



Advanced Propulsion, Power, & Comm.
for Space, Sea, & Air

Space Tethers 101



Dr. Rob Hoyt

CEO & Chief Scientist

Tethers Unlimited, Inc.

www.tethers.com

Agenda

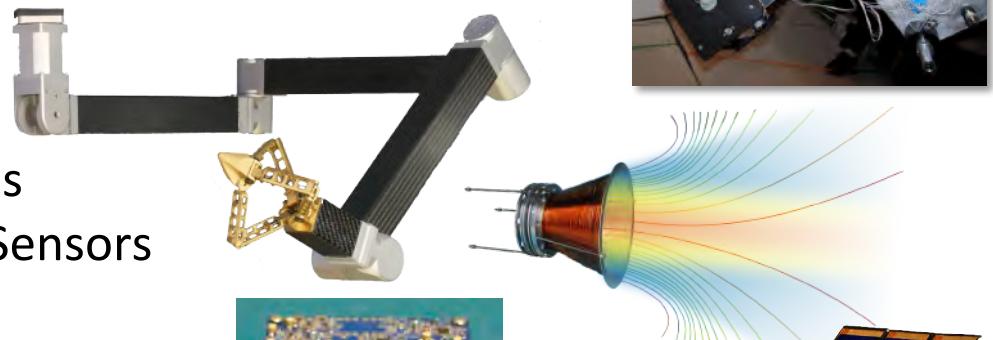
- About Tethers Unlimited, Inc.
- What's a Space Tether?
- History & Status of Tethers
- Space Tether Physics
- Electrodynanic Propulsion
- Momentum Exchange Propulsion

About Tethers Unlimited, Inc.



Advanced Propulsion, Power, & Comm
for Space, Sea, & Air

- **Founded in 1994 by Robert L. Forward & Robert Hoyt**
- **NASA SBIR & NIAC funding fueled initial growth**
 - 2005 NASA SBIR “Success Story” Selection
- **Successfully completed >70 contracts for NASA, DARPA, Navy, AFRL, Army, & industry primes**
- **Designed, built, launched, & operated a 3-picosatellite space flight mission in 2007, for less than \$1M**
- **7 Patents on space technologies**
- **Core Technologies:**
 - Tether Propulsion & De-Orbit Technologies
 - Software Defined Radio Comm. and Nav. Sensors
 - Deployable Apertures and Structures
 - Additive Manufacturing of Spacecraft Components
 - Space Robotics
 - Optical Fiber Tether Dispensers for Mobile Robots

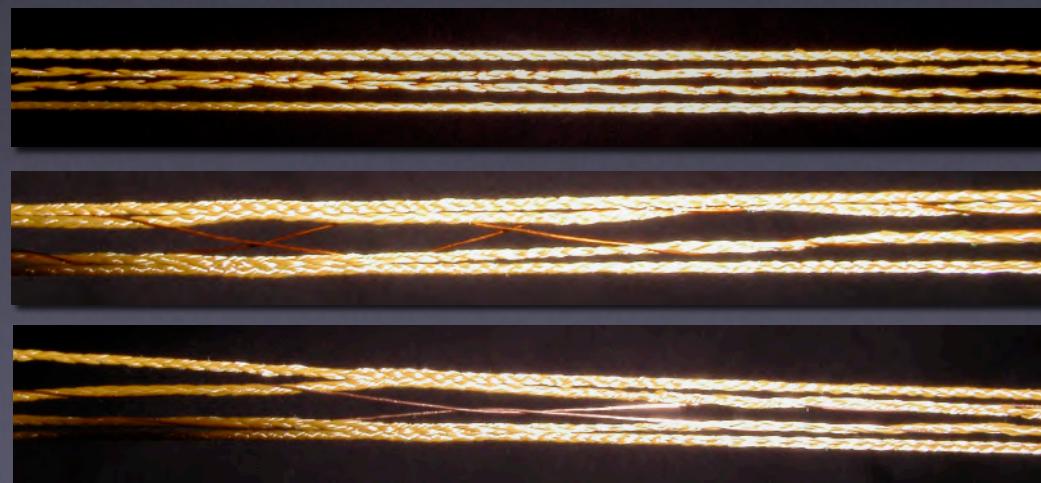
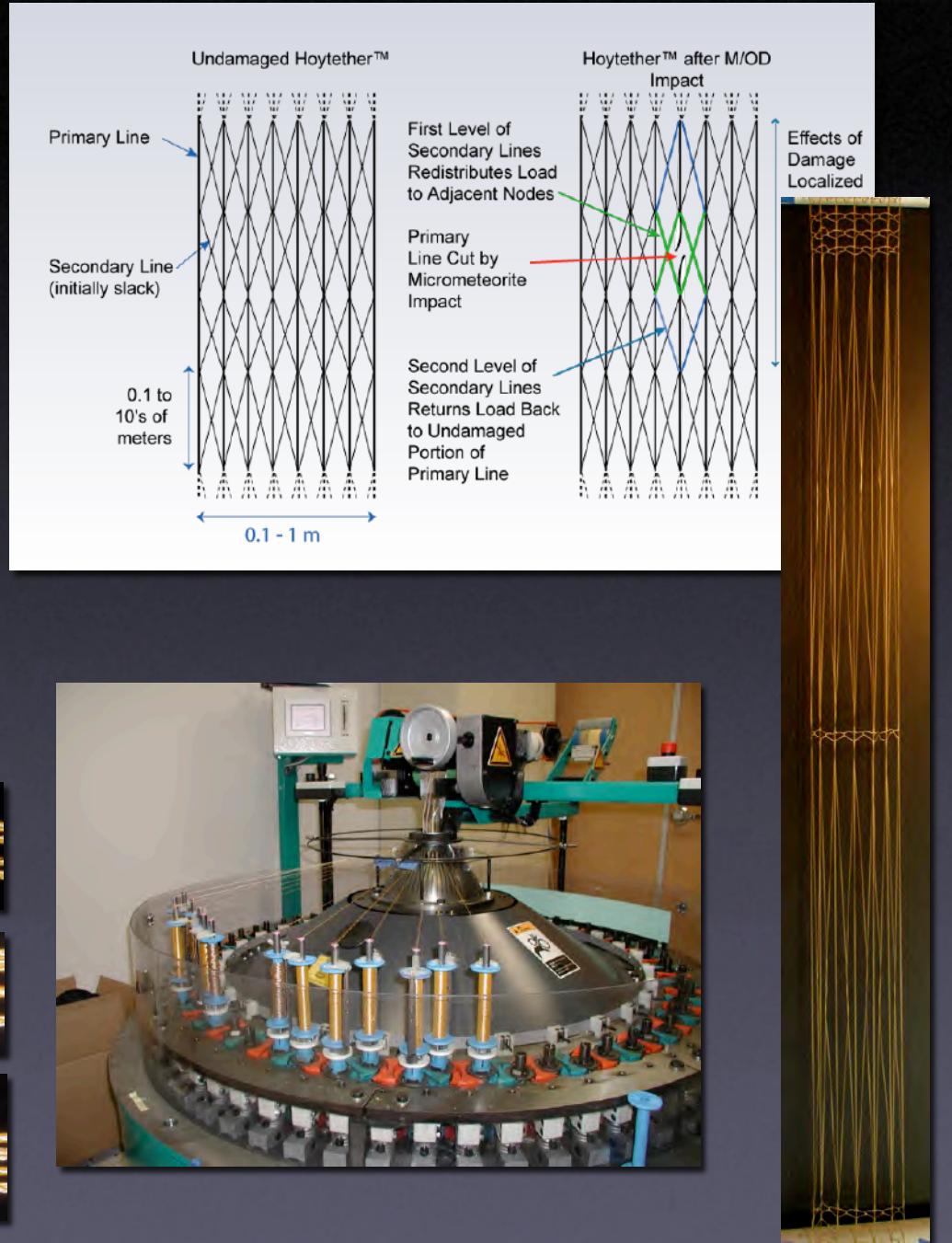


Space Tethers

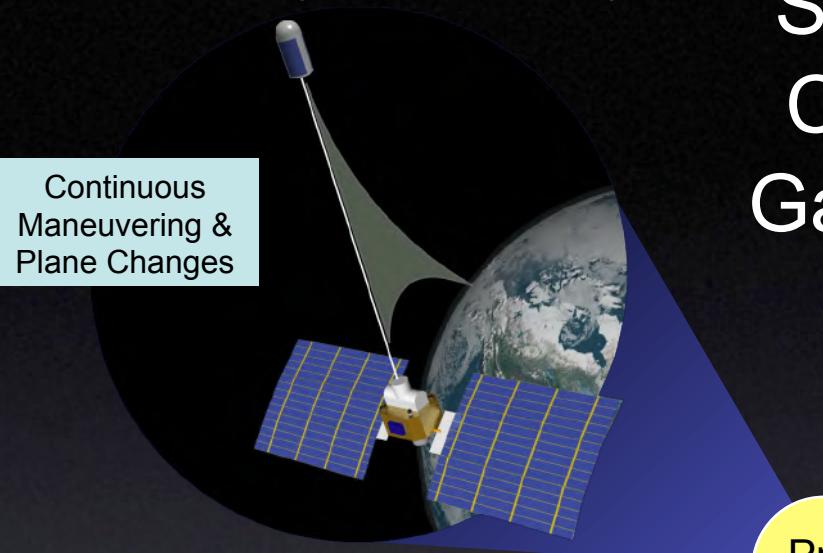
- Long, thin cable or wire deployed from a spacecraft
- High strength tethers can enable momentum transfer from one spacecraft to another
- Conducting tethers can create propulsive forces through Lorentz force interactions with the Earth's magnetic field

High-Strength Space-Survivable Tether

- Materials available today (eg Spectra, Dyneema, Zylon) are sufficient for most applications
- Hoytether design provides structural redundancy to enable high survival probability for multi-year durations
- Can incorporate conducting elements to enable electrodynamic operations

