

Single Particle Motion in E and B fields

Everything follows from Lorentz Force:

1st assume time independent fields

- Gyration
- ExB drift: charge and energy independent
- Grad-B and curvature drifts: depend on both charge and energy (explains How the Radiation Belts Work)
- Adiabatic invariants of the motion in a dipole field

Single particle motion in B field

start with Lorentz force

$$m \frac{d\vec{v}}{dt} = q \vec{v} \times \vec{B}$$

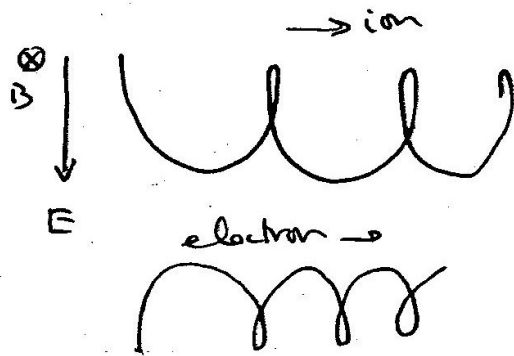
Simple harmonic Oscillator

$$\omega_c \equiv \frac{|e|B}{m}$$

$$r_L \equiv \frac{v_{\perp}}{\omega_c} = \frac{m v_{\perp}}{eB}$$

Larmor radius

Now add \vec{E} field and transform away E



$$\text{ie } F=0 = q\vec{E} + \vec{v} \times \vec{B}$$

$$\Rightarrow \vec{E} = -\vec{v} \times \vec{B}$$

$$\text{gives } \vec{v} = \frac{\vec{E} \times \vec{B}}{B^2}$$

Gyration at $\frac{eB}{m}$ + drift at

$$\vec{v}_d = \frac{\vec{E} \times \vec{B}}{B^2}$$

in general any force \vec{F}

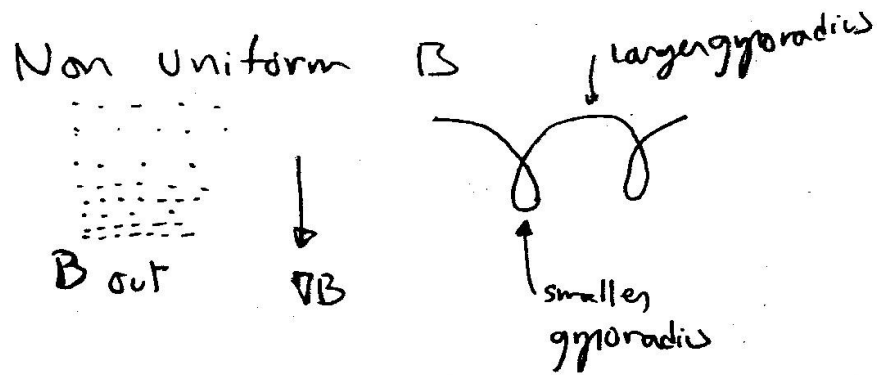
(substitute $\vec{F} = q\vec{E}$)

$$\vec{v}_d = \frac{\vec{F} \times \vec{B}}{qB^2}$$

for force $\perp B$

How the Radiation Belts Work

- Grad B drift = $-\mu \nabla \vec{B} \times \vec{B} / qB^2$
- Force on Parallel Motion
 - Magnetic bottle
 - Pitch angle
 - Bounce Motion
- Longitudinal Drift
- Radiation Belt Organization
 - Loss cone



Acts like a particle slowing down when it moves into ∇B .

Force = $-\mu \nabla B$ force on magnetic moment μ

$$\mu \equiv \frac{E_{\perp}}{B} = \frac{\frac{1}{2} m v_{\perp}^2}{B} \equiv \text{current} \times \text{area}$$

assume $\nabla \propto \frac{1}{L}$ and $L \gg r_L$



Guiding center equation

$$\vec{V}_G = v_{\parallel} \hat{b} + \underbrace{\frac{\vec{E} \times \vec{B}}{B^2}}_{E \times B} - \underbrace{\frac{\mu \nabla B \times \vec{B}}{q B^2}}_{\text{Gradient drift}} + \underbrace{\frac{B}{q B^2} m v_{\parallel}^2 \frac{(\vec{B} \cdot \nabla) \vec{B}}{B^2}}_{\text{Curvature drift}}$$

Parallel Motion of Guiding Center

- From Lorentz Force, looking at average motion parallel to \mathbf{B} ($v_{\parallel} = \vec{v} \cdot \vec{\mathbf{B}}/B$)

we get this equation of motion:

$$\frac{d}{dt} m v_{\parallel} = e E_{\parallel} - \mu \frac{\partial B}{\partial l} \quad \left| \quad \text{where} \quad \frac{\partial}{\partial l} \equiv \frac{\vec{\mathbf{B}}}{B} \cdot \vec{\nabla} \right.$$

Where $\mu = \frac{1}{2} m v_{\text{perp}}^2 / B = \text{constant}$ when $E_{\parallel} = 0$

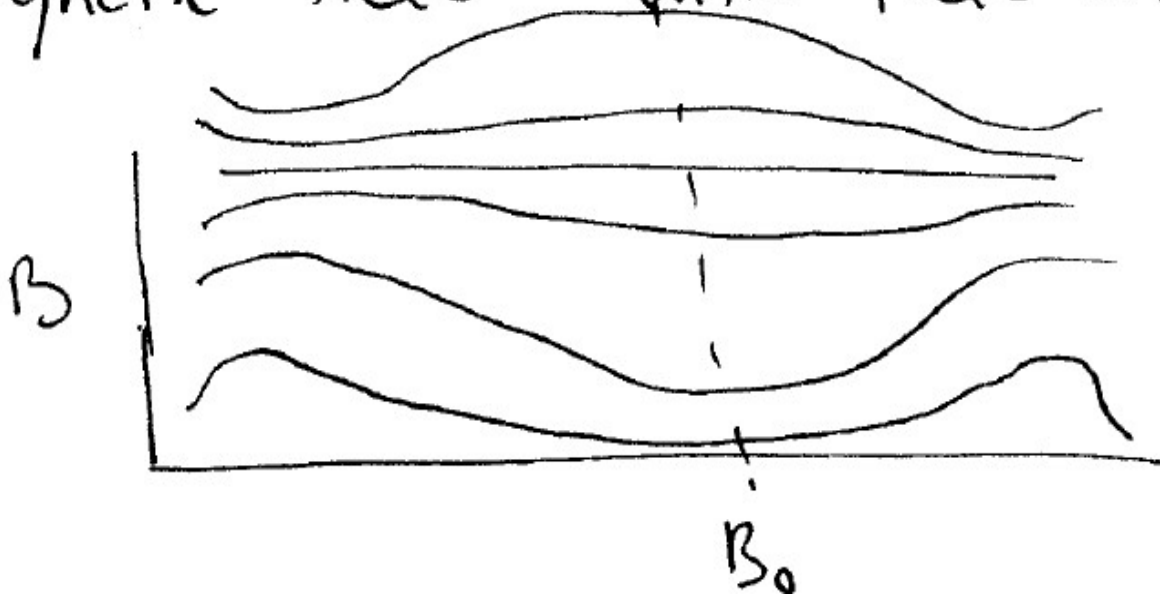
(for derivation see

http://earthweb.ess.washington.edu/bobholz/ess515/parallel_guiding_center_motion.pdf)

Magnetic Bottle

Magnetic Bottle

Consider a cylindrically symmetric magnetic field with field lines as



Suppose you start a particle on the axis at the place where field strength is B_0 .
 Suppose the velocity of the particle makes an angle α with respect to the magnetic field.
 What happens?

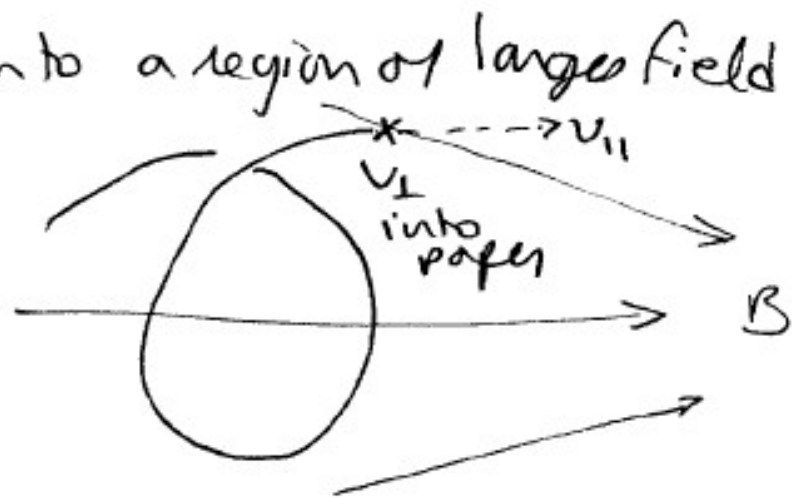
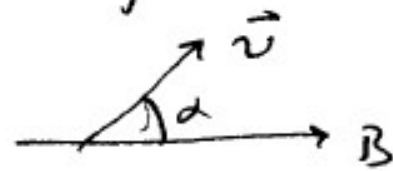
$\alpha \equiv$ pitch angle

$$v_{\parallel} = v \cos \alpha$$

$$v_{\perp} = v \sin \alpha$$

v_{\parallel} carries the particle into a region of larger field strength. Some time later we have

v_{\parallel} to right
 v_{\perp} into paper



at the particle \vec{B} has a component B_1 that is parallel to the guiding center field and a component B_2 that is perpendicular.

So we have

$$\begin{array}{c} \otimes \\ \downarrow \\ V_{\perp} \text{ (into)} \end{array} \rightarrow V_{\parallel}$$

$$\begin{array}{c} B_1 \\ \rightarrow \\ \downarrow \\ B_2 \end{array}$$

consider components of $\vec{v} \times \vec{B}$ (Lorentz Force)

$v_{\parallel} B_2$	causes force that	increases	v_{\perp}
$v_{\perp} B_2$	" " "	decreases	v_{\parallel}

thus, v_{\parallel} decreases while v_{\perp} increases.

Since $v_{\parallel}^2 + v_{\perp}^2 = \text{constant}$ (energy conserved),
after a while v_{\parallel} will be zero. But
 $v_{\perp} B_2$ continues to act, so v_{\parallel} changes

sign

ie: Particle enters magnetic field a
certain distance, stops, turns around
and comes out!

This is called Mirroring

We want to know the point where
the particle turns around, or the Mirror Point

Equation for v_{\perp} is $\mu = \text{constant}$
or $\frac{\frac{1}{2}mv_{\perp}^2}{B} = \text{const.}$

if particle moves into region where B is larger,
then its v_{\perp} must get larger too.

Question? How far into the region
of increasing magnetic field will a particle
penetrate if it starts with pitch angle
 α_0 at a place where $B = B_0$?

$$\mu = \frac{\frac{1}{2}mv_{\perp}^2 \sin^2 \alpha_0}{B_0} = \frac{\frac{1}{2}mv^2 \sin^2 \alpha}{B} \quad \left(v_{\perp} = v \sin \alpha \text{ initially} \right)$$

as it penetrates, B increases, so does $\sin \alpha$
until, at the mirror point $\alpha = 90^\circ$

and $v_{\parallel} = v \cos \alpha = 0$

$$v_{\perp} = v \sin \alpha = v \quad \leftarrow \text{all energy in } v_{\perp} \text{ at}$$

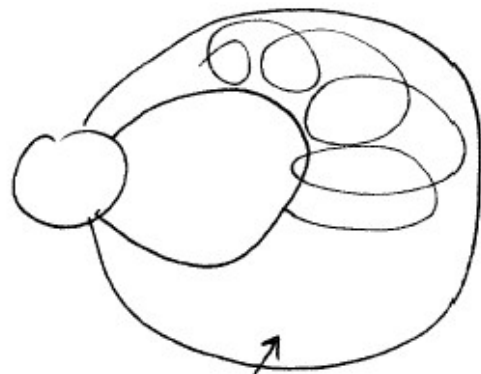
Define B at this point to be B_m

we have $\frac{\sin^2 \alpha_0}{B_0} = \frac{1}{B_m}$

$$\text{or } B_m = \frac{B_0}{\sin^2 \alpha_0}$$

All particles of Any
energy, charge, mass
will mirror at same
point B_m if they start with same α_0 !

