2001) scaled s.t.f.'s to a common moment of  $10^{19}$  N m as follows. Scaled moment rate  $\dot{M}_{sc}$  and scaled time  $t_{sc}$  are given by

$$\dot{M}_{sc}(t_{sc}) = \dot{M}(t_{sc}) \times (10^{19}/M_m)^{2/3} \quad \text{Nm s}^{-1}, \quad (8)$$

and

$$t_{sc} = t \times (10^{19}/M_m)^{1/3}, \quad (9)$$

where  $M_m$  is the moment of a mainshock,  $\dot{M}(t)$  and  $t$  are unscaled seismic moment rate (i.e. the original s.t.f.) and unscaled time respectively. These transformations are equivalent to normalizing the



**Figure 6.** Scaled s.t.f.'s for three California earthquakes: 1992  $M7.3$  Landers (dashed line), 1994  $M6.7$  Northridge (dash-dotted line), and 1999  $M7.1$  Hector Mine (solid line) and moment release of their immediate aftershocks, corrected for missing small aftershocks (eq. 7) and averaged over logarithmic time intervals. The s.t.f.'s and aftershock moment release rates were normalized to account for the effect of varying mainshock moments, allowing the averaging of data for mainshocks of different size. Here we scale all mainshocks and aftershock sequences to a magnitude 6.67 event.

s.t.f. for an  $m = 6.67$  earthquake. The variables  $\tau_{pk}$ ,  $\dot{M}_{pk}$ ,  $t$ , and  $c$  in the formula for moment rate decay with time (eq. 4) can be scaled similarly.

As in Fig. 5 the extrapolation of aftershock moment release rates according to Omori's law is approximately 1.5 orders of magnitude below the maximum of the scaled s.t.f. at about 5 scaled seconds. This would mean  $k \approx 1/30$  in eq. (4).

The seismic moment scaling with the  $2/3$  exponent as in eq. (8) and averaging the obtained quantities correspond to summation of earthquake rupture areas

$$S \propto M^{2/3}. \quad (10)$$

When we sum aftershock numbers in the standard application of Omori's law, small events dominate the sum. In a sum of seismic moments of events with a Gutenberg–Richter distribution with  $\beta = 2/3$ , the largest earthquake on average carries  $1/3$  of the total moment (Zaliapin *et al.* 2005). For  $\beta = 2/3$ , the average of earthquake rupture areas balances the influence of large and small earthquakes (Rundle 1989).

### 3.2 Global shallow earthquakes

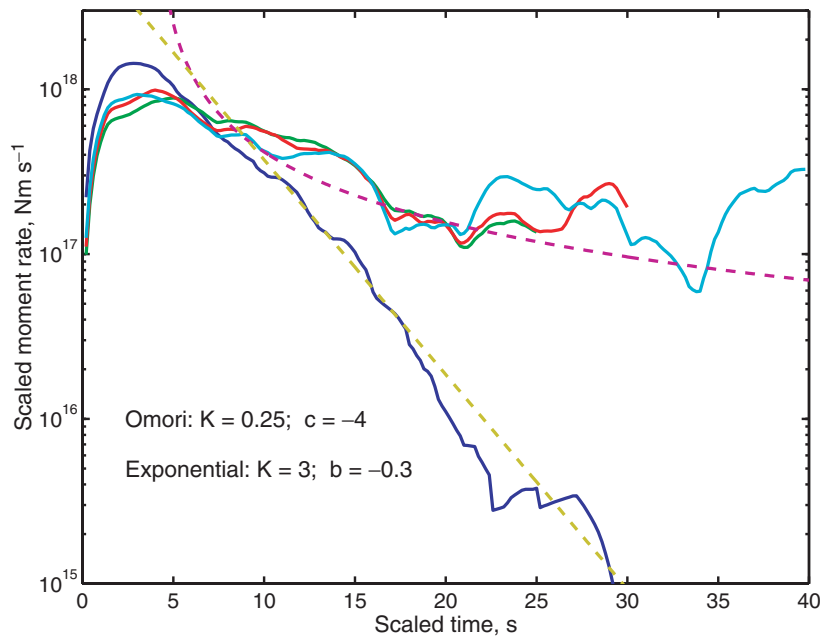
To make a more general comparison between moment release rates during mainshocks and those during aftershock sequences, we compare average scaled s.t.f.'s for several sets of global large shallow earthquakes with scaled aftershock sequences of six California mainshocks. Houston (2001) studied 255 s.t.f.'s determined by inversions of teleseismic body waves by Tanioka & Ruff (1997) and colleagues at the University of Michigan. Fig. 7 shows the average of the scaled time functions of 143 events with depths between 5 and 40 km ranging in size from  $m$  6.2 to  $m$  8.3. In the scaling and aver-