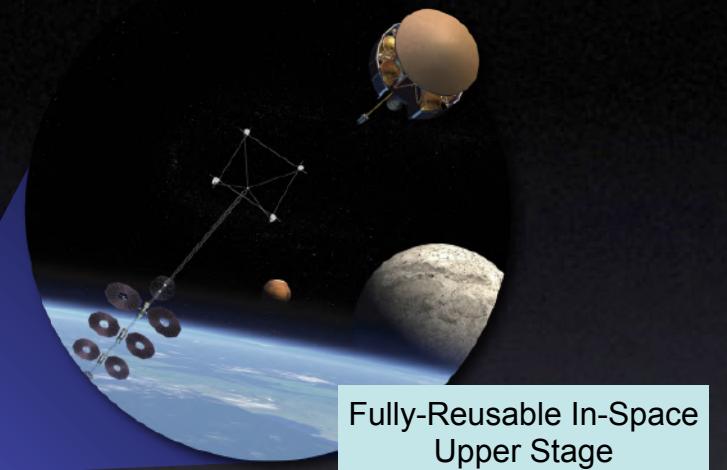


Electrodynamic Tether Orbit-Raising and Repositioning

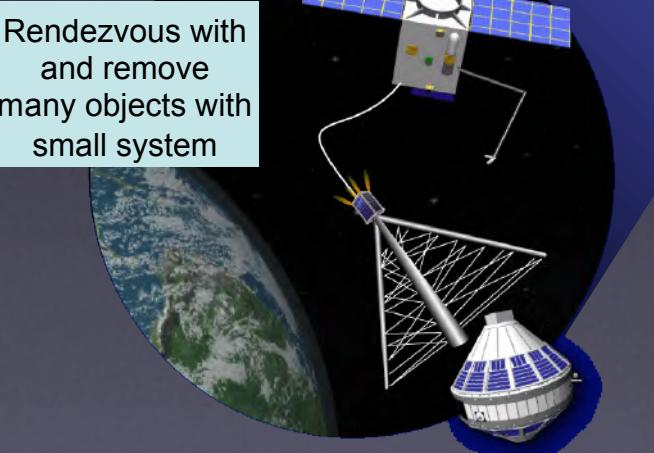


Space Tethers: Cross-Cutting, Game-Changing Benefits

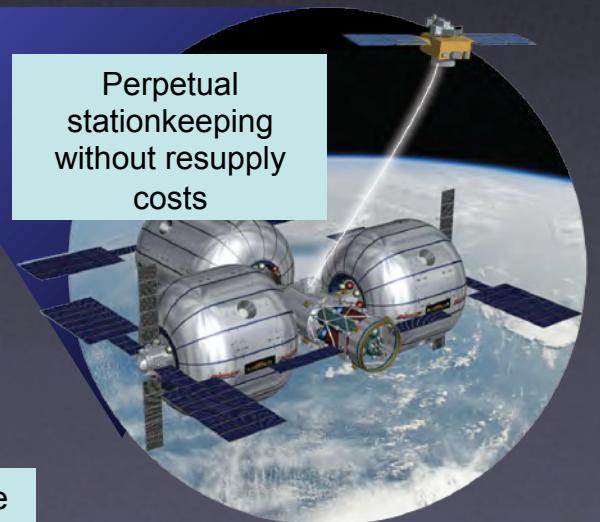
Momentum-Exchange Launch-Assist & Orbit Transfer



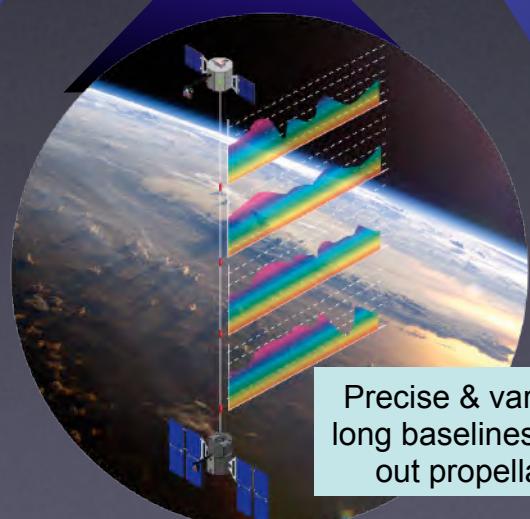
Propellantless propulsion
enables **large ΔV**
missions with **low mass
impact**



Capture & Deorbit of Space Debris



Drag-Makeup Stationkeeping
for LEO Assets



Formation Flying for
Multi-Point Science & Long-Baseline Sensing

History & Status of Space Tethers

Space Tethers: Prior Missions

■ = Met All Mission Goals ■ = Did Not Meet All Mission Goals

| Year | Mission | Type | Description | Lessons Learned |
|------|-----------------------|-------------------|--|---|
| 1966 | Gemini-11 | Dynamics | <ul style="list-style-type: none"> • 15-m tether between capsules • Tethered capsules set in rotation | + Successful deployment and stable rotation |
| 1966 | Gemini-12 | Dynamics | <ul style="list-style-type: none"> • 30-m tether between capsules • Tethered capsules set in rotation | + Successful deployment and stable rotation |
| 1989 | OEDIPUS-A | ED/Plasma Physics | <ul style="list-style-type: none"> • Sounding rocket experiment • 958-m conducting tether, spinning | + Successfully demonstrated strong EM coupling between the ends of conducting tether + Obtained data on behavior of tethered system as large double electrostatic probe |
| 1992 | TSS-1 | ED/Plasma Physics | <ul style="list-style-type: none"> • 20-km insulated conducting tether to study plasma-electrodynamic processes and tether orbital dynamics | - Too-long bolt added without proper review caused jam in tether deployer + Demonstrated stable dynamics of short tethered system + Demonstrated controlled retrieval of tether |
| 1993 | SEDS-1 | Momentum Exchange | <ul style="list-style-type: none"> • Deployed payload on 20-km nonconducting tether and released it into suborbital trajectory | + Demonstrated successful, stable deployment of tether + Demonstrated deorbit of payload |
| 1993 | PMG | ED | <ul style="list-style-type: none"> • 500-m insulated conducting tether • Hollow cathode contactors at both ends | + Demonstrated ED boost and generator mode operation - Did not measure thrust |
| 1994 | SEDS-2 | Dynamics | <ul style="list-style-type: none"> • Deployed 20-km tether to study dynamics and survivability | + Demonstrated successful, controlled deployment of tether with minimal swing |
| 1995 | OEDIPUS-C | ED/Plasma Physics | <ul style="list-style-type: none"> • Sounding rocket experiment • 1174-m conducting tether, spinning | + Successfully obtained data on plane and sheath waves in ionospheric plasma |
| 1996 | TSS-1R | ED/Plasma Physics | <ul style="list-style-type: none"> • 20-km insulated conducting tether to study plasma-electrodynamic processes and tether orbital dynamics | + Demonstrated electrodynamic efficiency exceeding existing theories + Demonstrated ampere-level current - Flaw in insulation allowed high-voltage arc to cut tether - Tether was not tested prior to flight |
| 1996 | TiPS | Dynamics | <ul style="list-style-type: none"> • Deployed 4-km nonconducting tether to study dynamics and survivability | + Successful deployment + Tether survived over 10 years on orbit |
| 1999 | ATEx | Dynamics | <ul style="list-style-type: none"> • Tape tether deployed with pinch rollers | - "Pushing on a rope" deployment method resulted in unexpected dynamics, experiment terminated early |
| 2000 | Picosats 21/23 | Formation | <ul style="list-style-type: none"> • 2 picosats connected by 30-m tether | + Demonstrated tethered formation flight |
| 2001 | Picosats 7/8 | Formation | <ul style="list-style-type: none"> • 2 picosats connected by 30-m tether | + Demonstrated tethered formation flight |
| 2002 | MEPSI-1 | Formation | <ul style="list-style-type: none"> • 2 picosats connected by 50-ft tether • Deployed from Shuttle | + Tethered formation flight |
| 2006 | MEPSI-2 | Formation | <ul style="list-style-type: none"> • 2 picosats connected by 15-m tether • Deployed from Shuttle | + Tethered formation flight of nanosats with propulsion and control wheels |
| 2009 | AeroCube-3 | Formation | <ul style="list-style-type: none"> • 2 picosats connected by 61-m tether • Deployed from Minotaur on TacSat-3 launch | + Tethered formation flight with tether reel and tether cutter |
| 2007 | MAST | Dynamics | <ul style="list-style-type: none"> • 3 tethered picosats to study tether survivability in orbital debris environment | - Problem with release mechanism resulted in minimal tether deployment; + Obtained data on tethered satellite dynamics |
| 2007 | YES-2 | Momentum Exchange | <ul style="list-style-type: none"> • Deployed payload on 30-km nonconducting tether and released it into suborbital trajectory | + Tether did deploy, but: - Controlling computer experienced resets during tether deployment, preventing proper control of tether deployment |
| 2010 | T-REX | ED/Plasma Physics | <ul style="list-style-type: none"> • Sounding rocket experiment • 300-m bare tape tether | + Successfully deployment of tape and fast ignition of hollow cathode |

>70% of Tether Missions Have Been Fully Successful

Early Rocket Test History

| Rocket # | Date | Successes/Failures |
|----------|--------------|-----------------------------------|
| 2 | 18 Mar 1942 | • Gyro & propellant feed failures |
| 3 | 16 Aug 1942 | • Nose broke off |
| 4 | 3 Oct 1942 | • Success |
| 5 | 21 Oct 1942 | • Steam generator failure |
| 6 | 9 Nov 1942 | • Success |
| 7 | 28 Nov 1942 | • Tumbled |
| 9 | 9 Dec 1942 | • Hydrogen peroxide explosion |
| 10 | 7 Jan 1943 | • Explosion on ignition |
| 11 | 25 Jan 1943 | • Trajectory failure |
| 12 | 17 Feb 1943 | • Trajectory failure |
| 13 | 19 Feb 1943 | • Fire in tail |
| 16 | 3 Mar 1943 | • Exploded in flight |
| 18 | 18 Mar 1943 | • Trajectory failure |
| 19 | 25 Mar 1943 | • Tumbled, exploded |
| 20 | 14 Apr 1943 | • Crashed |
| 21 | 22 Apr 1943 | • Crashed |
| 22 | 14 May 1943 | • Cut off switch failed |
| 25 | 26 May 1943 | • Premature engine cutoff |
| 26 | 26 May 1943 | • Success |
| 24 | 27 May 1943 | • Success |
| 23 | 1 Jun 1943 | • Premature engine cutoff |
| 29 | 11 Jun 1943 | • Success |
| 31 | 16 Jun 1943 | • Premature engine cutoff |
| 28 | 22 June 1943 | • Exploded in flight |



**80% Failure Rate
of Early Missions**

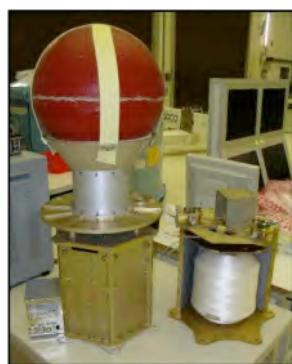
Past Space Tether Experiments

- Rotating tethered capsule experiments during Gemini missions
- Small Expendable Deployer System (SEDS)
 - SEDS 1: de-orbited a small payload using 20 km tether
 - SEDS 2: demonstrated controlled deployment of a 20 km tether
 - PMG: demonstrated basics of electrodynamic physics using 500 m conducting wire
- Shuttle Tethered Satellite System (TSS) - 20 km insulated conducting tether
 - TSS-1: 200 m deployed, demonstrated stable dynamics & retrieval
 - Last-minute S&MA demanded design change resulting in oversized bolt that jammed deployer (configuration control process failure)
 - TSS-1R: 19.9 km deployed, >5 hours of excellent data validating models of ED tether-ionosphere current flow
 - Arc caused the tether to fail (contamination of insulation & failure to properly test tether prior to flight)
- TiPS - Survivability & Dynamics investigation
 - 4 km nonconducting tether, ~1000 km alt, survived over 10 years on orbit
- MAST – low cost tethered CubeSat experiment
 - Release mechanism malfunction prevented full deployment of tether
- YES-2
 - Computer resets during deployment prevented proper control of deployment
- T-Rex (JAXA)
 - Demonstrated conducting tape deployment current collection on sounding rocket

Past missions demonstrated stable tether deployment and physics of electrodynamic propulsion