Another Example of Guiding Center Motion
 Particles in a Magnetic Dipole Field
The Radiation Belts



Bounce motion

as $v_{||}$ carries particles away from the equator they enter region of increasing B field
 \therefore mirror and bounce back & forth

Additionally, the guiding center drifts around the earth in longitude due to gradient & curvature drifts.

I Gyration

$$\tau_{\text{gyration}} \equiv \text{gyroperiod} = \frac{2\pi}{\Omega} = \frac{2\pi m}{Be}$$

10^{-2} sec protons at low α

10^{-5} s e^- at low α

10 sec p at $r=10R_e$

10^{-2} s e^- at $r=10R_e$

Bounce
 bounce time $\equiv \tau_{\text{bounce}} = \int \frac{ds}{v_{\parallel}}$

$$ds = (dr^2 + r^2 d\lambda^2)^{1/2} = r_e \cos \lambda (1 + 3 \sin^2 \lambda)^{1/2} d\lambda$$

$$v_{\parallel} = (v^2 - v_{\perp}^2)^{1/2}$$

$$\text{but } \frac{v_{\perp}^2(r, \lambda)}{B(r, \lambda)} = \frac{v^2 \sin^2 \alpha_e}{B_e} = \text{const}$$

where α_e and B_e are equatorial pitch angle and field strength

$$\text{so } v_{\parallel} = v \left(1 - \frac{\sin^2 \alpha_e B(r, \lambda)}{B_e} \right)^{1/2}$$

$$B(r, \lambda) = \frac{M}{r^3} (1 + 3 \sin^2 \lambda)^{1/2} \quad (\text{Dipole field})$$

$$= \frac{B_e}{\cos^6 \lambda} (1 + 3 \sin^2 \lambda)^{1/2} \quad \left(\begin{array}{l} \text{because} \\ r = r_e \cos^2 \lambda \\ \text{field line} \\ \text{equation} \end{array} \right)$$

numerically integrating

$$\tau_{\text{bounce}} \sim 4 \frac{r_e}{v} T(\alpha_e)$$

where $T(\alpha_e) = 1.3 - 1.5 \sin \alpha_e$
 (note strong dependence on α_e)

for $v = c$ and $T(\alpha) = 1$

r_e	$1.5 R_e$	$3 R_e$	$6 R_e$
τ_{bounce}	$\sim 1.3 \text{ s}$	$\sim 2.6 \text{ s}$	$\sim 5.2 \text{ s}$

III Longitudinal Drift

for $\mathbf{J} = 0 = \nabla \times \mathbf{B}$

$$V_G = \frac{\overline{\mathbf{B} \times \nabla B}}{e B^3} (\mathcal{E}_\perp + 2\mathcal{E}_\parallel)$$

integrate around drift path of 360° Longitude

gives $\tau_{\text{drift}} \approx \frac{44}{r_e \times \mathcal{E}(\text{MeV})}$ minutes
 r_e in earth radii

That is, $r_e \equiv L R_e \equiv L$ earth radii

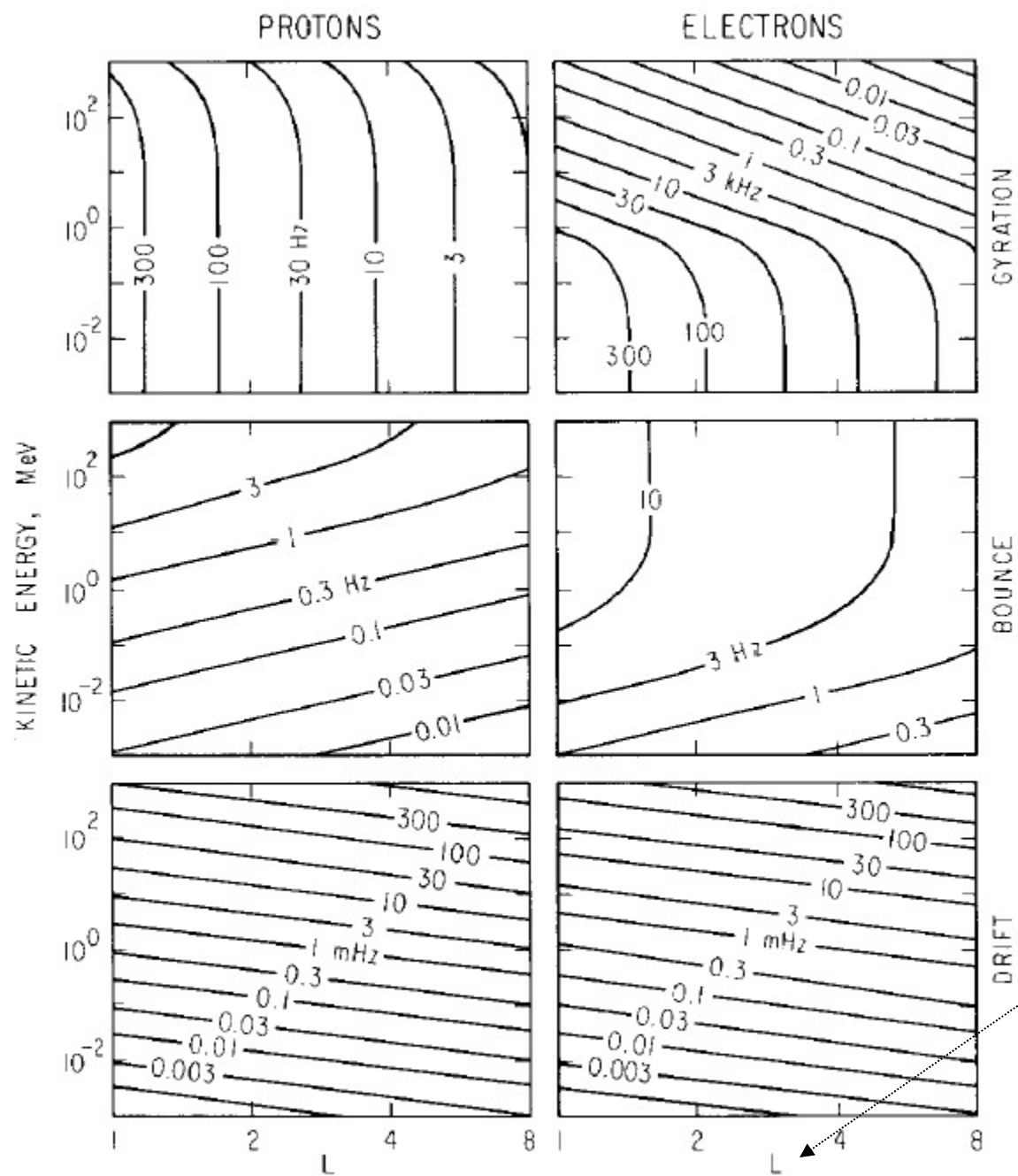
for $\mathcal{E} = 0.1 \text{ MeV}$ and $r_e = 10 R_e$
 $\tau_{\text{drift}} \approx 44$ minutes

so, in general

$$\tau_{\text{drift}} \gg \tau_{\text{bounce}} \gg \tau_{\text{gyro}}$$

Neglecting scattering and plasma instabilities
particles can be trapped forever

in practice some species at some energies
are trapped for 100 yrs!



L is the place
the dipole field
line crosses the
equator, in
units of Earth
Radii

Fig. 6. Contours of constant adiabatic gyration, bounce, and drift frequency for equatorially mirroring particles in a dipole field. Adiabatic approximation

- Continue Bounce motion
- Longitudinal Drift
- Radiation Belt Organization:
 - Shielding layer
 - L-shell
- Field Line Equation: $r=LR_e \cos^2\lambda$
- Loss Cone
- Begin Large Scale Current

Single Particle Motion in dipole field

- $\mu = \frac{1}{2}mv_{\perp}^2/B$ = Magnetic Moment = constant
gave us gyration and drift.

Now:

- Pitch angle analysis gives us $B_m = B_o/\sin^2\alpha_o$
- Then add: Dipole field
 $B(r,\lambda) = (M/r^3)*(1 + 3\sin^2\lambda)^{1/2}$ (where λ is latitude)
- We will Find :
Gyro period \ll Bounce period \ll Drift Period

Bounce
 bounce time $\equiv \tau_{\text{bounce}} = \int \frac{ds}{v_{\parallel}}$

$$ds = (dr^2 + r^2 d\lambda^2)^{1/2} = r_e \cos \lambda (1 + 3 \sin^2 \lambda)^{1/2} d\lambda$$

$$v_{\parallel} = (v^2 - v_{\perp}^2)^{1/2}$$

$$\text{but } \frac{v_{\perp}^2(r, \lambda)}{B(r, \lambda)} = \frac{v^2 \sin^2 \alpha_e}{B_e} = \text{const}$$

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numerically integrating

$$\tau_{\text{bounce}} \sim 4 \frac{r_e}{v} T(\alpha_e)$$

where $T(\alpha_e) = 1.3 - 1.5 \sin \alpha_e$
 (note strong dependence on α_e)

for $v = c$ and $T(\alpha) = 1$

	r_e	$1.5 R_e$	$3 R_e$	$6 R_e$
τ_{bounce}	$\sim 1.3 \text{ s}$	$\sim 2.6 \text{ s}$	$\sim 5.2 \text{ s}$	$\sim 10.4 \text{ s}$

III Longitudinal Drift

$$\text{for } \mathbf{J} = 0 = \nabla \times \mathbf{B}$$

$$V_G = \frac{\overline{\mathbf{B} \times \nabla B}}{e B^3} (\mathcal{E}_\perp + 2\mathcal{E}_\parallel)$$

integrate around drift path of 360° Longitude

$$\text{gives } \tau_{\text{drift}} \approx \frac{44}{r_e \times \mathcal{E}(\text{MeV})} \text{ minutes}$$

r_e in earth radii

That is, $r_e \equiv L R_e \equiv L$ earth radii

$$\text{for } \mathcal{E} = 0.1 \text{ MeV and } r_e = 10 R_e$$
$$\tau_{\text{drift}} \approx 44 \text{ minutes}$$

So, in general

$$\tau_{\text{drift}} \gg \tau_{\text{bounce}} \gg \tau_{\text{gyro}}$$

Neglecting scattering and plasma instabilities
particles can be trapped forever

in practice some species at some energies
are trapped for 100 yrs!

to employ semi-empirical models to account for the associated adiabatic effects upon radiation-belt particles.