aging procedure, these time functions were truncated (i.e. assumed to be zero) after the duration picked as the end of rupture by Tanioka and Ruff and colleagues (Houston 2001). After its maximum, the average decreases exponentially with time (dashed and solid lines, Fig. 7).

Since picking the end of rupture from the inversion result is a subjective procedure and ignores possible moment release during an interval of interest, we also constructed the averages of three subsets of events for which the inversion included a sufficient interval after the apparent end of mainshock rupture. Specifically, we selected those events which had the inversion result available for at least 25, 30 or 40 s, respectively, of scaled time. In averaging these events, the moment release rate was not truncated at the assumed end of rupture. These subsets contain 23, 15 and 8 events, respectively, so their averages are inherently more variable. Whereas the average of the truncated scaled time functions (yellow dashed and blue solid lines) follows an exponential falloff with time, the average of the non-truncated scaled time functions (thin solid lines) follows a power-law falloff similar to Omori's law (Fig. 7).

Most likely both selection criteria are biased. In the first case the possible continuation of moment release after a minimum in activity is ignored; in the second case, the selected s.t.f.'s tend to have longer than average duration because a significant moment release was observed in later stages of earthquake rupture. Ideally, to study moment release rates in the first few tens to hundreds of seconds following mainshocks, one would average many s.t.f.'s based on the inversions of waveforms that continue for a sufficient length of time after the apparent end of rupture. A large consistent set of such time functions is not presently available.

Fig. 8 compares the global average s.t.f. (green curve in Fig. 7) with scaled and corrected aftershock moment rates for six California earthquakes, similar to Fig. 6. These sequences are for the



**Figure 7.** Average scaled seismic moment s.t.f.'s for 143 shallow (5–40 km) global earthquakes, and their approximation by an exponential function (yellow) and a power-law (Omori's) distribution (magenta). For the latter approximation we use  $c = -4$  s, which is close to the rupture time of  $m = 6.67$  earthquake. The blue curve shows the average of scaled time functions truncated at the inferred end of rupture. Green, red and cyan curves show averages of subsets of s.t.f.'s comprising those non-truncated time functions for which the s.t.f. inversion result was available for at least 25, 30 and 40 scaled seconds (i.e. including a sufficient interval after the apparent end of mainshock rupture). For the non-truncated time functions, moment release at the end of mainshock rupture seems to decay as  $1/t$  similar to Omori's law.

1952 Kern County, the 1992 Joshua Tree, 1992 Landers, 1992 Big Bear, the 1994 Northridge and 1999 Hector Mine earthquakes. Although the Big Bear earthquake was an aftershock of the Landers event, it has an extensive aftershock sequence of its own which has all the properties of a regular mainshock event. We calculated the ratio of total moment release in the aftershock sequences to the seismic moment of the mainshock. The percentages are 6.3, 12, 5.8, 19, 12 and 2.8 per cent, respectively. After correction for missing small aftershocks, they are 6.8, 13, 6.5, 21, 14 and 3.3 per cent, respectively. As explained earlier, the correction is in general small; only for those time intervals closest to the end of mainshock rupture, does it reach several tens of percent.

In Fig. 9 scaled moment release rates of the aftershock sequences are averaged. The average behavior is similar to that of Fig. 6: an extrapolation of the average aftershock moment rate according to Omori's law (assuming  $c = 0$ ) is about 1.5 orders of magnitude below the maximum of the s.t.f., that is,  $k \approx 1/30$  in (4).