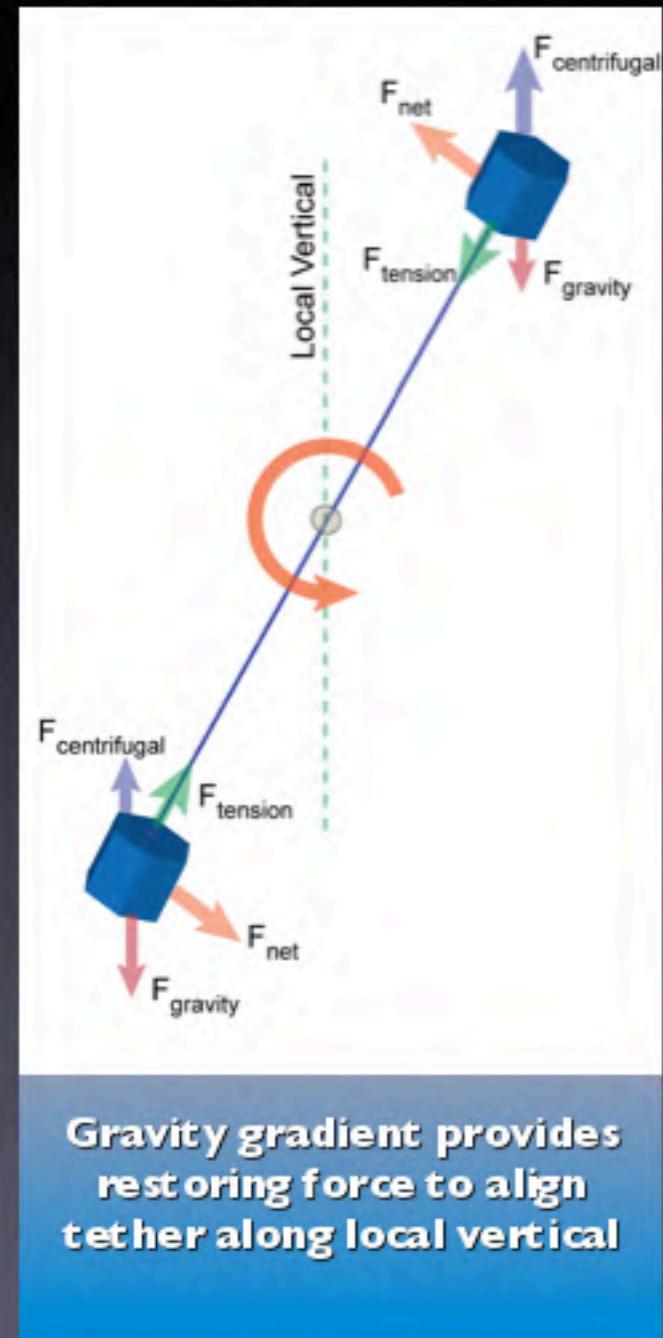
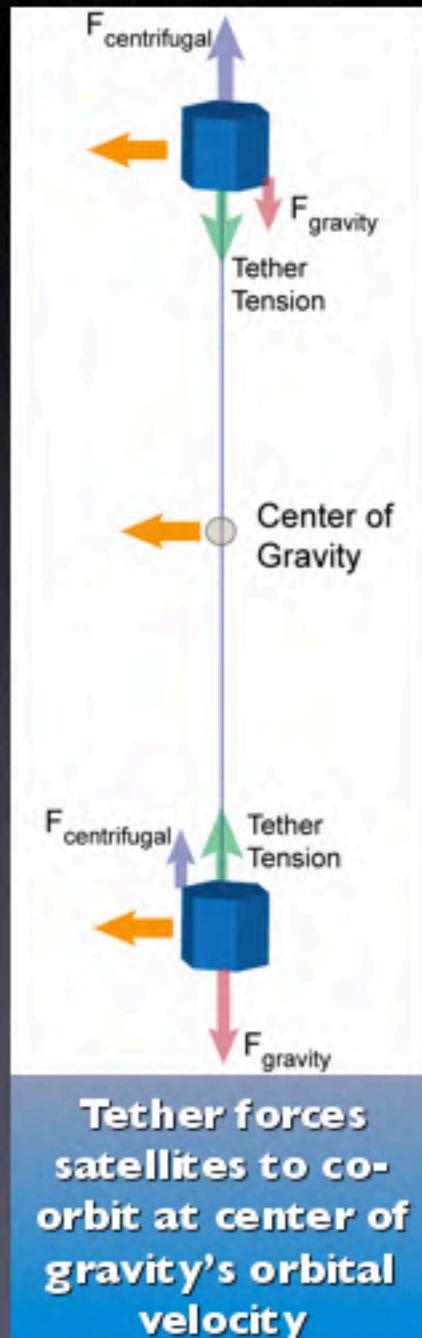
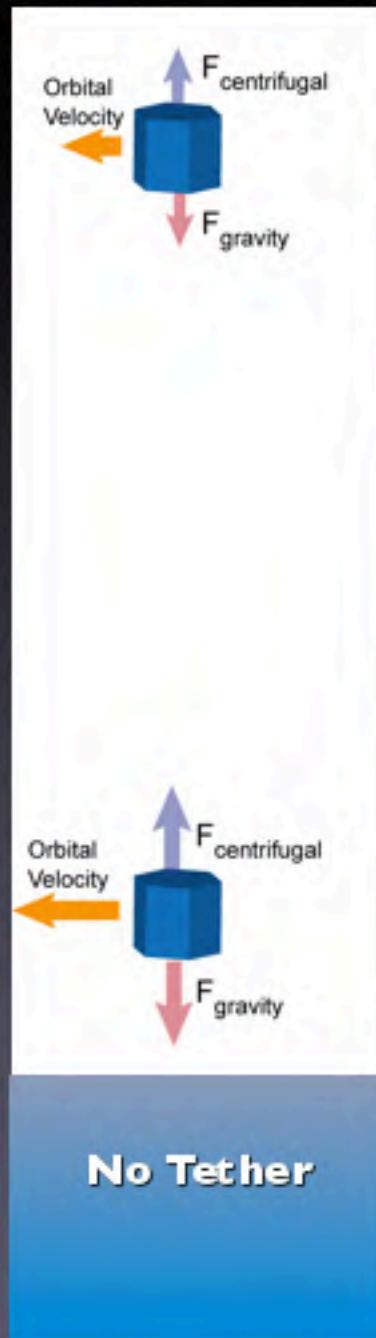
Mission failures were due to design, QA, & process errors, not due to fundamental physics

Significant, predictable orbital maneuvering with a tether still needs to be demonstrated



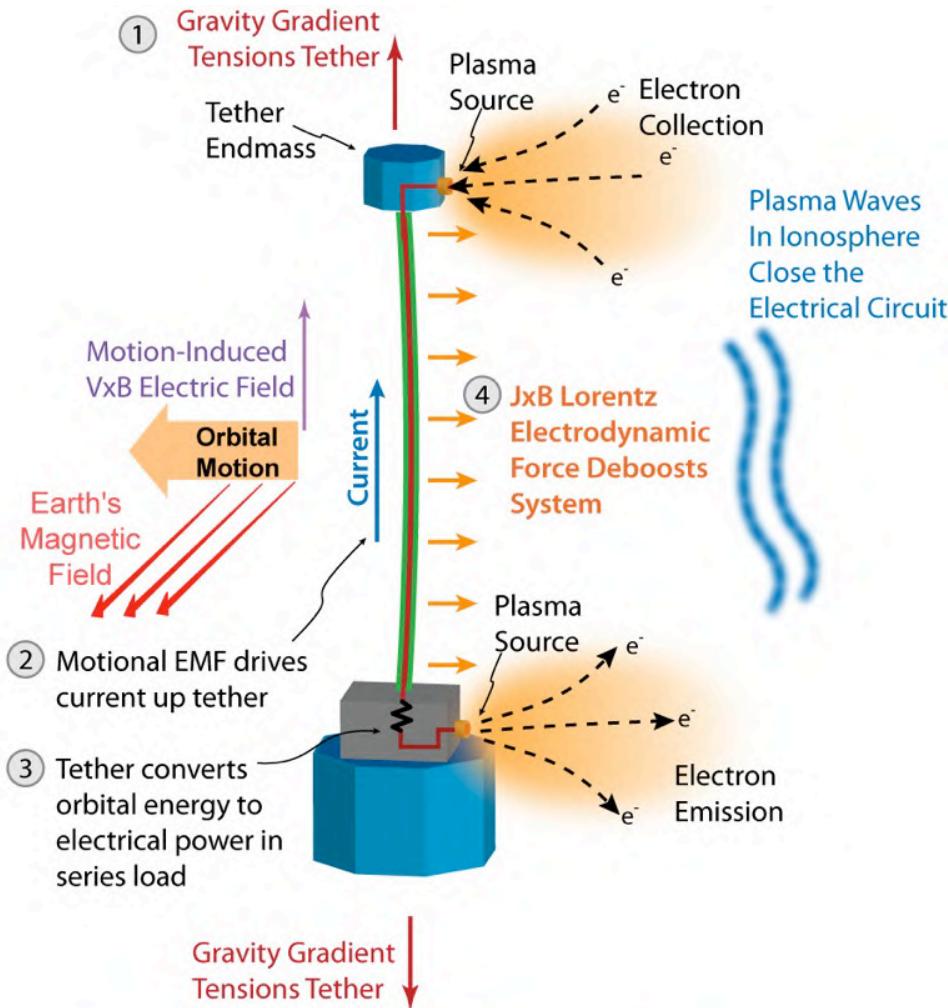
Space Tether Physics

Gravity Gradient

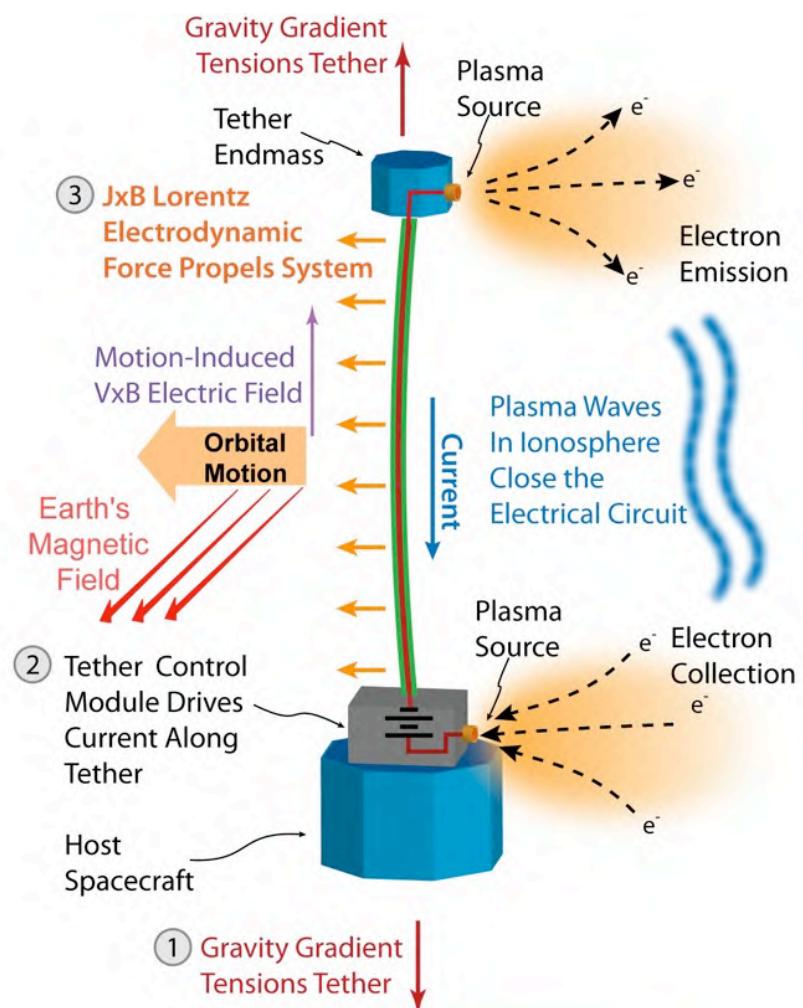


Electrodynamic Tether

Deboost/Power Generation



Boost Mode



Electrodynamic Propulsion Fundamentals

- Conducting wire deployed from an orbiting spacecraft
- Motion of wire through Earth's magnetic field induces voltage along the wire

$$V = L \cdot (v \times B)$$

- Currents flowing in the wire generate forces on the wire through Lorentz interactions with the Earth's magnetic field

$$F = J \times B$$

- Same fundamental physics as electric motors & electric generators
- Conducting plasma in ionosphere provides a mechanism for 'closing the current loop'
- The Earth serves as the reaction mass for conservation of momentum
- ED propulsion generates thrust without consuming propellant
- ED propulsion can provide unlimited delta-V