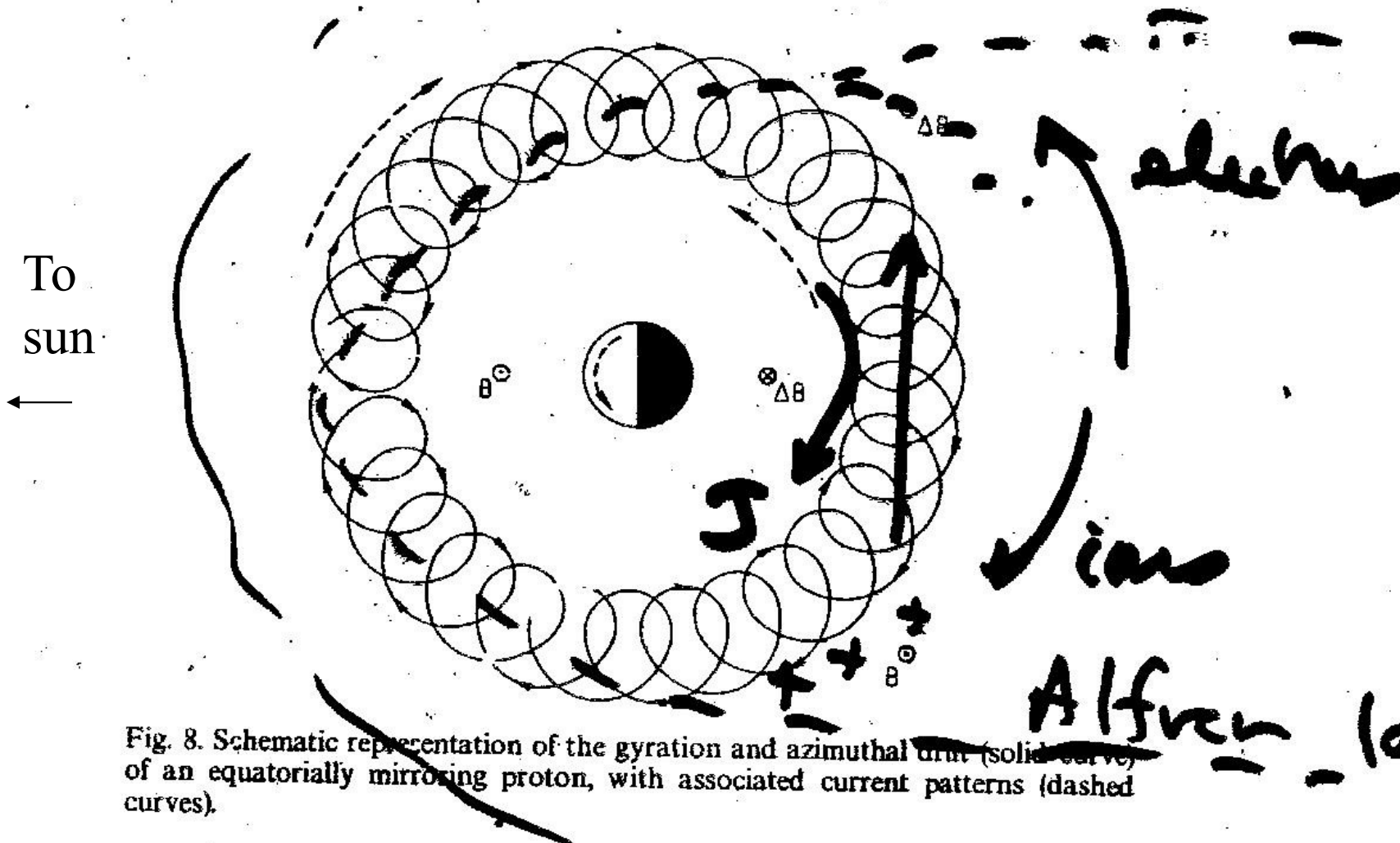


Fig. 8. Schematic representation of the gyration and azimuthal drift (solid curve) of an equatorially mirroring proton, with associated current patterns (dashed curves).

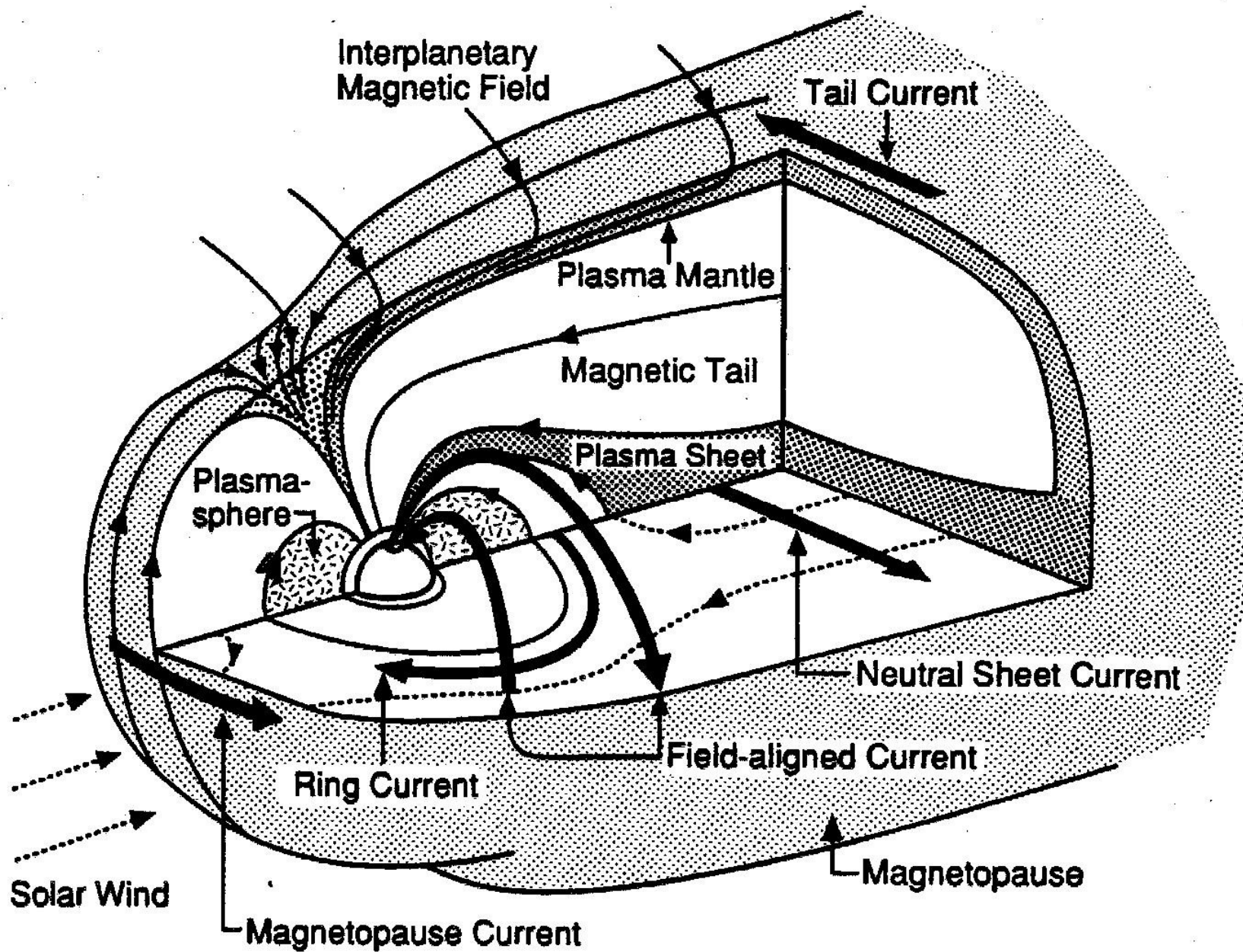
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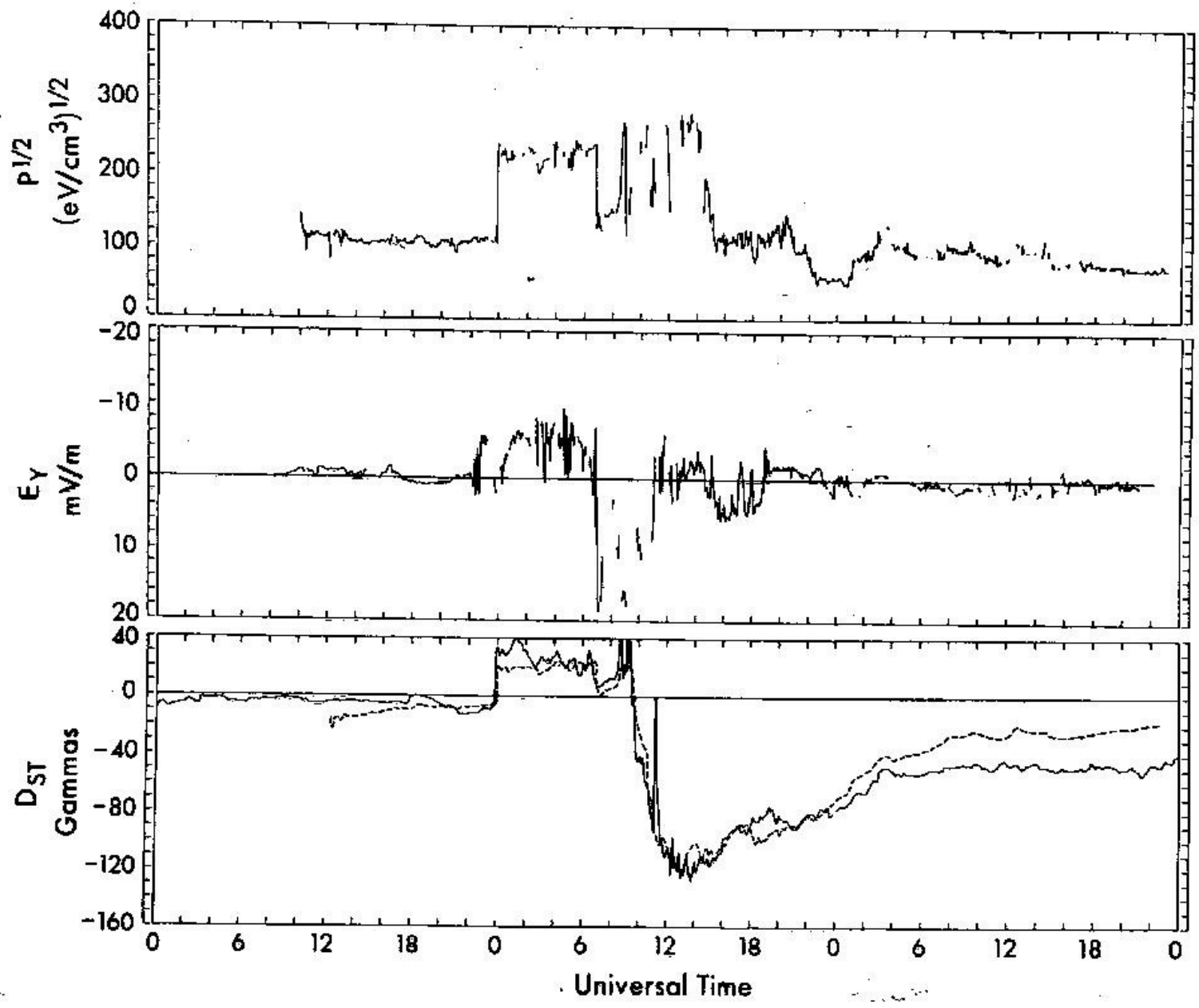
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where $p_{||}$ = the pressu field. Obsc both at densely pc This regio and near I