Figs 6 and 8 compare the seismic moment release of mainshocks and aftershocks. Such a comparison can be made only retrospectively, that is, only after an aftershock sequence has ended, do we know that the first (main) event is not followed by an even stronger shock. For example, the  $M6.1$  1992 Joshua Tree, California earthquake which occurred on 1992 April 23, was followed 66 days later by the  $M7.3$  June 28 Landers event. Another example is the earthquake sequence in the New Ireland region (Papua New Guinea), where on 2000 November 16–17, four earthquakes with surface-wave magnitude from 7.2 to 8.2 occurred. Hence, were we to predict its aftershock decay, the forecast would be significantly wrong (Kagan 2004). Therefore, our results relate to *typical* aftershock sequences, that is, such that no earthquake comparable or stronger than the mainshock occurs in the sequence. Similarly the ratio of mainshock moment to the total moment of aftershock sequence,

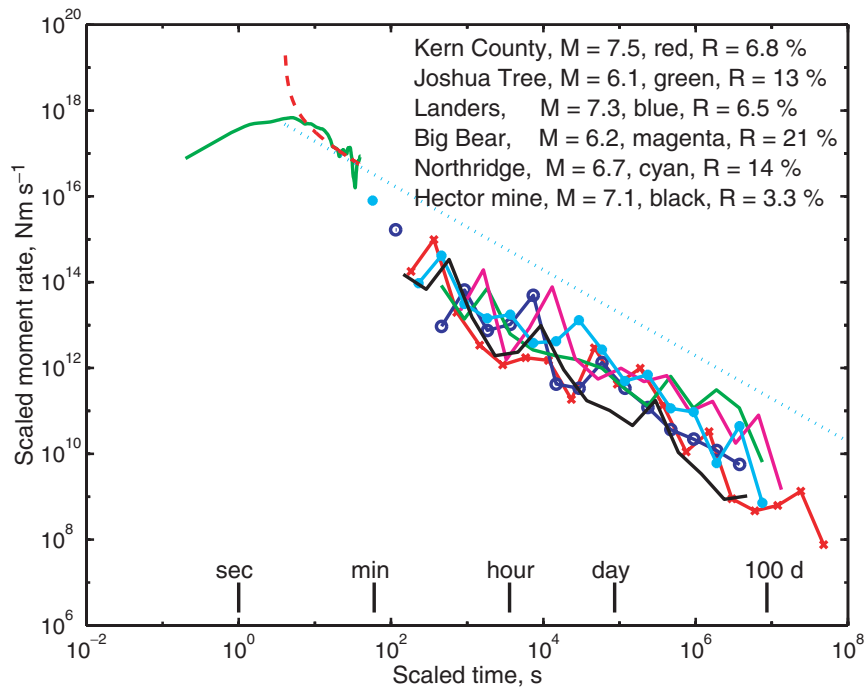
discussed above, would substantially change if unusual earthquake clusters are considered.

## 4 DISCUSSION

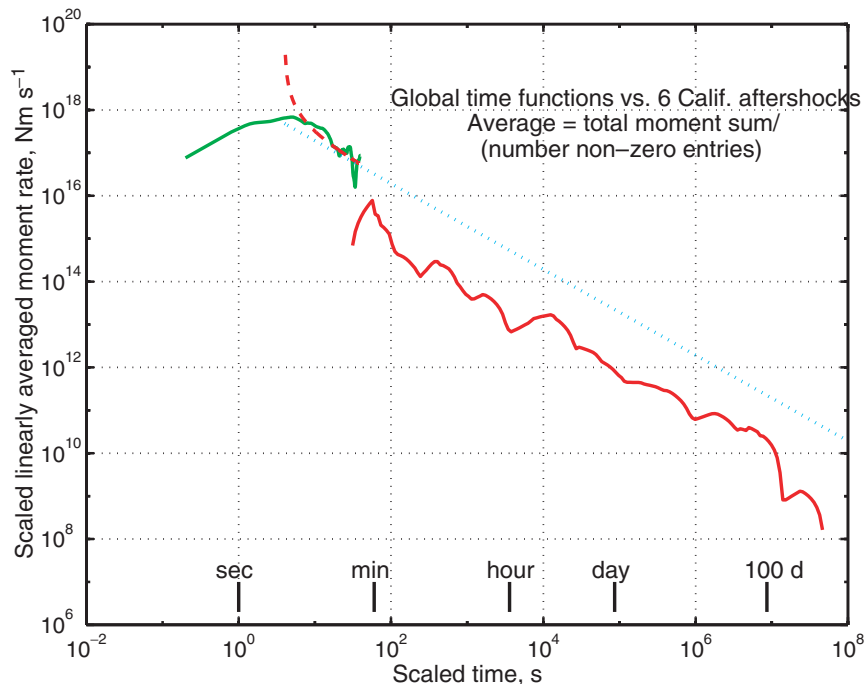
### 4.1 Comparison of s.t.f.'s and aftershock moment release