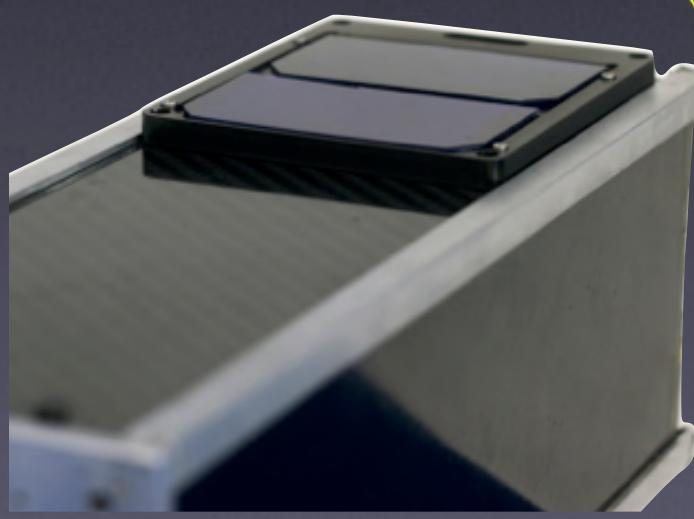
Terminator Tape™

Affordable, Lightweight, End-of-Mission Disposal Module for Orbital Debris Mitigation

- Deploys conducting tape at end-of-mission, gravity gradient stabilized
 - Works regardless of whether its deployed up or down
- Generates electrodynamic and aerodynamic drag to enable de-orbit within 25 years
- Bolt-on interface with pass-throughs for solar cells
- CubeSat and MicroSat modules available



MicroSat Terminator Tape

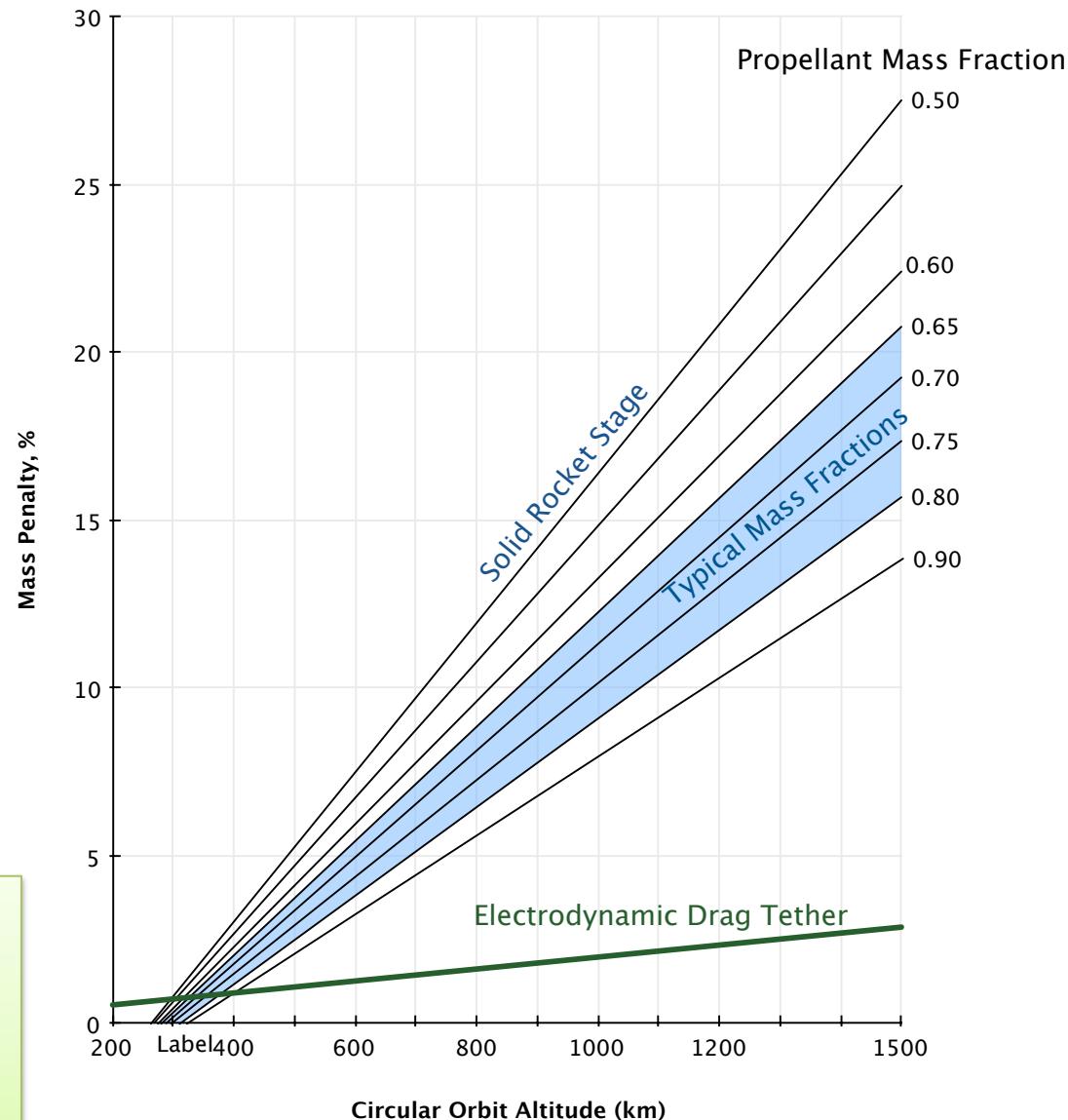


CubeSat Terminator Tape

EDTs Enable Deorbit Mass Savings

- **Electrodynamic drag tether does not consume propellant to induce thrust**
- **EDTs can meet end-of-mission disposal requirements with mass penalty of 1-3%**
- **Chemical rocket stages require 5-20% mass penalty**
- **Unlike rockets, EDT does not require host spacecraft power and ADCS system to be functional**

Terminator Tape Lowers Mass Impact of End-of-Life Disposal
=> More Mass for Payloads & Fuel for Longer Operations