The in in the inn (- $\hat{\phi}$) direc is spatially Simplif

$$V = E \times B_{\text{drift}} \text{ PLUS } \text{Grad-B}_{\text{drift}}$$





Equatorial
Magnetic
field
perturbation

Radiation Belt organization

For \vec{r}_0 a dipole B-field with
 $M =$ dipole moment of the earth

$$\left[\vec{M}_{\text{eff}} = \int \vec{u} \cdot \vec{f}(\vec{r}, \vec{u}, t) d^3v = \text{magnetic moment/volume} \right.$$

\equiv Magnetization

For a dipole $\vec{B} = -\vec{\nabla}\Psi$ remind: (Parks (3.10))

where $\Psi = -\vec{M} \cdot \nabla\left(\frac{1}{r}\right)$ for dipole

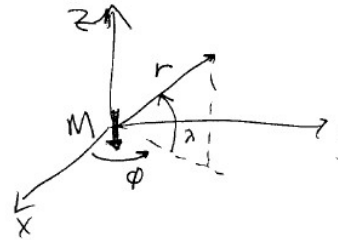
in spherical coords:

$$B_r = \frac{\partial}{\partial r} \Psi = -2M \frac{\sin^2 \lambda}{r^3}$$

$$B_\theta = \frac{1}{r \cos \lambda} \frac{\partial}{\partial \theta} \Psi = 0$$

$$B_\lambda = -\frac{1}{r} \frac{\partial}{\partial \lambda} \Psi = M \frac{\cos \lambda}{r^3}$$

$$|\vec{B}| = \sqrt{B_r^2 + B_\lambda^2 + B_\theta^2} = \frac{M}{r^3} (1 + 3 \sin^2 \lambda)^{1/2}$$



~~⊗~~

from Parks 3.30 / 3.31 can write

$$\frac{dr}{r} = 2 \frac{d(\cos \lambda)}{\cos \lambda}$$

integrate to get

$$\phi = \phi_0 \quad \underline{r = r_0 \cos^2 \lambda}$$

Now let $L \equiv \frac{r_0}{R_e}$

marks Equatorial distance
of a particular Field Line

$$\text{so } \boxed{r = L R_e \cos^2 \lambda}$$

over \rightarrow

or, to put it another way,
the Latitude at the surface is given
by $r = R_e$ so $\cos^2 \lambda = \frac{1}{L}$

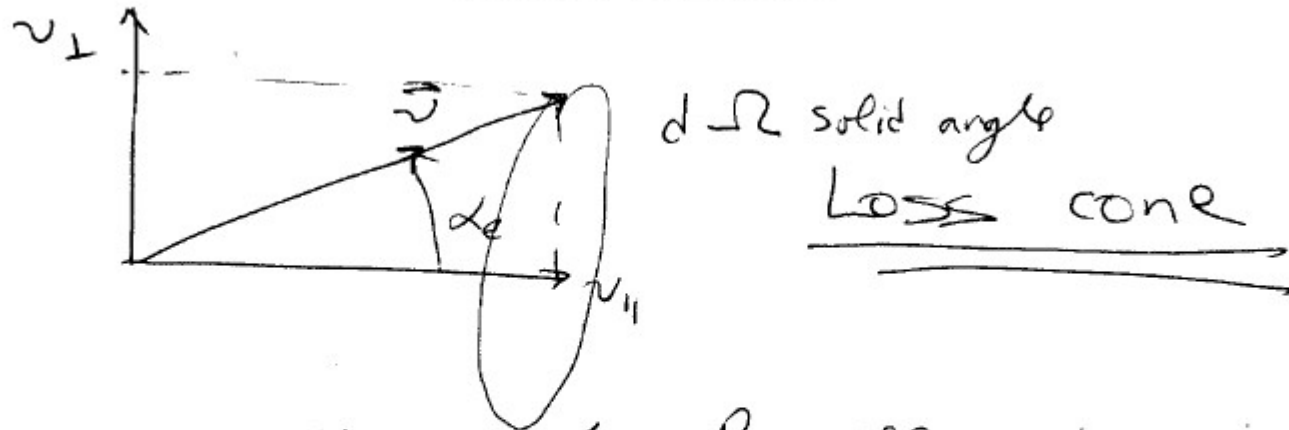
This is definition of Invariant Latitude

L can be defined more carefully for a distorted field.

So, for a given L shell most particles
will be undergoing 3 distinct motions -
(gyration, bounce + VB drift) but if
mirror point is $< 1 R_e$ they will be
lost due to scattering from atmosphere.

Actually, the loss altitude $\sim R_e + 100 \text{ km}$ where
probability of scattering becomes high

Which Particles are Lost?



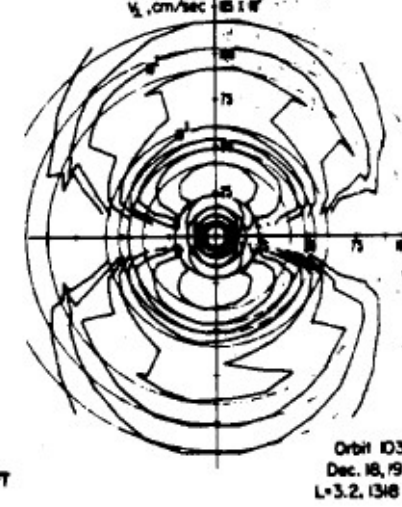
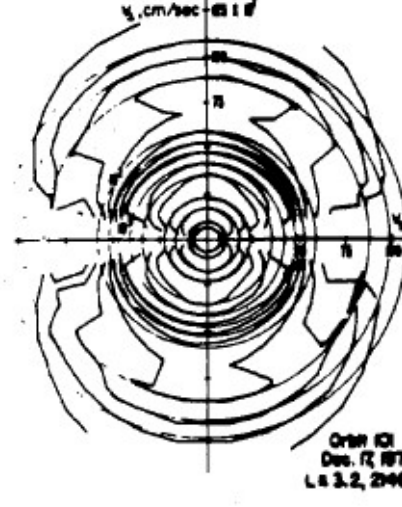
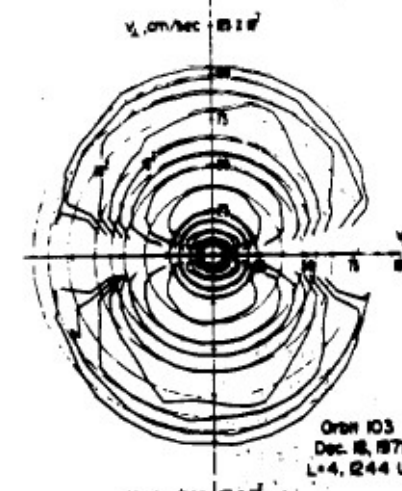
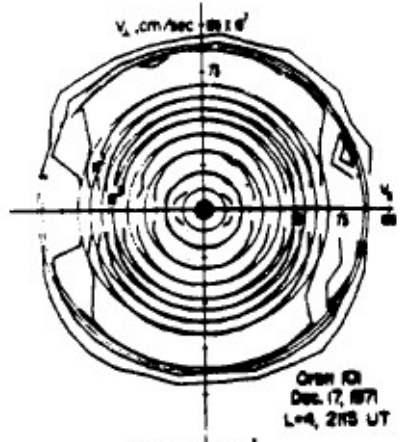
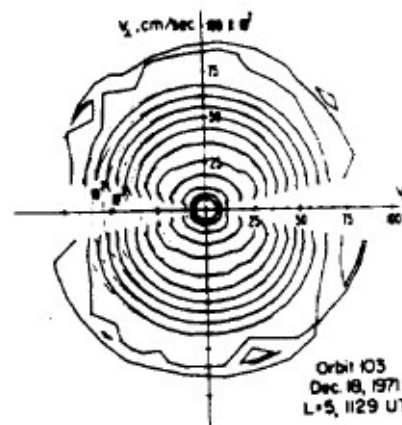
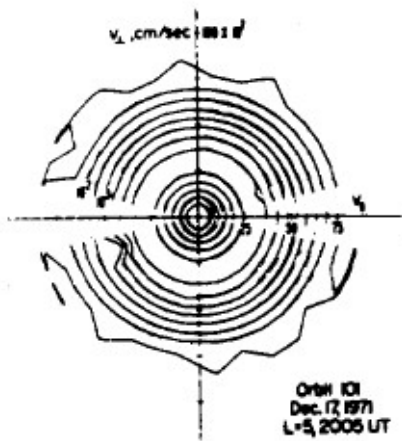
if mirror point is $<$ particle is lost.

$R_e + 100 \text{ km}$, then
Find this α_e

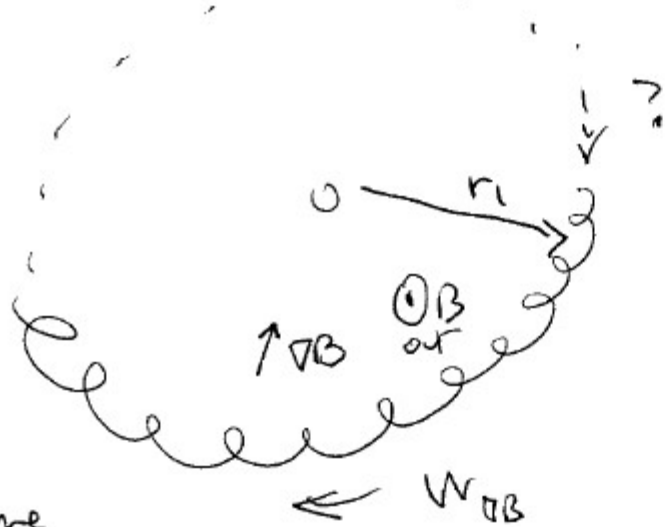
using $\mu = \text{constant} = \frac{v^2 \sin^2 \alpha_e}{B_e}$

find α_e such that $\alpha = 90^\circ$ at B for $r = R_e + 100 \text{ km}$
we find that $\alpha_e \sim 3^\circ$ at $L = 6$
so MOST particles are trapped.

show Pitch angle Distributions along Field Lines



L-shell drift: How can you tell the drift motion always returns guiding center to starting point?



assume
equatorially mirroring
 then $E = E_{\perp}$ always

Answer: if energy is conserved then B_1 with $\mu = \text{constant}$, if start from r_1 where $B = B_1$

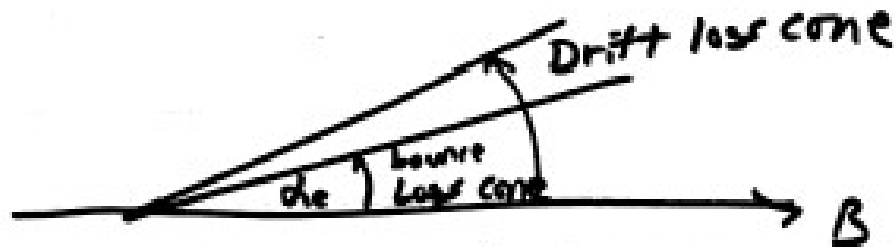
$$\mu = \frac{E}{B_1} \text{ at } r_1$$

if returned at $r \neq r_1$, $B \neq B_1$
 so $\mu \neq \text{constant}$

L defines a closed shell for perfect dipole

Ah! But the field is not a perfect dipole:

Drift loss cone



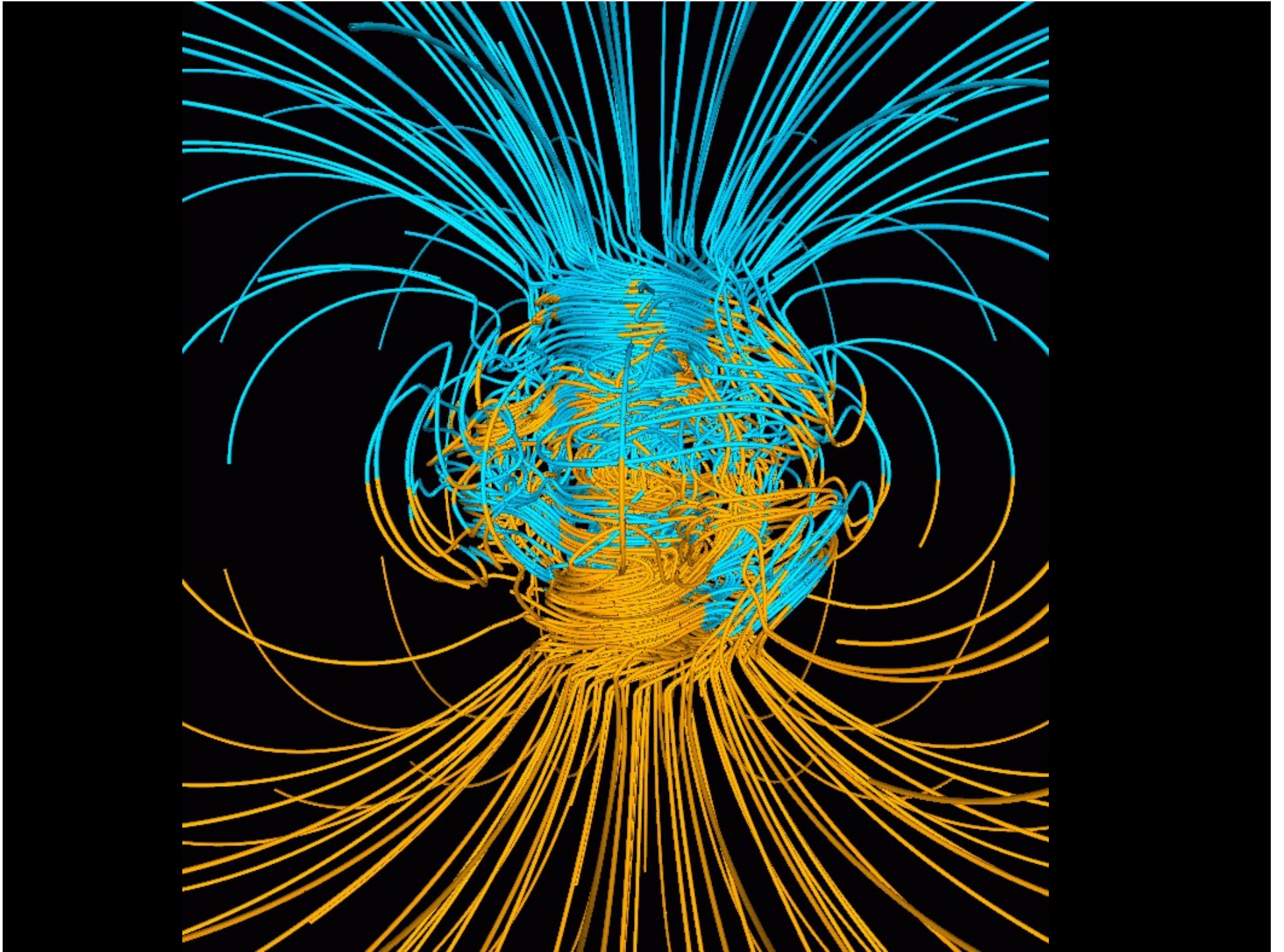
Drift loss cone = largest α_e at equator which equals the bounce loss cone at some longitude.

That is: all particles in the bounce loss cone are lost in 1 bounce period

while particles in the drift loss cone are lost sometime during their drift period. Namely, somewhere in drift period they see the Smallest Earth's field so their mirror point is lowest.

Waves are constantly affecting particles' pitch angles.

So, there is a random diffusion of particles from larger to smaller pitch angles, where particles get lost inside the loss cone, or drift loss cone.



Contours of constant Magnetic field Strength

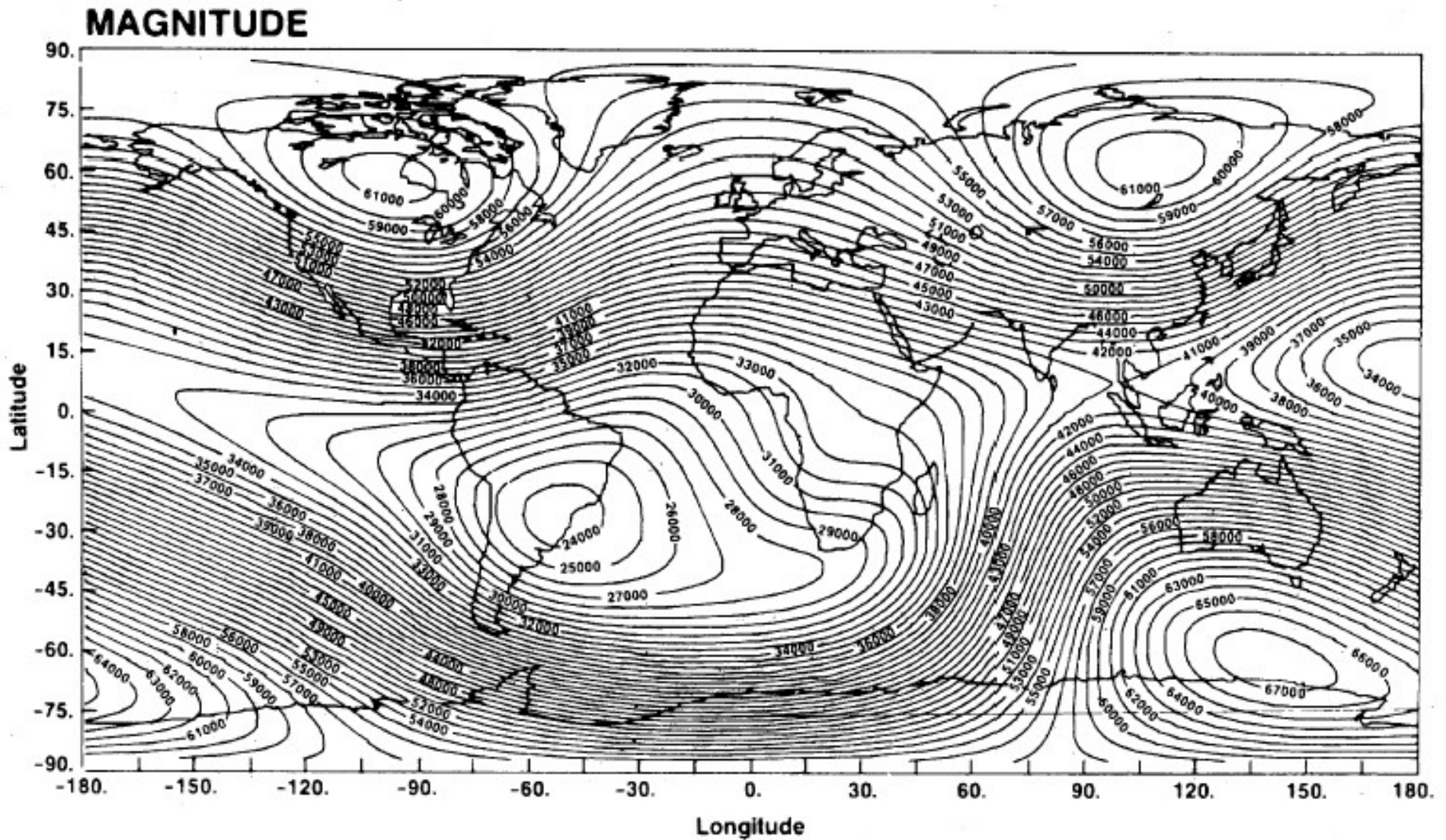


Figure 4-11. Contours of constant total field B at the surface of the earth from the model IGRF 1980.0.

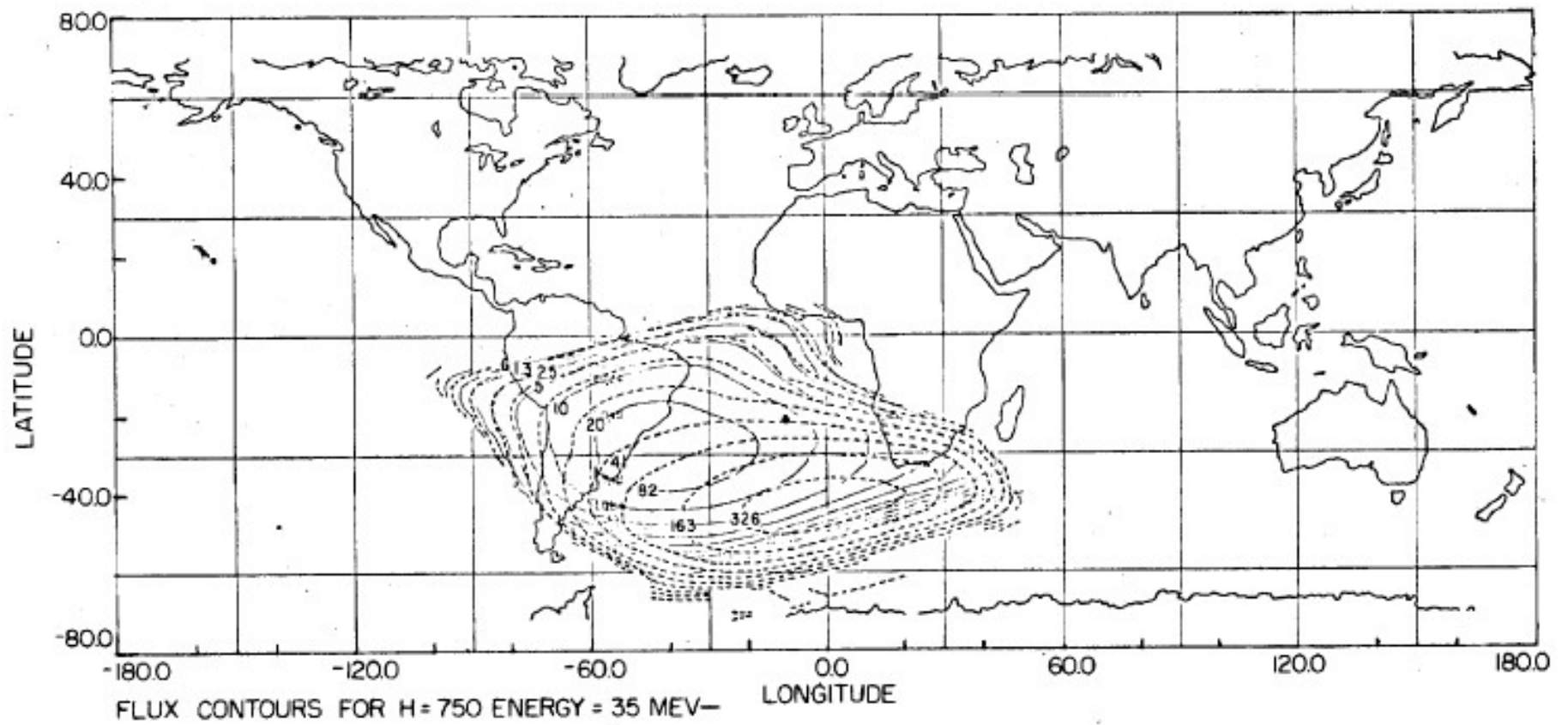
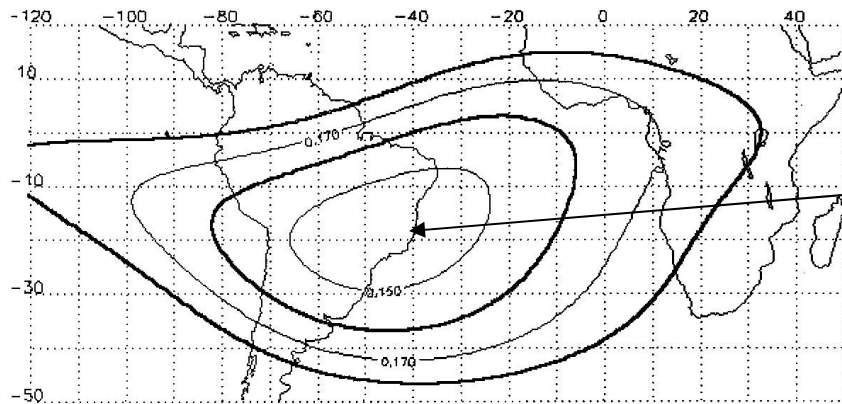