We compared average s.t.f.'s for large shallow earthquakes with the ensuing moment release of immediate aftershocks. The global and California earthquakes are plotted against the average aftershock curves of California events. In both of these cases the pattern is similar: aftershock moment release follows Omori's law with the  $p$ -value (i.e. exponent in eq. 2) close to 1.0. If the average curve is extrapolated toward the earthquake origin time, its continuation is about 30 times below the maximum of the average s.t.f. at the scaled time of about 5 s, which corresponds to the maximum release of seismic moment for a  $m = 6.7$  earthquake. Taking into account the size of the focal zone for such an earthquake (about 20 km) and the average rupture velocity ( $2\text{--}3 \text{ km s}^{-1}$ ), this time seems to be reasonable for a bilateral rupture. The value of  $k$  in eq. (4) found here,  $k \approx 1/30$ , is consistent with the rule of thumb known as Båth's law (Console *et al.* 2003) which holds that the magnitude of the largest aftershock in a sequence is roughly 1–1.2 units smaller than that of the mainshock.

Around scaled time interval 20–60 s there is no moment release activity either in the s.t.f.'s or in aftershock curves. This gap is most likely caused by the mainshock coda, which hinders aftershock detection. If this conjecture is true, one can extrapolate aftershock curves right to the end of earthquake rupture. Because of the coda wave interference we cannot extend the aftershock moment rate right to the end of mainshock rupture, but it seems likely that the transition of mainshock rupture into the aftershock process is smooth.



**Figure 8.** Average scaled s.t.f. for shallow global earthquakes compared to scaled aftershock moment release rates for six California aftershock sequences. The average includes only events with inversion results available for at least 25 s of scaled time. Both types of moment rates were scaled to a magnitude 6.67 event. Two Omori law approximations to the s.t.f.'s are shown with  $c = -4$  s (dashed magenta line), and with  $c = 0$  s (dotted blue line). The California aftershock sequences were corrected for missing small aftershocks (following eq. 7). The coefficient  $R$  in the figure is the percent of total seismic moment released by immediate aftershocks compared to the mainshock scalar moment. The activity level in the aftershock sequences extrapolates to about 30 times less than the peak rate in the average scaled global time function.



**Figure 9.** Average scaled s.t.f. for global shallow earthquakes with non-truncated time functions (green line taken from Fig. 7) compared to the corrected scaled average for six California aftershock sequences (red line). Approximations of average time function by power-law (Omori) distributions (dashed and dotted lines) are also shown. As before, two Omori law approximations are given with  $c = -4$  s, and with  $c = 0$  s. The average aftershock rates fall about 8 orders of magnitude over about 200 days. Extrapolating back in time according to Omori's law yields a level of aftershock activity about 1.5 orders of magnitude less than the maximum mainshock moment rate.

What might explain the difference between the rate of seismic moment release during mainshock rupture and that extrapolated from the aftershock moment release via Omori's law? The earthquake rupture process is most likely controlled by dynamic stresses: a rupture front is concentrated in a pulse (Heaton 1990) with a strong stress wave initiating rupture. In contrast, the aftershock process is essentially static in that dynamic waves generated by an aftershock have almost always left the mainshock focal region before occurrence of a subsequent aftershock. According to various evaluations (Antonioli *et al.* 2002, 2004; Kilb *et al.* 2002; Gomberg *et al.* 2003) the amplitude of the dynamic stress wave is at least an order of magnitude stronger than the amplitude of the incremental static stress. If the number and total moment release of both aftershocks and the rupture events comprising the mainshocks are proportional to the stress increase, we would expect the s.t.f. to be higher than the appropriately scaled aftershock moment release rate. This may explain the difference in moment release rates for mainshocks and aftershock sequences.