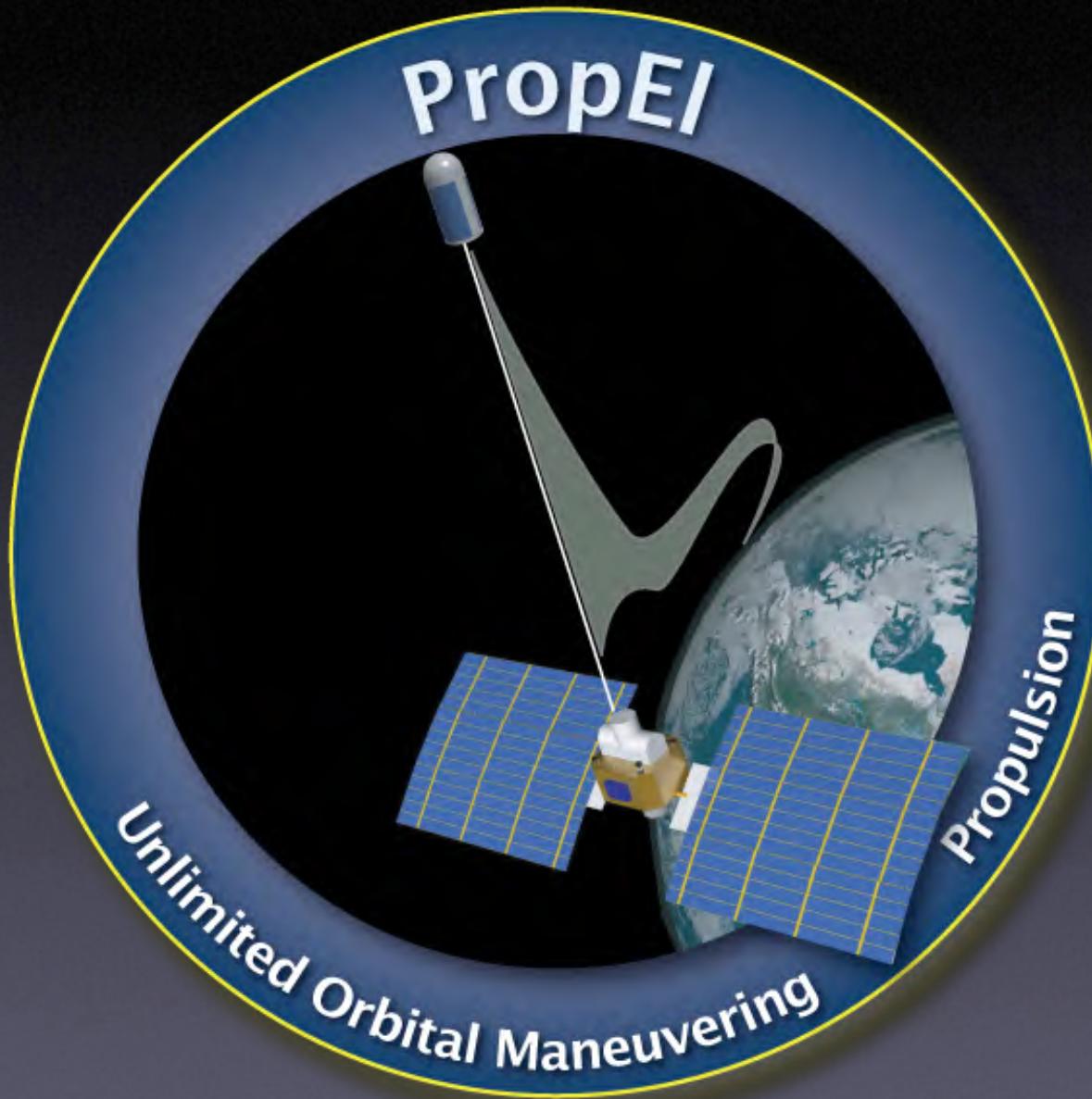
Cubesat Terminator Tape



Deployment
Successfully
Demonstrated
In Microgravity

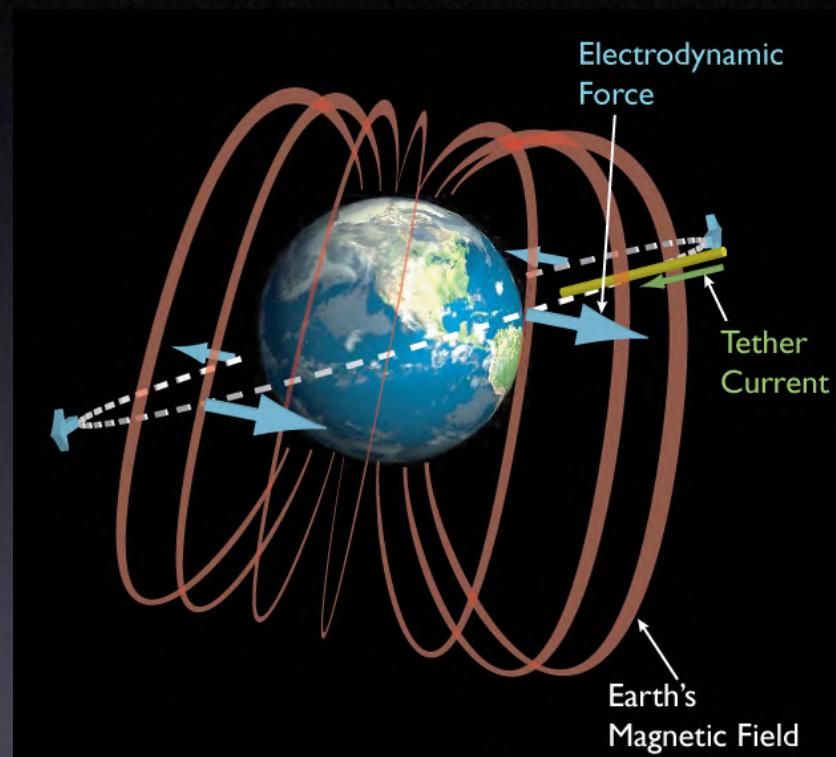


Electrodynamic Propulsion



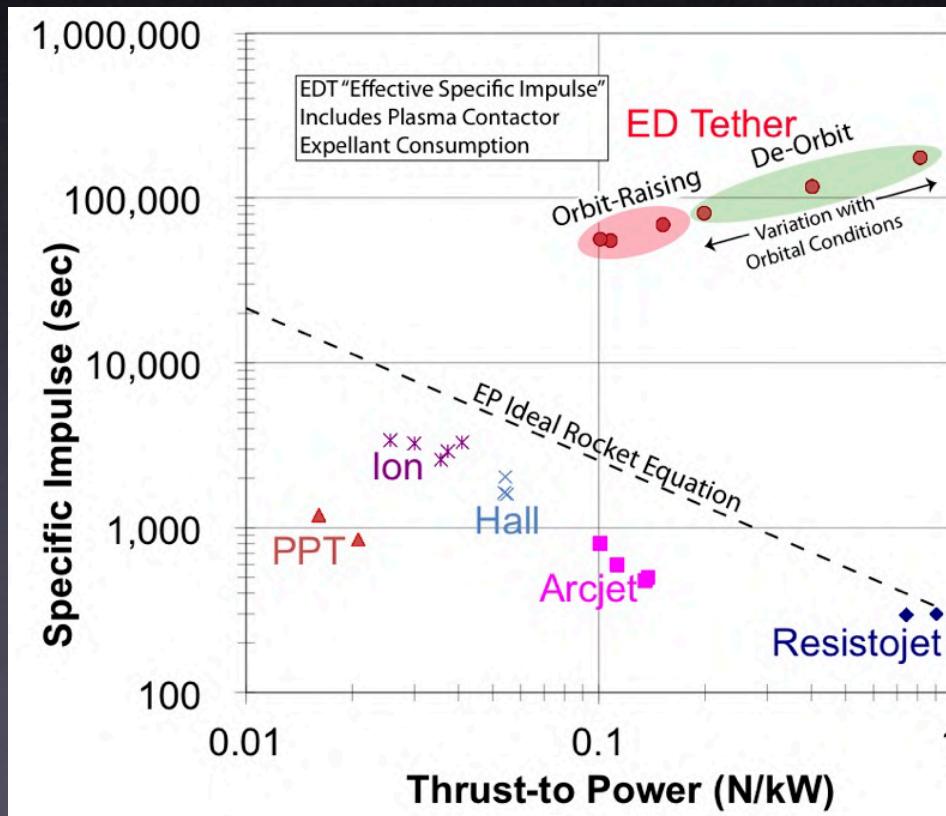
ED Orbit Modification & Limits

- Magnetic field strength and direction varies over each orbit
- Electrodynamic forces vary in magnitude and direction over each orbit
- Electrodynamic forces have components both:
 - In-plane (orbit raising/lowering)
 - Out-of-plane (inclination change)
- Tether current can be modulated over one or more orbits to change all six orbital elements
- Orbit raising/lowering most effective in low & moderate inclination ($>70^\circ$) orbits
- Inclination change most effective in high inclination orbits
- Useful altitude range: ~ 300 km to ~ 2500 km
 - Potentially higher with active current contactor technologies (“vacuum electrodynamics”)



ED Propulsion Performance

- ED Tethers can “escape the rocket equation” and provide BOTH high thrust-to-power AND extremely high specific impulse



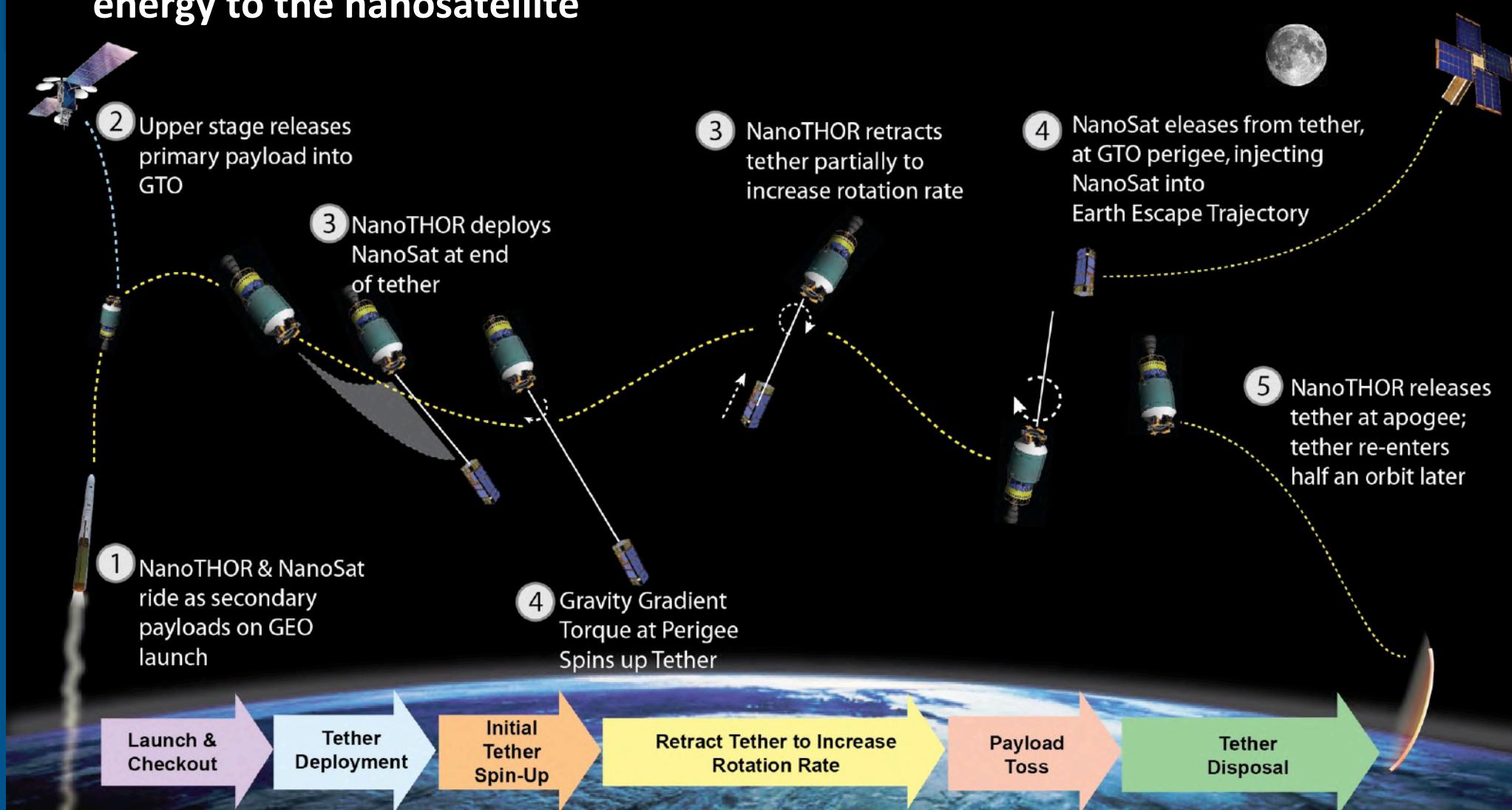
- Enable missions requiring large total ΔV to be performed by systems with small wet mass

Momentum-Exchange Propulsion



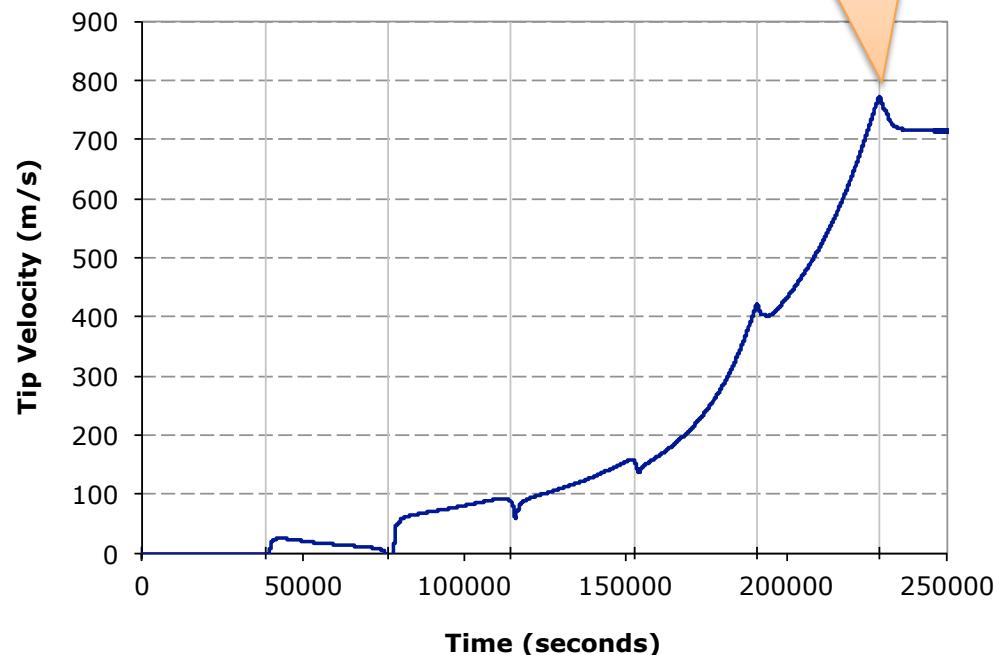
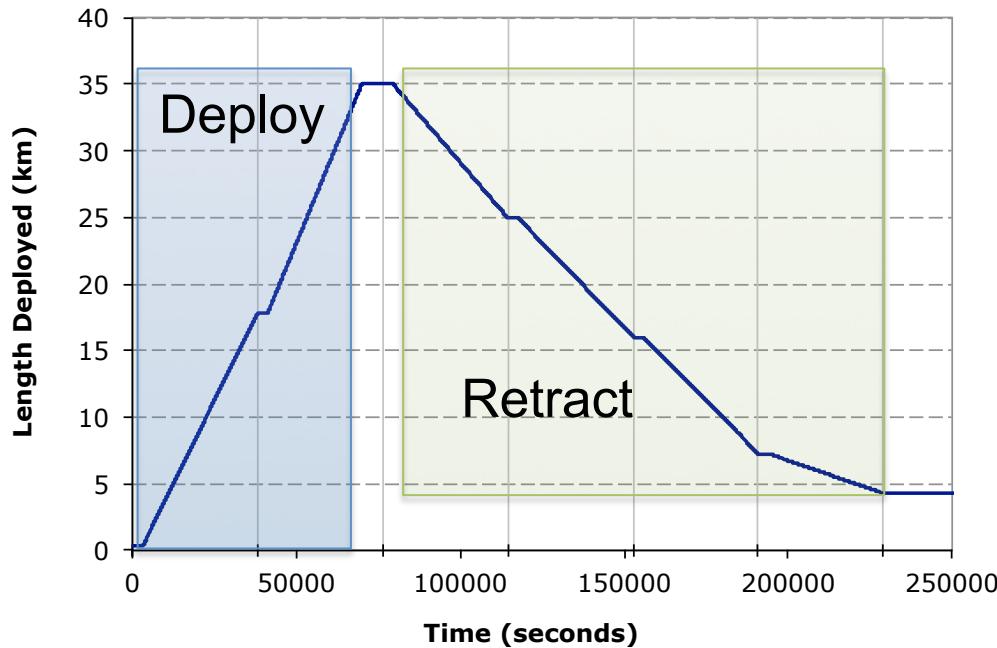
NanoTHOR CONOPS