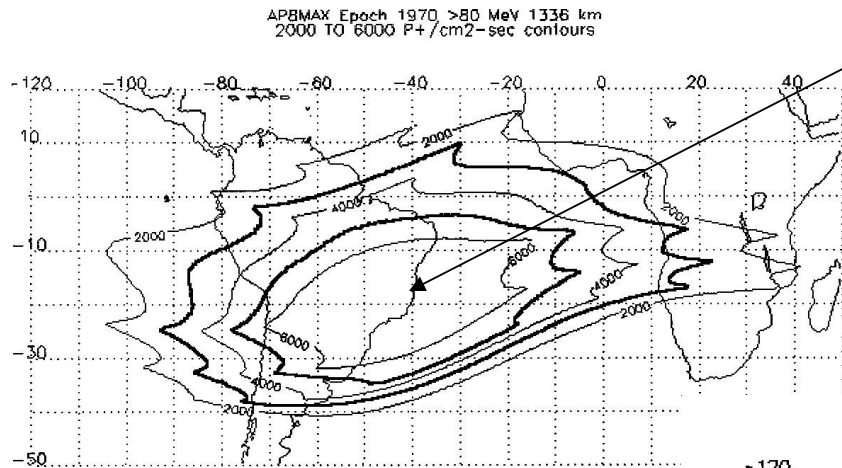
Figure 5-33. Proton isointensity flux contours as measured in the South Atlantic anomaly at an altitude of 750 km. The solid lines depict 28-45 MeV proton (ion) fluxes and the dashed lines 5-7 MeV proton fluxes. The flux units are particles/(cm²-s-MeV).



Magnetic Field Minimum

Precipitating $>80\text{MeV}$ protons

Figure 1. DGRF 65, Epoch 1970, 1336 km magnetic field contours.



Single Event Upsets in the
memory for Topex Satellite

Figure 2. AP-8 MAX Epoch 1970 $>80\text{MeV}$ protons at 1336 km.

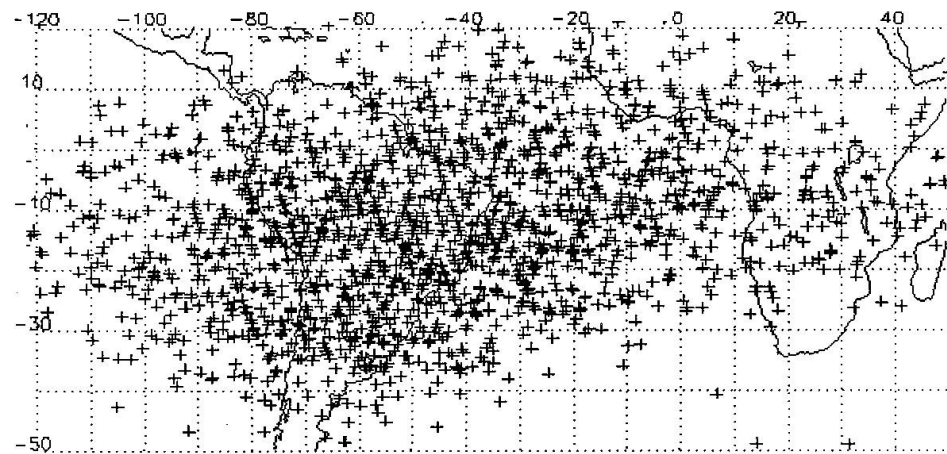


Figure 3. TOPEX SEE geographical distribution.

Advanced subject

For details see
adiabatic_invariants.pdf

Adiabatic Invariant

$$I(\bar{z}, \delta) = \oint d\theta \bar{p}(\bar{z}, \theta, \delta) \cdot \frac{\partial \bar{q}(\bar{z}, \theta, \delta)}{\partial \theta}$$

Usually abbreviated

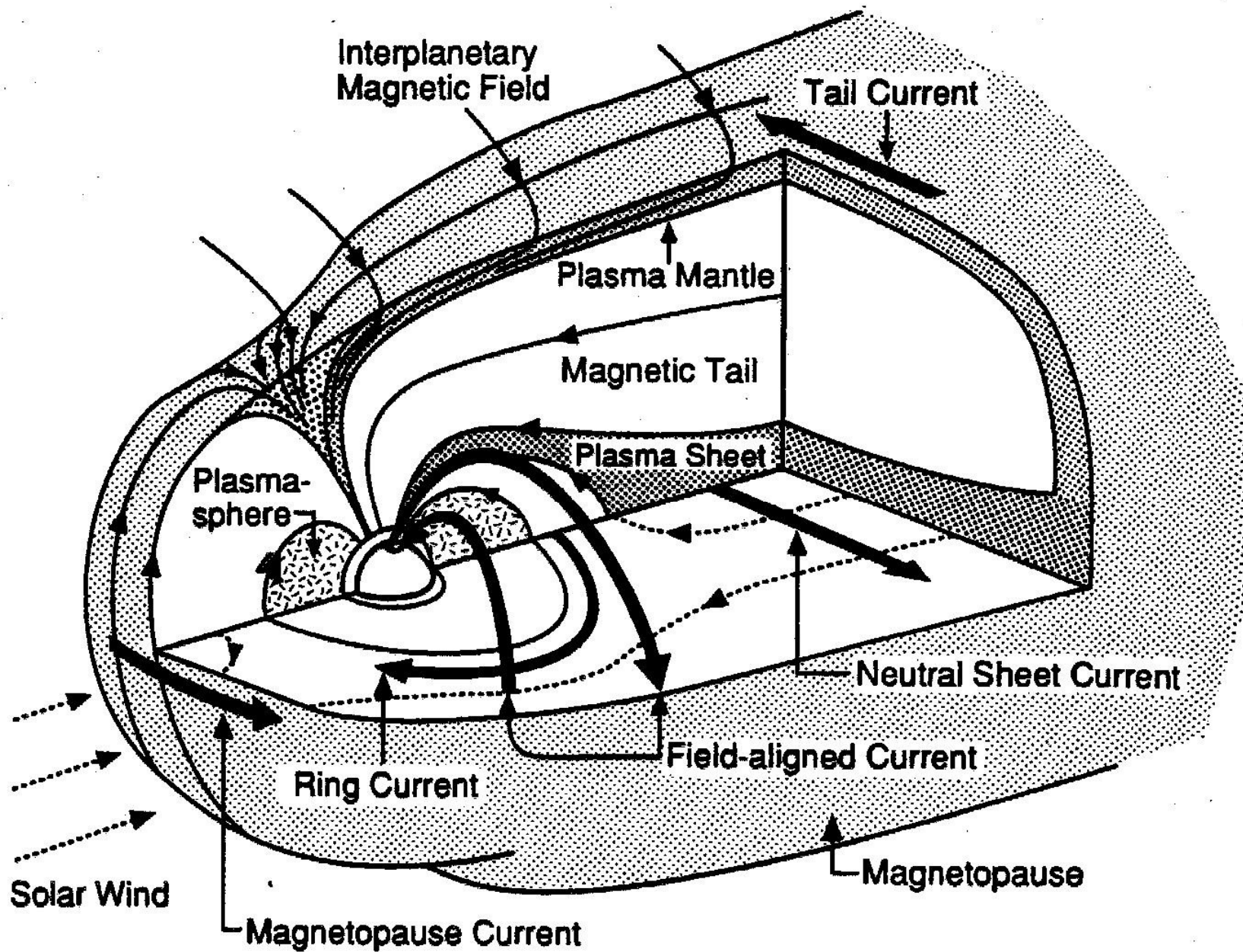
$$I = \oint_{\bar{z}=\text{constant}} \bar{\mathbf{p}} \cdot d\bar{\mathbf{q}} \stackrel{\text{by Stokes theorem}}{=} \int d^3 p d^3 q$$

but $\int d^3 p d^3 q$ has same value for any canonical \bar{p}, \bar{q}

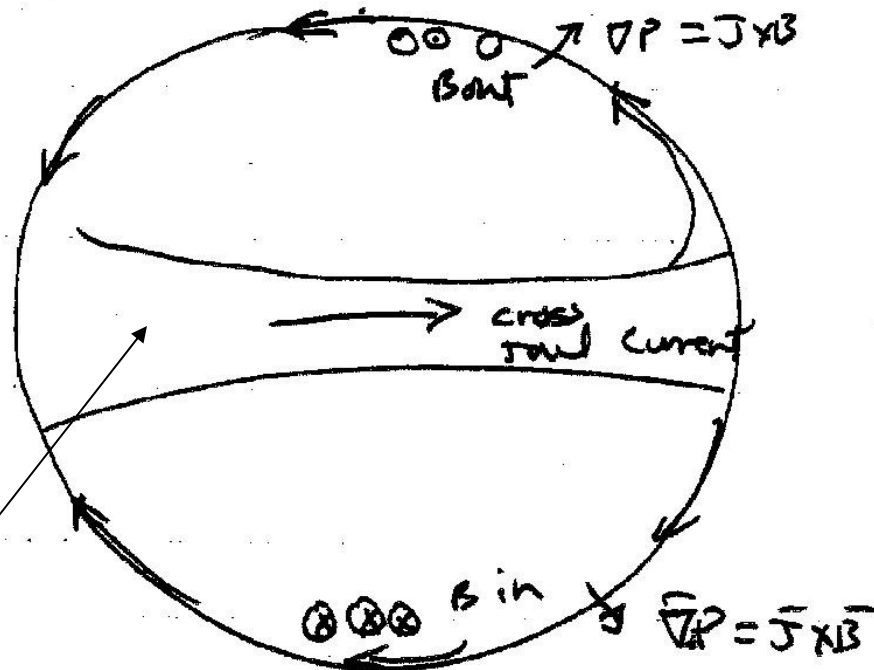
• since transformation ^{from} ~~from~~ unperturbed to perturbed \bar{p}, \bar{q} is canonical

$$\int_{\text{actual motion}} d^3 p d^3 q = \int_{\text{unperturbed motion}} d^3 p d^3 q = \oint_{\bar{z}=\text{constant}} \bar{\mathbf{p}} \cdot d\bar{\mathbf{q}} \quad \text{unperturbed motion}$$