Moreover, it is likely that the temporal and spatial properties of earthquake rupture differ significantly from those of an aftershock distribution. Spatially, aftershock patterns are not different from the general earthquake distribution; they seem to be fractally distributed with a correlation dimension close to 2 (Robertson *et al.* 1995; Guo & Ogata 1997). Although it seems likely that the aftershock cloud is slowly expanding with time after a strong earthquake, there is no obvious strong order in the space-time distribution of aftershocks. Earthquake rupture, on the contrary, has a clear pattern of associated with rupture driven by propagating seismic waves (e.g. Heaton 1990). Although the propagation of rupture has many complex features, like temporary stops, change of slip direction, jumping from one fault segment to another, in general the spatio-temporal evolution of rupture exhibits significantly more orderly behavior than that of an aftershock sequence. Unfortunately, presently there are insufficient numbers of long-duration source inversions for statistical analysis of the rupture propagation complexity.

#### 4.2 Reasons for non-zero $c$ -value

Our investigations and analysis of Omori's law (eq. 1) seem to suggest that the parameter  $c$  is either close to zero or should be a small negative value. What are the reasons for positive values of  $c$ , which have been reported by many researchers? We can summarize some of the possible causes:

- (1) the overlapping of seismic records in the wake of a strong earthquake,
- (2) workforce constraint which prevents detailed interpretation of complex seismograms during the beginning of an aftershock sequence,
- (3) absence or malfunction of seismic stations close to the source zone,
- (4) the extended spatio-temporal character of earthquake rupture zone implying failure of the point model of the earthquake source, and
- (5) temporary deployment of seismic stations introduces a new factor in identification and counting of aftershocks, a factor which is difficult to quantitatively evaluate. Such deployments have little effect on the results presented here because

- (a) they usually occur at least a few days after the mainshock, therefore cannot influence the aftershock rates in the first hours, a major focus of this work and

- (b) the moment release rates (as opposed to numbers of events) are dominated by the largest events, which are detected irrespective of a temporary deployment.

In sum, empirically determined positive values for  $c$  arise largely from fitting the functional form of the Omori law to systematically under-counted numbers of aftershocks at early times following a mainshock.

What is the time interval between the end of mainshock rupture and the beginning of the aftershock sequence? Our results shown in Figs 6, 8 and 9 indicate that the interval is small, no longer than 20–60 s of scaled time, perhaps effectively equal to zero. The end of mainshock rupture is defined by a relatively low level of moment release. If the release is still high, this is considered as a continuation of the earthquake rupture process. Hence, the low-level interval is assumed in the definition of rupture duration during the retrospective interpretation of seismic records. As we suggested, an objective way to study the late part of the mainshock moment release and the beginning aftershock sequence, would be to process all the seismic records to a pre-arranged scaled time interval.

How then can one self-consistently identify an individual earthquake event? One criterion is to define the end of an individual event by a rare (low probability) time interval without strong aftershocks. Another is to look at dynamic stress waves at a certain amplitude (or other characteristic property) in the source zone of an earthquake. An earthquake is considered to end when all such waves have ceased. Both of these definitions depend on some quantitative criterion; most likely, the number and properties of such identified individual events would depend strongly on the value adopted.

## 5 CONCLUSIONS

Moment release rates during mainshocks (i.e. s.t.f.'s) are compared with moment release rates during aftershock sequences.

From minutes to months following a mainshock, the moment release rate of the aftershock sequence follows a power-law decay similar to the familiar Omori law for aftershock frequency. We note inconsistencies in the standard Omori formula, and propose that the positive values for  $c$  found empirically by many studies are mainly due to the under-reporting of small aftershocks. We used a time-dependent magnitude threshold to approximately estimate corrections to the aftershock moment rate for this effect.

We made several comparisons of individual California mainshocks and global averages of shallow mainshocks with individual aftershock sequences and with an average California aftershock sequence. Before averaging, the mainshock time functions and the aftershock moment release rates were scaled to normalize for the effect of varying mainshock seismic moments.

In all the comparisons, the extrapolation of the aftershock moment rates back in time following Omori's law yields a rate about 30 times smaller than the maximum moment rate of the mainshock. This disparity reflects the difference between the process of mainshock rupture, which is highly organized in space and time by dynamically propagating stress waves, and the process of aftershock nucleation, which spans a much greater temporal extent.

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