- Nanosat & NanoTHOR ride as secondary payloads on GEO satellite launch
- NanoTHOR uses slender, high-strength tether to transfer stage's orbital energy to the nanosatellite



Tether Spin-Up in GTO

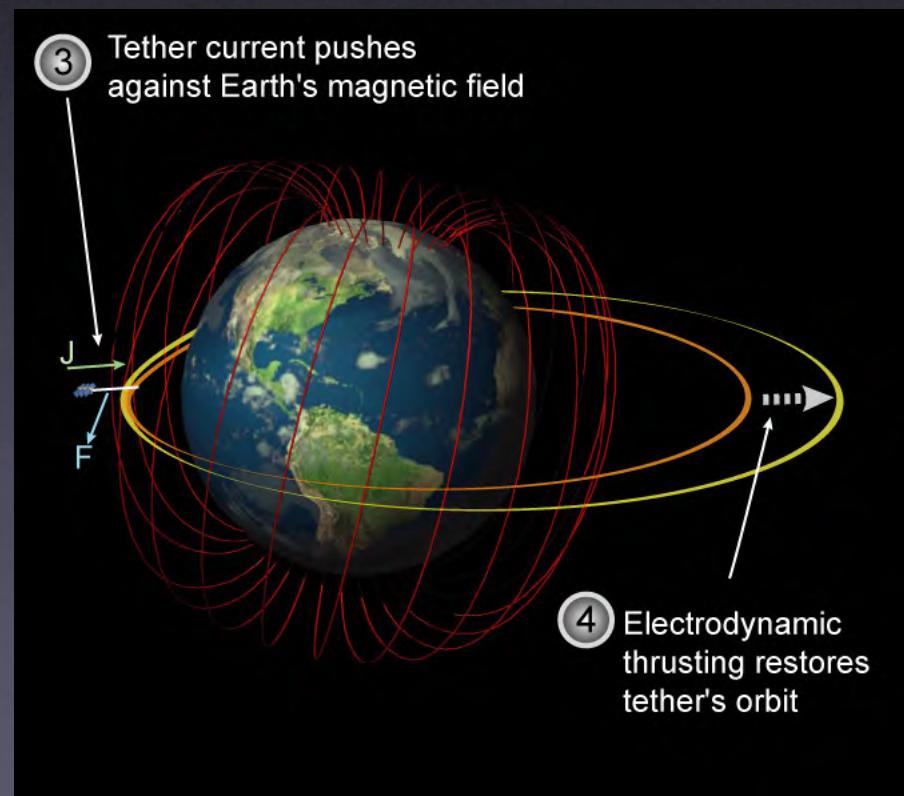
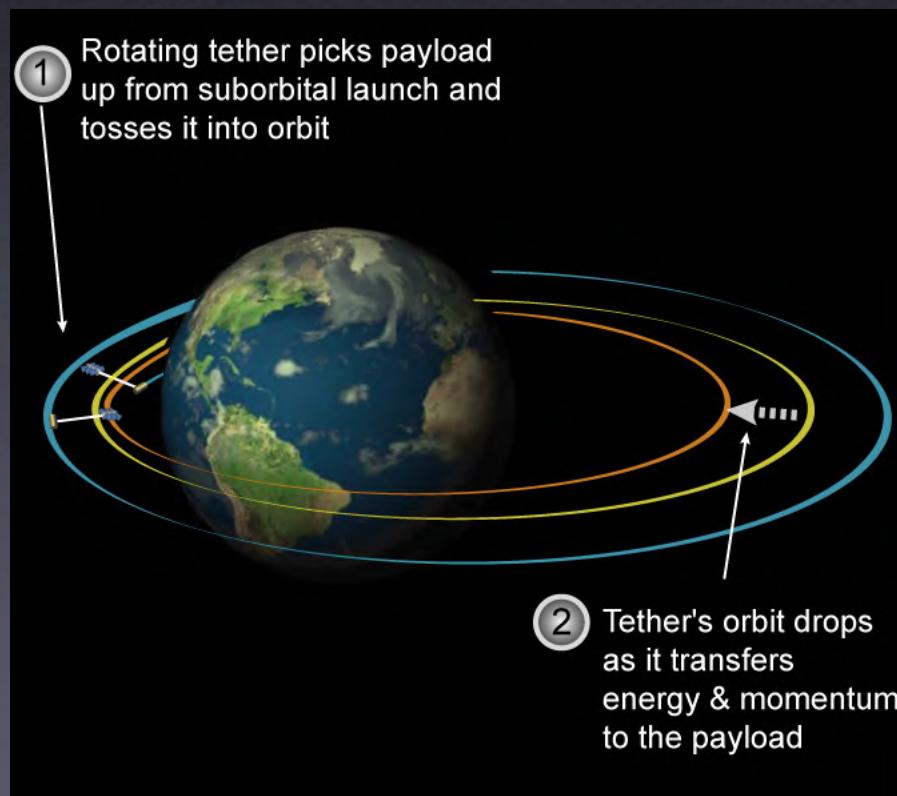
- Deploy tether over 2 orbits at ~50 cm/s
- Vary deployment rate so that tether is ~30° behind vertical when approaching perigee
- Gravity gradient provides torque to get tether spinning
- Retract tether at ~25 cm/s to increase spin rate



We can use tether reeling in the Earth's gravity well to spin up the tether

Momentum-Exchange/Electrodynamic-Reboost (MXER) Tether

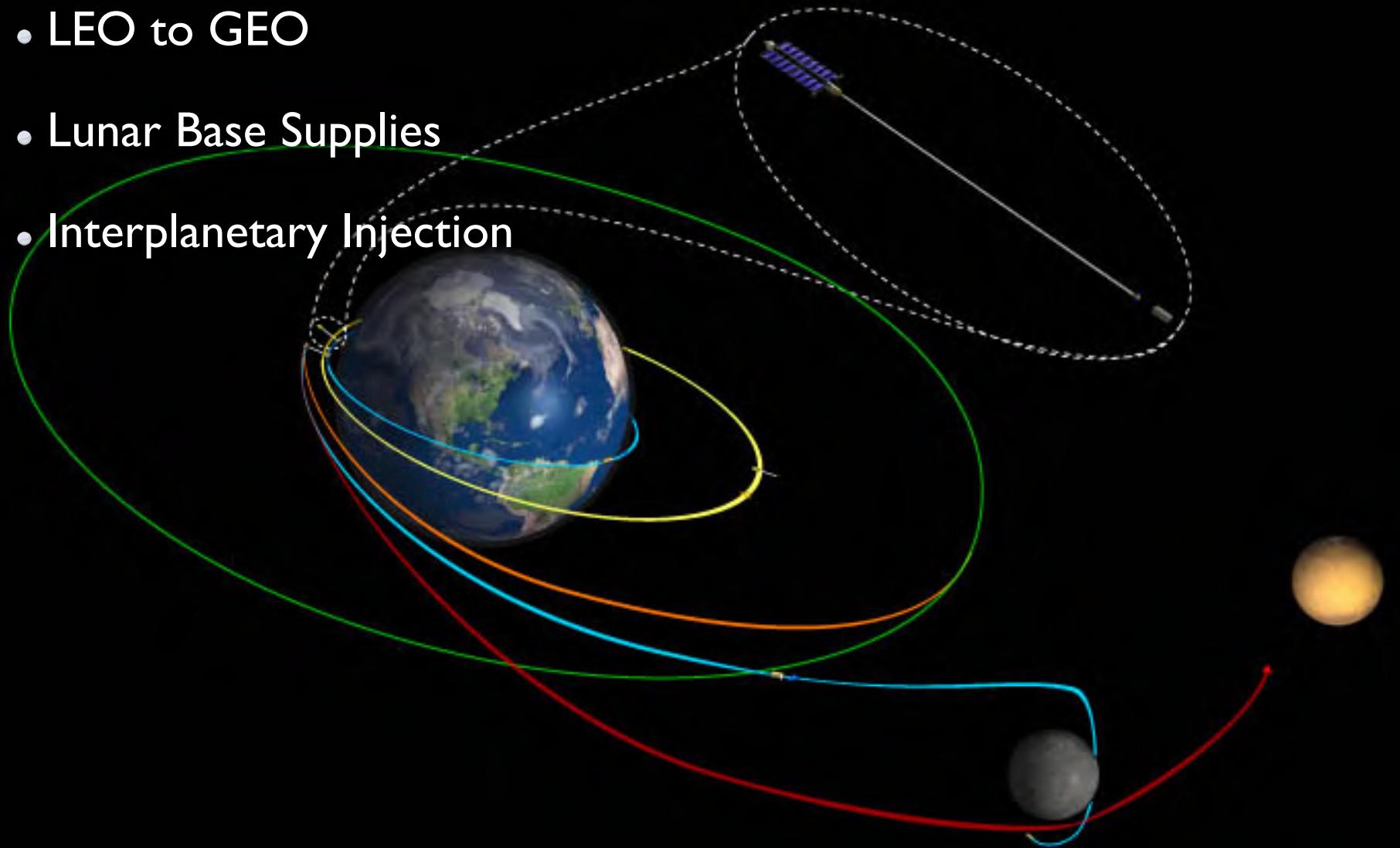
- Rotating tether picks payload up from low-LEO or a suborbital launch vehicle & tosses it to GTO
- System uses electrodynamic thrusting to restore its orbital energy
- Greatly reduces launch vehicle size and cost, or increases payload capacity of launch vehicle
- MXER Launch Assist could make single-stage RLV system viable