- Now, lets look at magnetotail Tail curenents
- Then combine cold and hot plasma drifts
- Cold:
 - Sunward convection on closed field lines
 - Plasmasphere co-rotation
- Hot
 - Ring current
 - Partial ring current/Alfven layer
- Then: Aurora and ionosphere



tail cross section

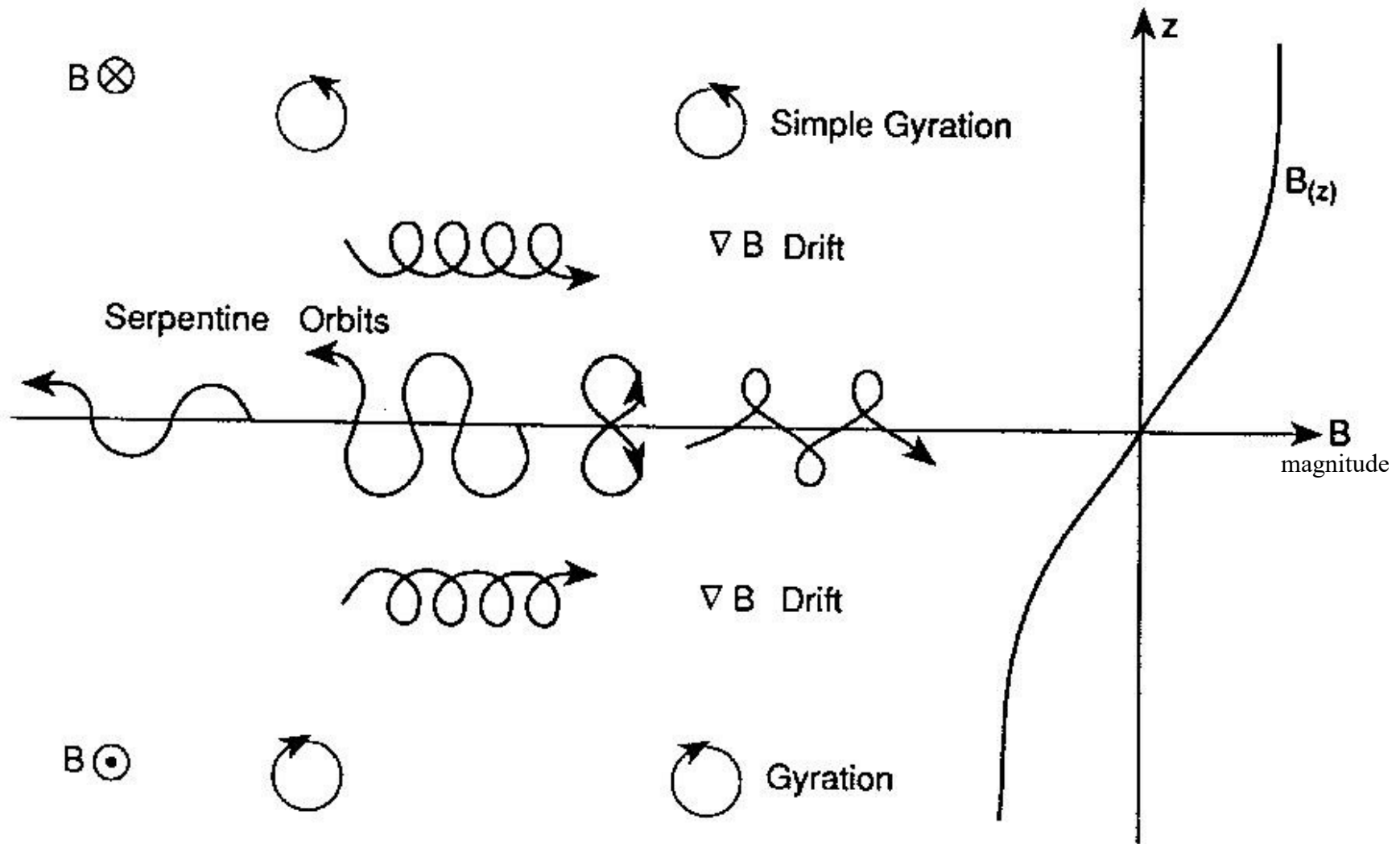


View from Earth
Looking
Away from
SUN

closed
with
Magnetization
current

How can there be a current

Like this: charge moving ACROSS
the B-field?



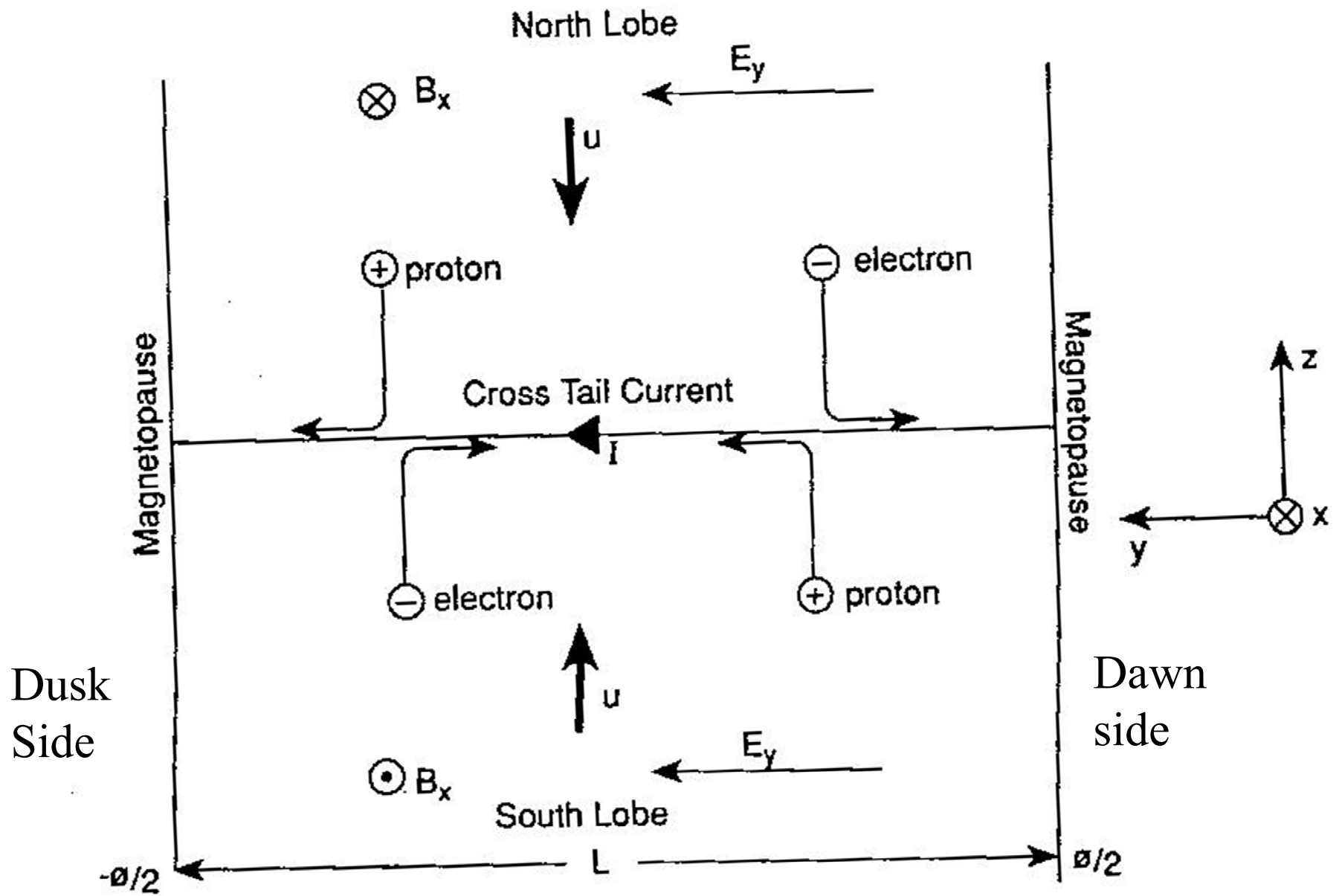
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View from the Tail looking back at Earth