MXER Tether Serves Multiple Exploration Missions

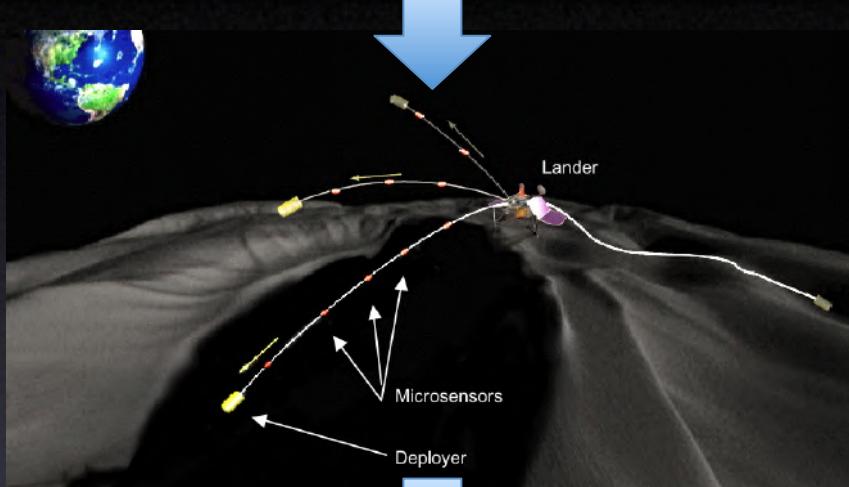
- Reusable In-Space “Upper Stage”

- LEO to GEO
- Lunar Base Supplies
- Interplanetary Injection



Terrestrial Spin-Off Applications

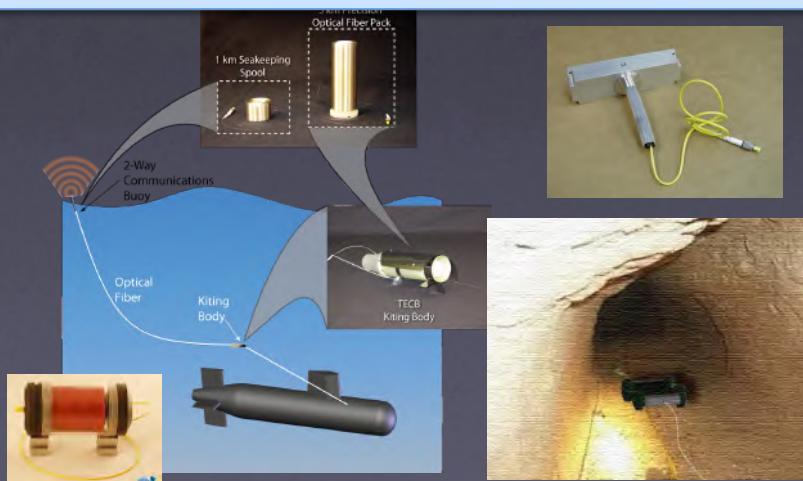
Space Tether Deployment Technology Applied to Planetary Exploration



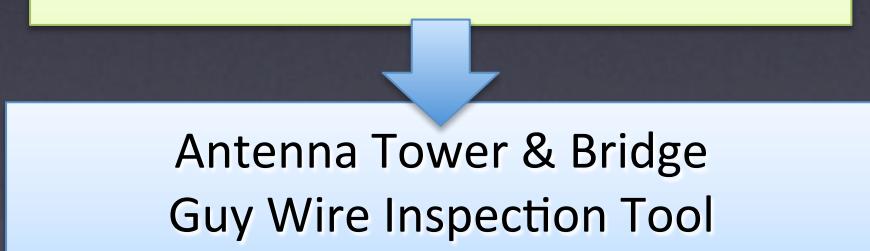
High Power and Tension Winch for MXER Tether System Applications



Optical Tether Dispensers for Underwater Communications & Mobile Robots

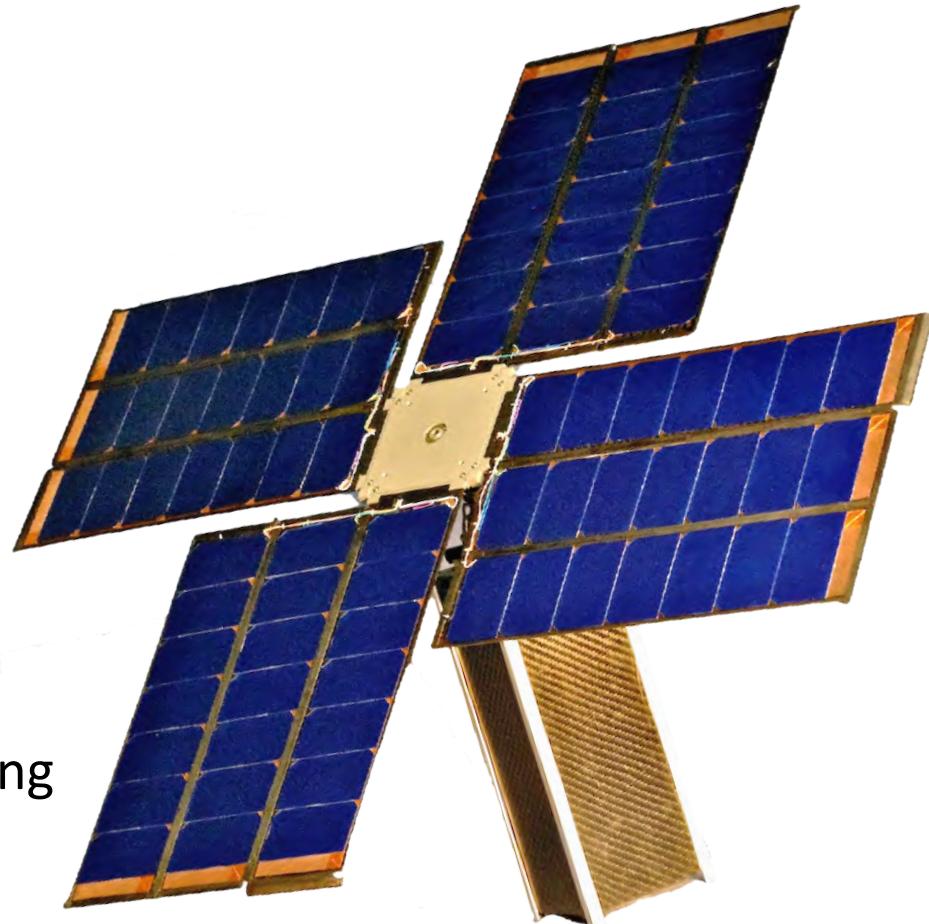


MAST CubeSat Mission Space Tether Inspection Technology



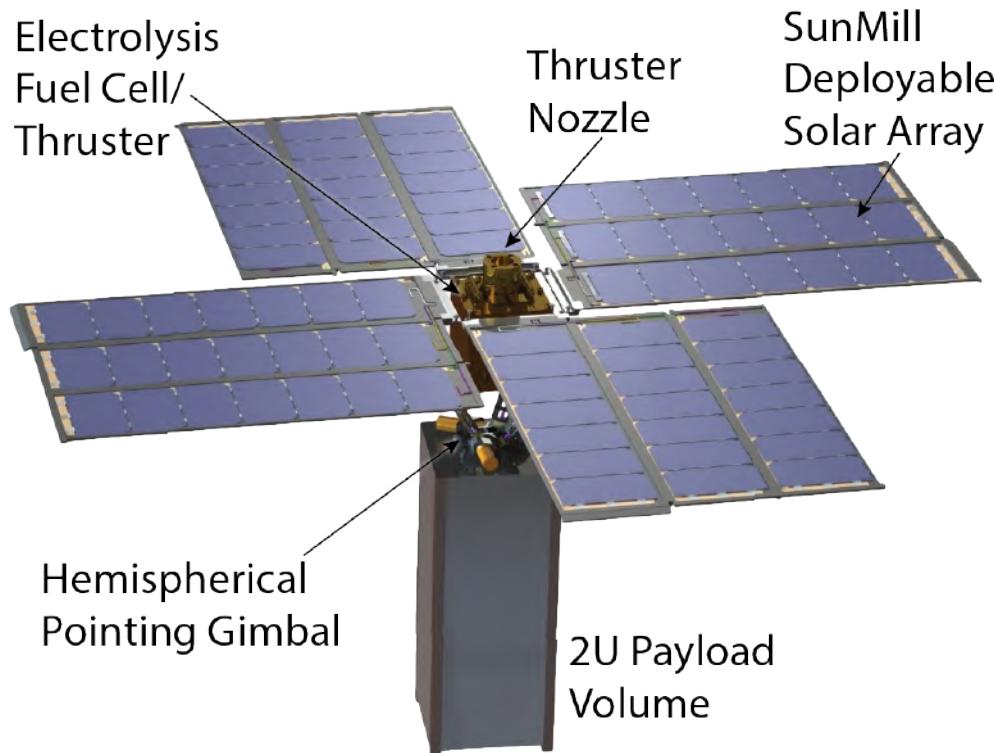
Sunmill™ Deployable Solar Array

- **Deployable Solar Array**
 - 80W Peak power and 49W OAP BOL
 - Panels utilized volume outside of 10x10cm CubeSat
 - Canfield joint carpal gimbal for panel deployment and pointing
- **Key Technologies**
 - Lightweight, stiff, carbon fiber panels
 - Power Density of 92 W/kg
 - High Panel Stiffness
 - Gimbal provides hemispherical pointing
- **SWaP**
 - Size: 2.35U remaining for bus & payload
 - Weight: Panels: 0.95kg, Gimbal: 0.15kg
 - Total: 1.1kg
 - Power: Gimbal consumes 1W maximum



PowerCube: Integrated Power, Propulsion and Pointing for CubeSats

PowerCube provides an enabling set of capabilities: Power, Propulsion and Pointing Control for CubeSats

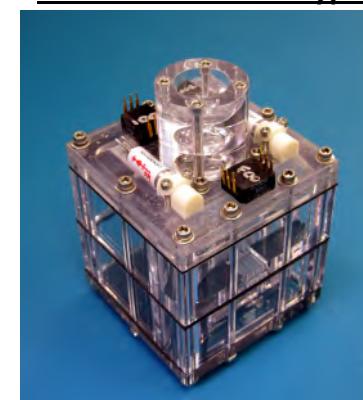


PowerCube is a 1U module that provides:

- 80 W Peak, 50 W OAP
- $\Delta V=100$ m/sec (for 3kg 3U easily scalable)
- 500 μ Ns bit-impulse, appropriate for attitude control
- Precision pointing of payloads using gimbal and PowerCube as reaction mass