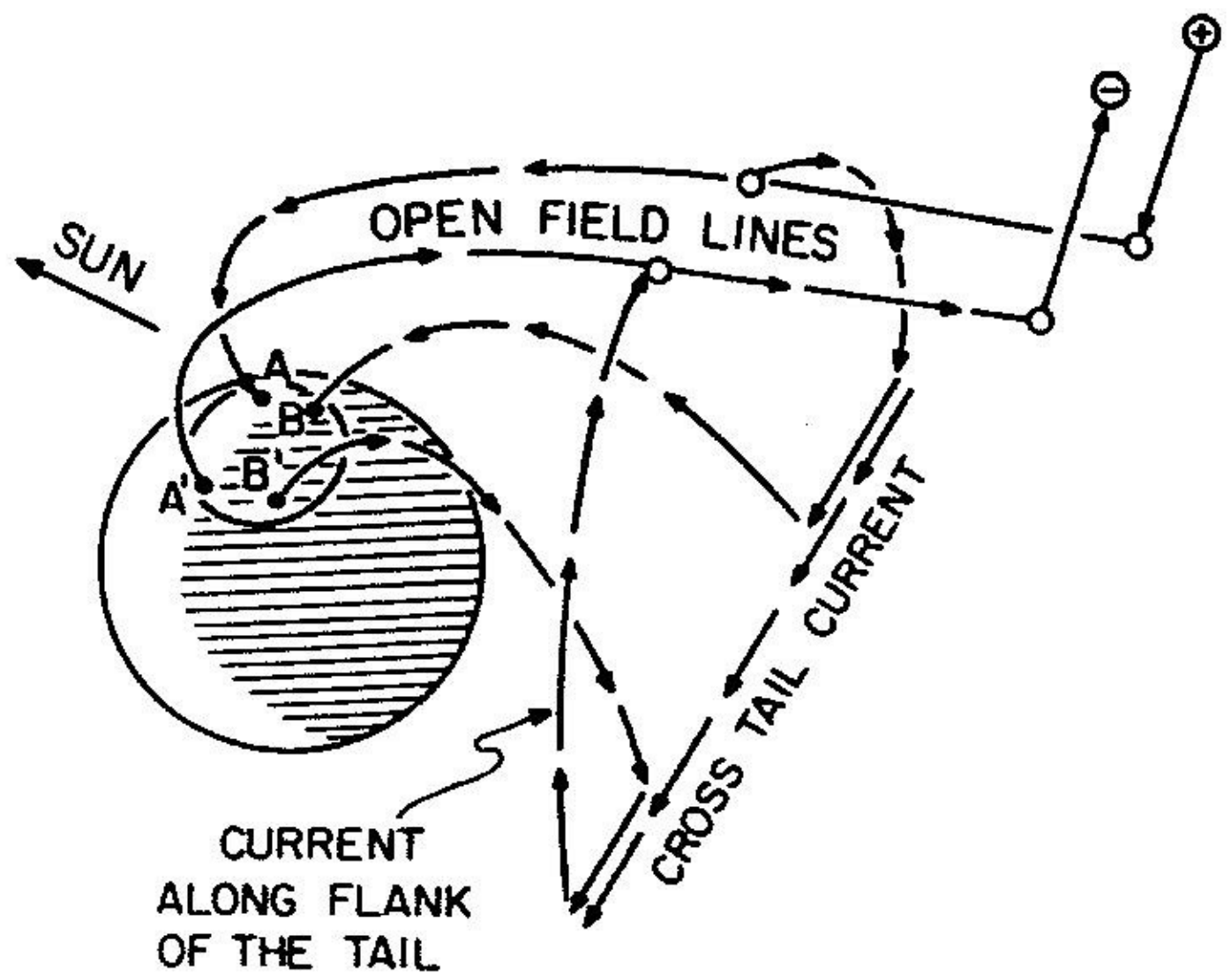
Dusk



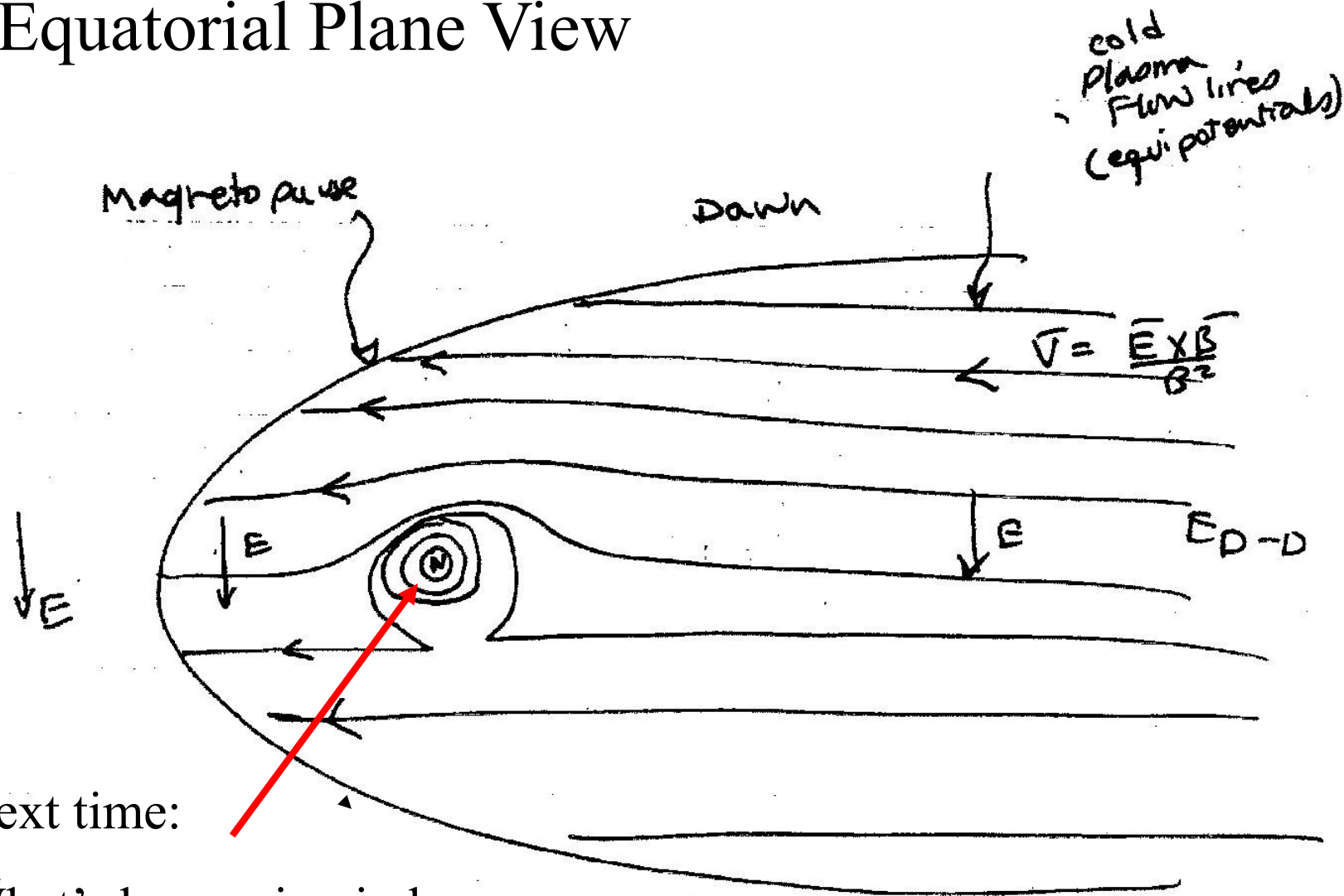
dawn



View from Tail towards Earth



Equatorial Plane View

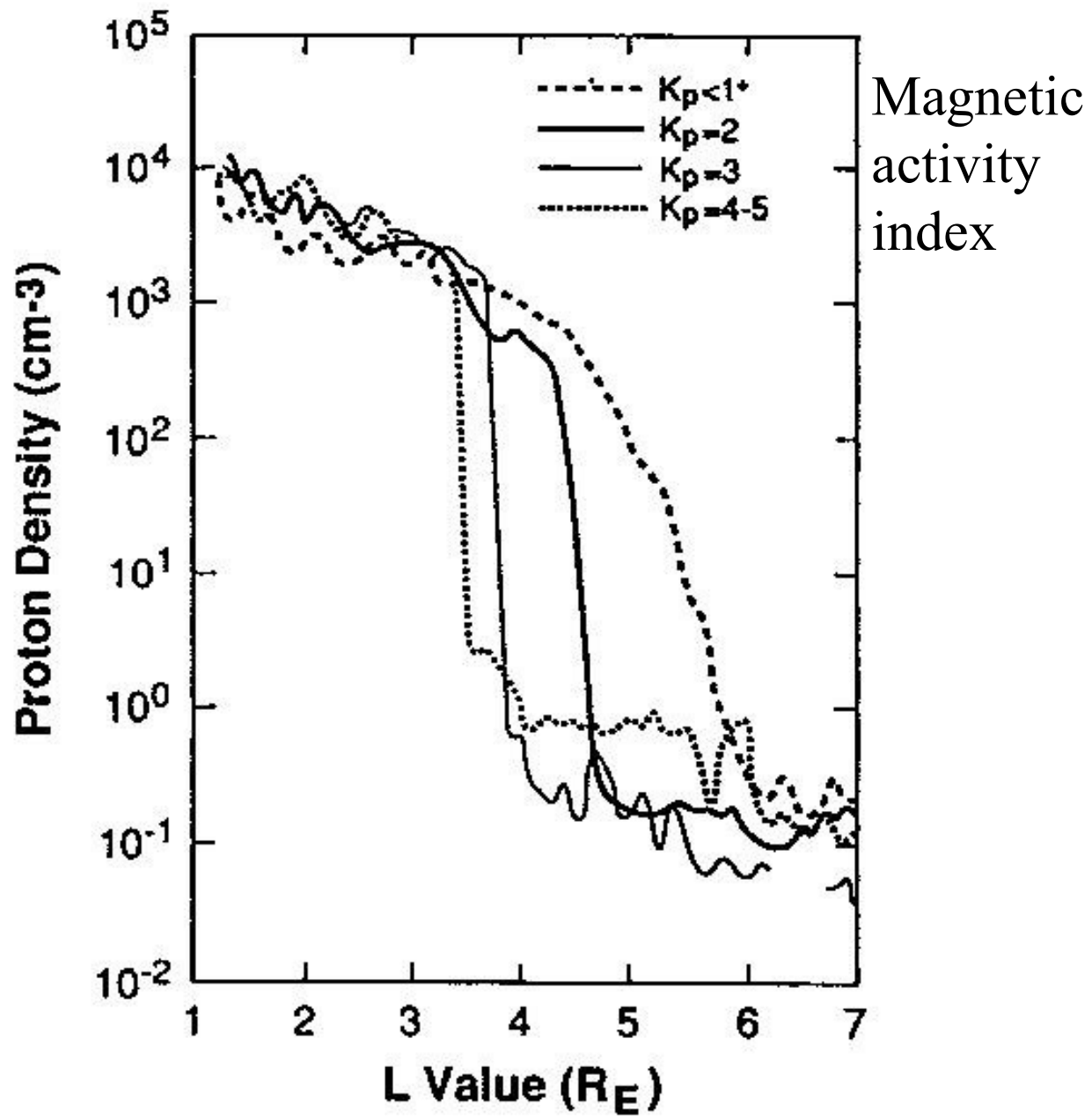


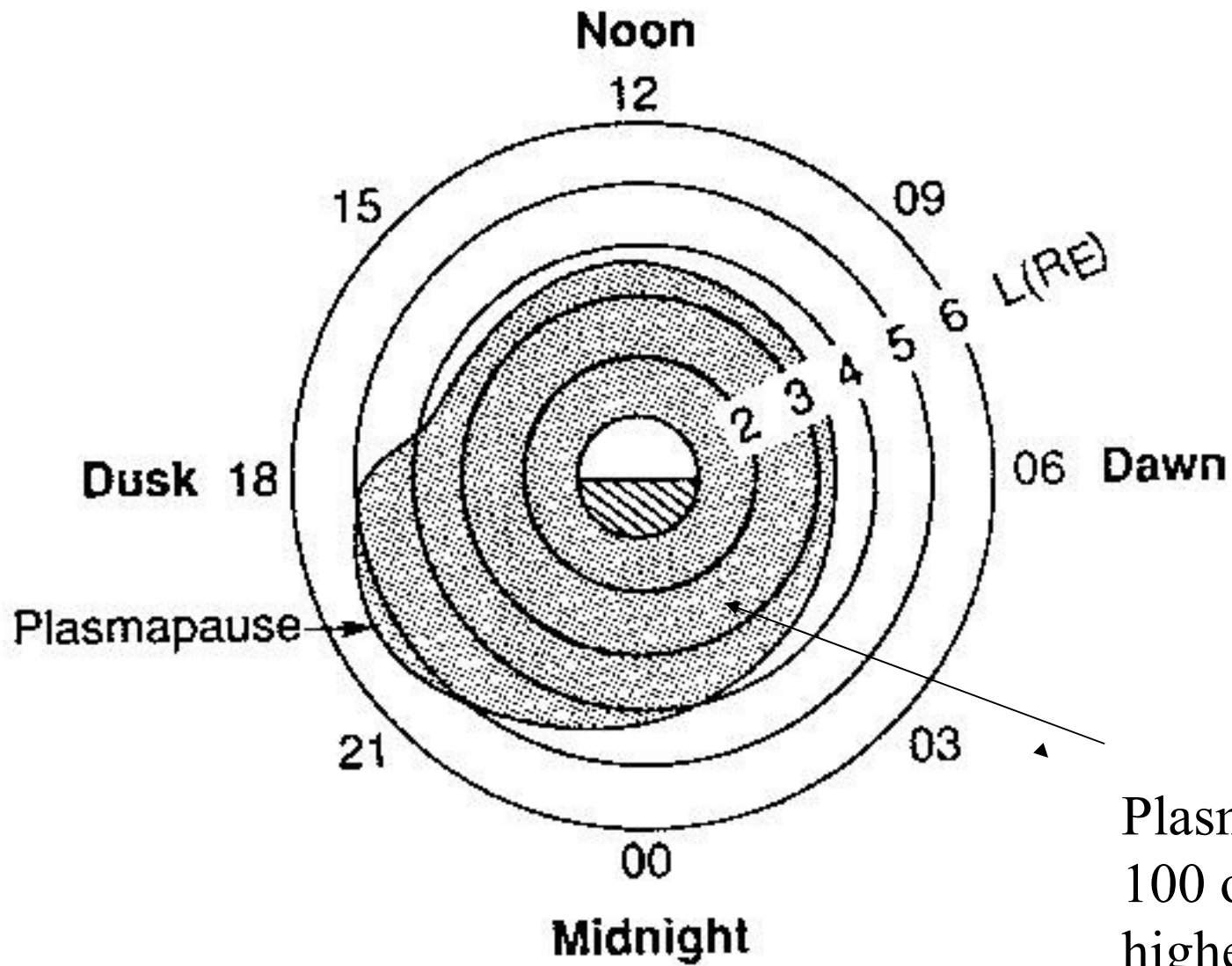
Next time:

What's happening in here

In the Plasmasphere?

DUSTC





Plasma density
100 or 1000 times
higher than outer
magnetosphere