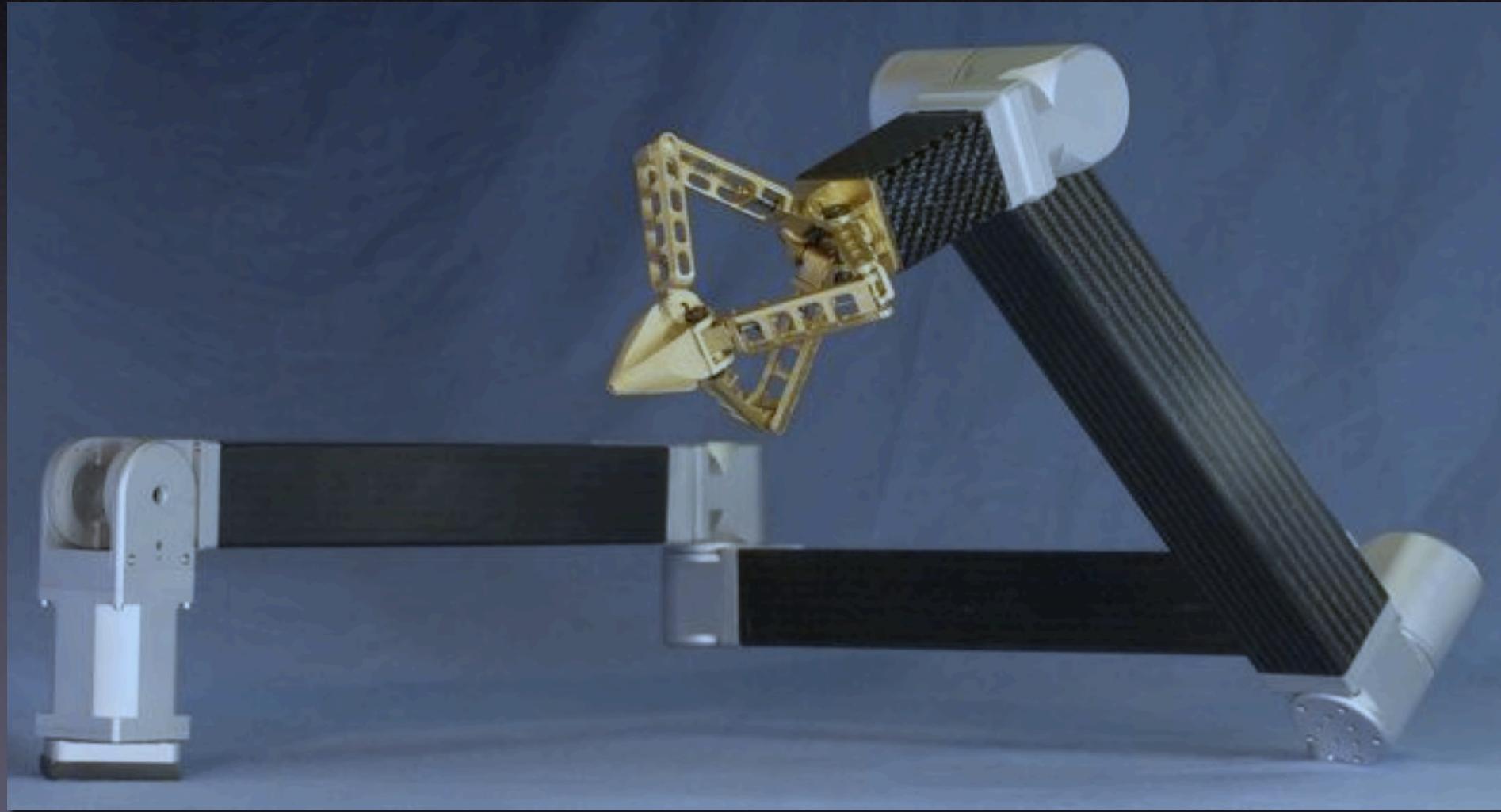
Enables high-performance, agile CubeSat missions in Earth orbit and beyond

Phase I SBIR Prototype



Lightweight Robotic Arm

- For use with nanosats and CubeSats
- 11 DOF, 2m dia. hemispherical workspace



Versatile Structural Radiation Shielding (VSRSTM)

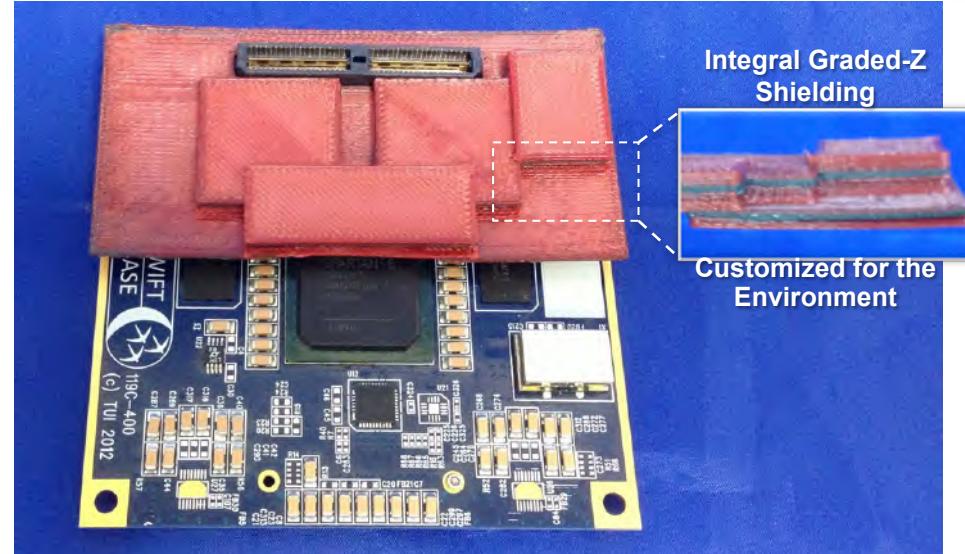
Tethers Unlimited, Inc. FA9453-12-M-0336



Advanced Propulsion, Power, & Comm
for Space, Sea, & Air

Technology:

- VSRSTM effort is developing fundamental technology for additive manufacturing with polymer-entrained metals to fabricate multi-functional structures with integral radiation shielding
- Combines high-Z/low-Z materials for optimal shielding-per-mass
 - **≥ 55% mass savings** over Al for simple enclosures
 - > 80% mass savings with spot shielding
- Additive manufacturing enables complex geometries and in-part variation of material properties to minimize mass of shielding
- Enables rapid and low-cost fabrication of a wide range of radiation shielding solutions:
 - Minimum-mass spot covers and EMI enclosures
 - Structures and MLI with integral radiation shielding
 - Graded-Z shielding



Prototype VSRSTM Cover with Spot Shielding

VSRSTM Extends the Lifetime of COTS Components in High-Rad Environments

Phase I Accomplishments

- Developed compounded PEEK/W and HDPE/W feedstock
- Developed new processes enabling 3D printing with PEEK materials
 - Low-outgassing, high-temperature, high-stiffness polymer
- Demonstrated Fused Deposition Modeling 3DP of prototype electronics cover with Graded-Z spot shielding
 - Responsive Capability: **1 Day from Design to Integration**
- Performed analytic modeling of shielding performance
 - Numerical modeling with Geant4 to optimize graded-Z shielding

Plans for Phase II Effort:

- Integrate additional compounds for increased material strength as well as thermal and electrical conductivity
- Prototype optimization with Geant4 for the GEO-environment
 - 3D numerical modeling to optimize the internal structure
- Qualification test the VSRSTM materials for performance:
 - Structural, thermal, outgassing, and conductivity tests
 - Comprehensive irradiation testing representative of the GEO-environment, to compare to on-orbit performance
- Fabricate test instrumentation and print materials to support EAGLE test flight
 - Provide flight heritage for the VSRSTM materials and technology through data collection and proof of performance on-orbit

Process for On-Orbit Construction of Kilometer-Scale Apertures

- **Challenge Addressed:**

- Currently, design, mass, & cost of space systems is driven largely by need to ensure they survive launch loads
- Size of apertures and structures constrained by need to stow them within available fairings

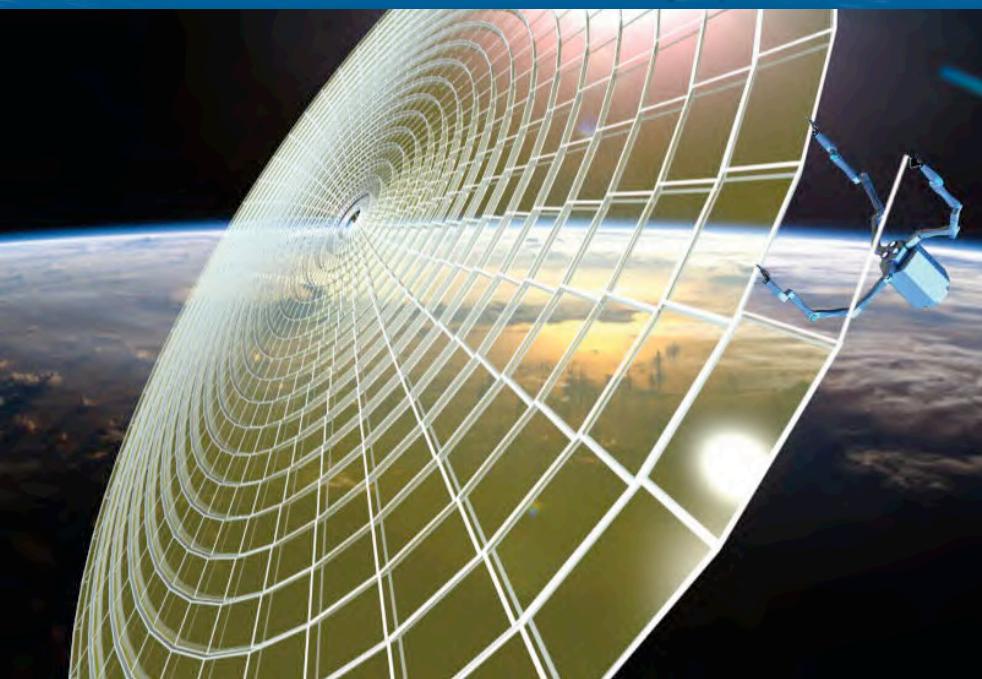
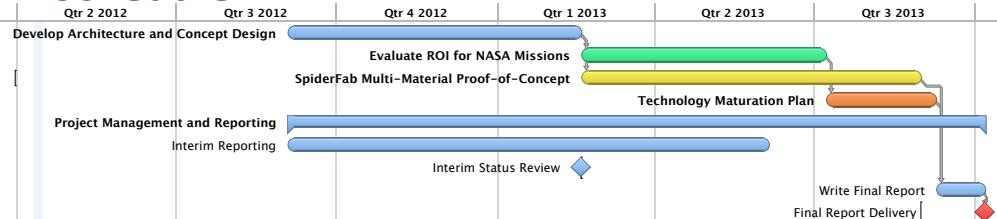
- **Proposed Innovation:**

- SpiderFab combines techniques evolved from terrestrial additive manufacturing and composite layup with robotic assembly to enable on-orbit construction of large spacecraft components optimized for the zero-g environment

- **Proposed Effort**

- Develop architecture and concept designs for SpiderFab system to construct and integrate very large apertures
- Evaluate ROI of SpiderFab on-orbit construction vs. current SOA deployable technologies
- Proof-of-concept testing of candidate methods

- **Schedule**



- **Benefits**

- SpiderFab constructs space system components with order-of-magnitude improvements in packing efficiency and structural performance, enabling NASA to deploy systems with larger apertures and baselines using smaller, lower cost launch vehicles

- **Payoff**

- SpiderFab on-orbit construction will enable NASA science and exploration missions to collect and distribute data products with higher bandwidth, higher resolution, higher signal-to-noise, and lower life-cycle cost

Summary

- Space tethers can provide propellantless propulsion to enable large total- ΔV missions with very low mass requirements
- Electrodynamic tethers can generate thrust at Isp's of 50,000-200,000 sec. with thrust-to-power competitive with EP thrusters
- Momentum-Exchange/Electrodynamic-Reboost tethers can act as fully-reusable in-space upper stages to achieve dramatic reductions in mission launch costs
- Contrary to popular belief, most tether missions HAVE BEEN SUCCESSFUL
 - Those that did not succeed did so due to failures of engineering processes, *not* due to fundamental physics
- Tethers are an emerging 'high-risk, high-payoff' technology that can enable sustainable space exploration architectures



**TETHERS
UNLIMITED**

*Advanced Propulsion, Power, & Communications
For Space, Sea, & Air*